

ÉCOLE POLYTECHNIQUE FÉDÉRALE DE LAUSANNE
School of Computer and Communication Sciences

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Learning Theory

Assignment date: June 23, 2026, 09:15
Due date: June 23, 2026, 12:15

Final Exam – CS 526 – Room INM 10

Use scratch paper if needed to figure out the solution. This exam is open-book (lecture notes, exercises, course materials). You can use the uploaded material on your computer but **switch off the wifi**. Good luck!

SCIPER No.: _____

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Problem 1 (10 pts). **Quick questions**

These questions have quick answers. You can directly use the relevant theorems or results seen in class without proof but you must clearly state your justifications.

1. **VC dimension I.** Let $\mathcal{H} = \{h_r(x) = \mathbf{1}[\|x\| \leq r] : r \geq 0\}$ be the class of classifiers given by Euclidean balls centered at the origin in $\mathbb{R}^d$. Determine the VC dimension of $\mathcal{H}$.
2. **VC dimension II.** Let $\mathcal{H}$ be a binary hypothesis class with exactly 8 hypotheses: $|\mathcal{H}| = 8$. Explain why $\mathcal{H}$ cannot shatter any set of 4 points. Give also an upper bound on the VC dimension of $\mathcal{H}$.
3. **Convexity.** Consider the function $f(x) = \frac{2x^2}{3} + \frac{|x|}{3}$ defined on the real line $\mathbb{R}$. Answer the following questions:
 - is f convex ?
 - is f differentiable everywhere ?
 - is f subdifferentiable everywhere ?
 - If you answered "yes" to the last question, then give its subdifferential set for each $x \in \mathbb{R}$.
 - Let $\omega \in 0, 1$ a Bernoulli random variable such that $\mathbb{P}(0) = \frac{2}{3}$ and $\mathbb{P}(1) = \frac{1}{3}$. Define the random function g_ω such that $g_0(x) = 2x$ and $g_1(x) = H(x) - H(-x)$ where $H(x) = 1$ for $x > 0$, $H(x) = 0$ for $x < 0$, and $H(0) = 0$. Does g_ω qualify for a stochastic gradient of f ?

4. **Tensors.** Let

$$T = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \otimes \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} \otimes \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 3 \\ 5 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 3 \\ 0 \end{pmatrix}.$$

Is this decomposition unique? What is the rank of T ? Justify your answers.

Solution to Problem 1.

1. **VC dimension I. 2pt.** A single point $x \neq 0$ is shattered since choosing $r < \|x\|$ labels it 0 and choosing $r \geq \|x\|$ labels it 1.

If x_1, x_2 satisfy $\|x_1\| < \|x_2\|$, then the labeling $(0, 1)$ cannot be realized, because every ball containing x_2 also contains x_1 . Hence $\text{VCdim}(\mathcal{H}) = 1$.

2. **VC dimension II. 2pt.** If $\mathcal{H}$ shatters a set of 4 points, it must realize all $2^4 = 16$ possible binary labelings of these points. A class with only 8 hypotheses can realize at most 8 labelings. Therefore no set of 4 points can be shattered. The argument also implies that $\text{VCdim}(\mathcal{H}) \leq 3$.

3. **Convexity. 3pt.** The function is the sum of two convex functions so its convex.

It is not differentiable at $x = 0$.

But it has a subdifferential everywhere.

At $x = 0$ this is the set $\{-1/3, +1/3\}$; for $x > 0$ it is $\{4x/3 + 1/3\}$; for $x < 0$ it is $\{4x/3 - 1/3\}$.

Finally yes g_ω is a stochastic gradient since its average is $\frac{1}{3}g_0 + \frac{2}{3}g_1$ which is equal to a subgradient (the one where we use 0 for the subgradient at 0).

4. **Tensors. 3pt.** We have

$$T = \vec{a}_1 \otimes \vec{b}_1 \otimes \vec{c}_1 + \vec{a}_2 \otimes \vec{b}_2 \otimes \vec{c}_2 + \vec{a}_3 \otimes \vec{b}_3 \otimes \vec{c}_3,$$

where

$$[\vec{a}_1 \ \vec{a}_2 \ \vec{a}_3] = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 3 \\ 1 & 2 & 5 \end{bmatrix}$$

has pairwise independent columns,

$$[\vec{b}_1 \ \vec{b}_2 \ \vec{b}_3] = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

has linearly independent columns, and

$$[\vec{c}_1 \ \vec{c}_2 \ \vec{c}_3] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 3 \\ 0 & 1 & 0 \end{bmatrix}$$

has linearly independent columns.

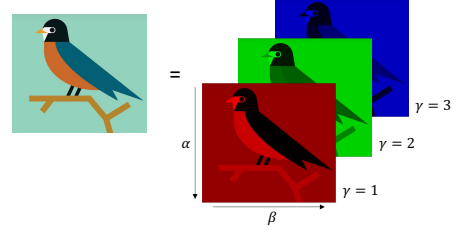
Hence by Jenrich's theorem the decomposition is unique and

$$\text{rank}(T) = 3.$$

Problem 2 (20 pts). *Tucker Decomposition for RGB Image Compression*

Let $\mathcal{X} \in \mathbb{R}^{m \times n \times 3}$ represent an RGB image admitting the Tucker representation

$$\mathcal{X}^{\alpha\beta\gamma} = \sum_{p=1}^{r_1} \sum_{q=1}^{r_2} \sum_{r=1}^{r_3} \mathcal{G}^{pqr} A^{\alpha p} B^{\beta q} C^{\gamma r},$$



where

$$A \in \mathbb{R}^{m \times r_1}, \quad B \in \mathbb{R}^{n \times r_2}, \quad C \in \mathbb{R}^{3 \times r_3},$$

have **orthonormal columns** (i.e. $A^T A = I_{r_1}$, $B^T B = I_{r_2}$, $C^T C = I_{r_3}$).

We introduce the following notation. For a tensor $\mathcal{T}$ and matrices M_1, M_2, M_3 of compatible sizes, define the *multilinear multiplication* $\mathcal{T}(M_1, M_2, M_3)$ as the tensor with entries

$$\mathcal{T}(M_1, M_2, M_3)^{\delta\epsilon\eta} = \sum_{\alpha,\beta,\gamma} \mathcal{T}^{\alpha\beta\gamma} M_1^{\delta\alpha} M_2^{\epsilon\beta} M_3^{\eta\gamma}.$$

For any core $\mathcal{Y} \in \mathbb{R}^{r_1 \times r_2 \times r_3}$, we also write

$$\mathcal{T}_{\mathcal{Y}}^{\alpha\beta\gamma} = \sum_{p=1}^{r_1} \sum_{q=1}^{r_2} \sum_{r=1}^{r_3} \mathcal{Y}^{pqr} A^{\alpha p} B^{\beta q} C^{\gamma r},$$

so that in particular $\mathcal{X} = \mathcal{T}_{\mathcal{G}}$.

1. Consider an image of size $1024 \times 1024 \times 3$ and a Tucker approximation of multilinear rank $(r_1, r_2, r_3) = (20, 20, 3)$.

- Count the number of real scalars needed to store the original image and the Tucker factors A, B, C together with the core $\mathcal{G}$.
- Deduce the compression ratio.

2. Suppose $r_3 = 3$. Show that one can always reparametrize the decomposition so that $C = I_3$, without changing $\mathcal{X}$.

Hint: absorb C into the core by defining a new core $\tilde{\mathcal{G}}$.

3. From now on, assume that $C = I_3$ (and hence $r_3 = 3$). Define the linear subspace of $\mathbb{R}^{m \times n \times 3}$

$$S = \{ \mathcal{T}_{\mathcal{Y}} : \mathcal{Y} \in \mathbb{R}^{r_1 \times r_2 \times 3} \},$$

and set $\hat{\mathcal{X}} = \mathcal{X}(A^T, B^T, I_3) \in \mathbb{R}^{r_1 \times r_2 \times 3}$.

Show that $\mathcal{T}_{\hat{\mathcal{X}}}$ is the *orthogonal projection* of $\mathcal{X}$ onto S ; that is, verify that

$$\langle \mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}}, \mathcal{Z} \rangle_F = 0 \quad \forall \mathcal{Z} \in S,$$

where the Frobenius inner product is $\langle \mathcal{T}, \mathcal{Z} \rangle_F = \sum_{\alpha, \beta, \gamma} \mathcal{T}^{\alpha\beta\gamma} \mathcal{Z}^{\alpha\beta\gamma}$.

Hint : Show that it suffices that for every p, q, γ , $\sum_{\alpha, \beta} (\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}})^{\alpha\beta\gamma} A^{\alpha p} B^{\beta q} = 0$.

4. Consider the least-squares problem

$$\min_{\mathcal{Y} \in \mathbb{R}^{r_1 \times r_2 \times 3}} \|\mathcal{X} - \mathcal{T}_{\mathcal{Y}}\|_F^2.$$

- a) Show that the minimum is achieved for $\mathcal{Y} = \hat{\mathcal{X}}$.
- b) Deduce that $\min_{\mathcal{Y}} \|\mathcal{X} - \mathcal{T}_{\mathcal{Y}}\|_F^2 = \|\mathcal{X}\|_F^2 - \|\hat{\mathcal{X}}\|_F^2$
- c) Interpret this result in the context of image compression.

Hint : Justify that you can use the Pythagorean identity $\|\mathcal{X}\|_F^2 = \|\mathcal{T}_{\hat{\mathcal{X}}}\|_F^2 + \|\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}}\|_F^2$.

Solution to Problem 2.

1. (a) Parameter counts. 3pt.

Original image. The image $\mathcal{X} \in \mathbb{R}^{1024 \times 1024 \times 3}$ requires

$$1024 \times 1024 \times 3 = 3,145,728 \text{ scalars.}$$

Tucker decomposition. The four objects to store are:

- Core $\mathcal{G} \in \mathbb{R}^{20 \times 20 \times 3}$: $20 \times 20 \times 3 = 1,200$ scalars.
- Factor $A \in \mathbb{R}^{1024 \times 20}$: $1024 \times 20 = 20,480$ scalars.
- Factor $B \in \mathbb{R}^{1024 \times 20}$: $1024 \times 20 = 20,480$ scalars.
- Factor $C \in \mathbb{R}^{3 \times 3}$: $3 \times 3 = 9$ scalars.

Total: $1,200 + 20,480 + 20,480 + 9 = 42,169$ scalars.

(b) Compression ratio. 1pt.

$$\text{Compression ratio} = \frac{3,145,728}{42,169} \approx 74.6.$$

The Tucker decomposition requires roughly 75 times fewer parameters than the original image.

2. 4pt.

Since $r_3 = 3$ and $C \in \mathbb{R}^{3 \times 3}$ has orthonormal columns, C is a square orthogonal matrix satisfying $CC^T = C^TC = I_3$. Define the new core $\tilde{\mathcal{G}} \in \mathbb{R}^{r_1 \times r_2 \times 3}$ by

$$\tilde{\mathcal{G}}^{pq\gamma} = \sum_{r=1}^3 \mathcal{G}^{pqr} C^{\gamma r}, \quad \text{i.e.} \quad \tilde{\mathcal{G}} = \mathcal{G}(I_{r_1}, I_{r_2}, C).$$

Then

$$\mathcal{X}^{\alpha\beta\gamma} = \sum_{p,q,r} \mathcal{G}^{pqr} A^{\alpha p} B^{\beta q} C^{\gamma r} = \sum_{p,q} \tilde{\mathcal{G}}^{pq\gamma} A^{\alpha p} B^{\beta q},$$

which is exactly the Tucker representation with color factor I_3 . Hence $\mathcal{X}$ is unchanged and we may always set $C = I_3$.

3. 6pt.

Take any $\mathcal{Z} \in S$, so $\mathcal{Z} = \mathcal{T}_{\mathcal{Y}}$ for some $\mathcal{Y} \in \mathbb{R}^{r_1 \times r_2 \times 3}$, i.e.

$$\mathcal{Z}^{\alpha\beta\gamma} = \sum_{p,q} \mathcal{Y}^{pq\gamma} A^{\alpha p} B^{\beta q}.$$

Following the hint, we first show that for every p_0, q_0, γ_0 ,

$$\sum_{\alpha, \beta} (\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}})^{\alpha\beta\gamma_0} A^{\alpha p_0} B^{\beta q_0} = 0. \quad (1)$$

By definition of $\hat{\mathcal{X}} = \mathcal{X}(A^T, B^T, I_3)$, the first term gives $\sum_{\alpha, \beta} \mathcal{X}^{\alpha\beta\gamma_0} A^{\alpha p_0} B^{\beta q_0} = \hat{\mathcal{X}}^{p_0 q_0 \gamma_0}$. For the term involving $\mathcal{T}_{\hat{\mathcal{X}}}$,

$$\begin{aligned} \sum_{\alpha, \beta} \hat{\mathcal{T}}^{\alpha\beta\gamma_0} A^{\alpha p_0} B^{\beta q_0} &= \sum_{\alpha, \beta} \sum_{p, q} \hat{\mathcal{X}}^{pq\gamma_0} A^{\alpha p} B^{\beta q} A^{\alpha p_0} B^{\beta q_0} \\ &= \sum_{p, q} \hat{\mathcal{X}}^{pq\gamma_0} \left(\sum_{\alpha} A^{\alpha p} A^{\alpha p_0} \right) \left(\sum_{\beta} B^{\beta q} B^{\beta q_0} \right) \\ &= \sum_{p, q} \hat{\mathcal{X}}^{pq\gamma_0} (A^T A)_{pp_0} (B^T B)_{qq_0} = \hat{\mathcal{X}}^{p_0 q_0 \gamma_0}, \end{aligned}$$

using $A^T A = I_{r_1}$ and $B^T B = I_{r_2}$. Subtracting confirms (1). Substituting the definition of $\mathcal{Z}$,

$$\begin{aligned} \langle \mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}}, \mathcal{Z} \rangle_F &= \sum_{\alpha, \beta, \gamma} (\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}})^{\alpha\beta\gamma} \sum_{p, q} \mathcal{Y}^{pq\gamma} A^{\alpha p} B^{\beta q} \\ &= \sum_{p, q, \gamma} \mathcal{Y}^{pq\gamma} \underbrace{\sum_{\alpha, \beta} (\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}})^{\alpha\beta\gamma} A^{\alpha p} B^{\beta q}}_{= 0 \text{ by (1)}} = 0. \end{aligned}$$

Hence $\mathcal{T}_{\hat{\mathcal{X}}}$ is the orthogonal projection of $\mathcal{X}$ onto S .

4. a) **$\hat{\mathcal{X}}$ is the minimizer. 2pt.** For any $\mathcal{Y} \in \mathbb{R}^{r_1 \times r_2 \times 3}$, decompose

$$\mathcal{X} - \mathcal{T}_{\mathcal{Y}} = \underbrace{(\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}})}_{\perp S} - \underbrace{(\mathcal{T}_{\mathcal{Y}} - \mathcal{T}_{\hat{\mathcal{X}}})}_{\in S}.$$

Since $\mathcal{T}_{\mathcal{Y}} - \hat{\mathcal{T}} \in S$, it is orthogonal to $\mathcal{X} - \hat{\mathcal{T}}$ by Question 3, so the Pythagorean theorem gives

$$\|\mathcal{X} - \mathcal{T}_{\mathcal{Y}}\|_F^2 = \|\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}}\|_F^2 + \|\mathcal{T}_{\mathcal{Y}} - \mathcal{T}_{\hat{\mathcal{X}}}\|_F^2 \geq \|\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}}\|_F^2,$$

with equality if and only if $\mathcal{T}_{\mathcal{Y}} = \mathcal{T}_{\hat{\mathcal{X}}}$, i.e. $\mathcal{Y} = \hat{\mathcal{X}}$. Hence $\min_{\mathcal{Y}} \|\mathcal{X} - \mathcal{T}_{\mathcal{Y}}\|_F^2 = \|\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}}\|_F^2$.

b) **Minimal loss. 3pt.** Like in a) we can deduce the Pythagorean identity. Since

$$\mathcal{X} = \underbrace{(\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}})}_{\perp S} + \underbrace{\mathcal{T}_{\hat{\mathcal{X}}}}_{\in S}.$$

we obtain directly

$$\|\mathcal{X} - \mathcal{T}_{\hat{\mathcal{X}}}\|_F^2 = \|\mathcal{X}\|_F^2 - \|\mathcal{T}_{\hat{\mathcal{X}}}\|_F^2.$$

Finally, $\|\mathcal{T}_{\hat{\mathcal{X}}}\|_F^2 = \|\hat{\mathcal{X}}\|_F^2$. Since A and B have orthonormal columns, the map $\mathcal{Y} \mapsto \mathcal{T}_{\mathcal{Y}}$ is an isometry. Indeed, expanding the square,

$$\begin{aligned} \|\mathcal{T}_{\hat{\mathcal{X}}}\|_F^2 &= \sum_{\alpha, \beta, \gamma} \left(\sum_{p, q} \hat{\mathcal{X}}^{pq\gamma} A^{\alpha p} B^{\beta q} \right)^2 = \sum_{p, p', q, q', \gamma} \hat{\mathcal{X}}^{pq\gamma} \hat{\mathcal{X}}^{p'q'\gamma} \left(\sum_{\alpha} A^{\alpha p} A^{\alpha p'} \right) \left(\sum_{\beta} B^{\beta q} B^{\beta q'} \right) \\ &= \sum_{p, p', q, q', \gamma} \hat{\mathcal{X}}^{pq\gamma} \hat{\mathcal{X}}^{p'q'\gamma} \delta_{pp'} \delta_{qq'} = \sum_{p, q, \gamma} (\hat{\mathcal{X}}^{pq\gamma})^2 = \|\hat{\mathcal{X}}\|_F^2, \end{aligned}$$

using $(A^T A)_{pp'} = \delta_{pp'}$ and $(B^T B)_{qq'} = \delta_{qq'}$.

Combining:

$$\min_{\mathcal{Y}} \|\mathcal{X} - \mathcal{T}_{\mathcal{Y}}\|_F^2 = \|\mathcal{X}\|_F^2 - \|\mathcal{T}_{\hat{\mathcal{X}}}\|_F^2 = \|\mathcal{X}\|_F^2 - \|\hat{\mathcal{X}}\|_F^2.$$

c) Interpretation. 1pt. For fixed A and B , the core $\hat{\mathcal{X}}$ give the best approximation of the original picture. Choosing A and B to maximize $\|\hat{\mathcal{X}}\|_F^2$ therefore minimizes the distortion, which is the goal of optimal image compression.

Problem 3 (20 pts). Stochastic Gradient Descent

Consider a dataset consisting of n given pairs $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$, where $x_i \in \mathbb{R}$ represent the features and $y_i \in \mathbb{R}$ represent the labels. We fit a linear model without intercept: $y = wx$.

We define the mean squared error objective function $f(w)$ as:

$$f(w) = \frac{1}{n} \sum_{i=1}^n f_i(w) = \frac{1}{n} \sum_{i=1}^n \frac{1}{2} (wx_i - y_i)^2$$

1. Compute w^* the unique global minimum of $f(w)$. Justify why it is unique. Write the standard Gradient Descent (GD) update rule with step size $\eta > 0$.
2. Now we consider Stochastic Gradient Descent. We initialize at w_1 (given) and at each step $k \geq 1$ we sample a fresh index $i_k \in \{1, \dots, n\}$ uniformly at random (with replacement).

(a) Justify why the SGD update step can be written as:

$$w_{k+1} = w_k - \eta(w_k x_{i_k}^2 - x_{i_k} y_{i_k}), \quad k \geq 1$$

- (b) Define the error $e_k = w_k - w^*$, $k \geq 1$. Prove that the expected error evolves as $\mathbb{E}[e_{k+1}] = (1 - \eta(\frac{1}{n} \sum x_i^2))^k e_1$, where the expectation is over the past history $i_k, i_{k-1}, \dots, i_1$.

Hint: Compute first the conditional expectation $\mathbb{E}_{i_k}[e_{k+1} \mid i_{k-1}, \dots, i_1]$. You can use $\mathbb{E}_{i_k}[e_{k+1}]$ as a short hand notation for this conditional expectation.

- (c) Give a condition on $\eta > 0$ to guarantee the convergence of $\mathbb{E}[e_k] \rightarrow 0$ as $k \rightarrow +\infty$.

3. Prove that the expected squared error satisfies

$$\mathbb{E}_{i_k}[e_{k+1}^2] = \frac{1}{n} \sum_{i=1}^n (e_k(1 - \eta x_i^2) + \eta(x_i y_i - w^* x_i^2))^2$$

4. From the previous result deduce the steady state behavior $\lim_{k \rightarrow +\infty} \mathbb{E}[e_k^2]$ where the expectation is over the whole (past) history.

Solution to Problem 3 (total 20 pts).

1. Taking the derivative of $f(w)$ with respect to w :

$$f'(w) = \frac{1}{n} \sum_{i=1}^n x_i (wx_i - y_i) = w \left(\frac{1}{n} \sum_{i=1}^n x_i^2 \right) - \frac{1}{n} \sum_{i=1}^n x_i y_i$$

We get $f'(w) = w - w^*$ which vanishes at

$$w^* = \frac{\sum_{i=1}^n x_i y_i}{\sum_{i=1}^n x_i^2}$$

which is the global minimum. The second derivative is equal to $\frac{1}{n} \sum_{i=1}^n x_i^2$ and is strictly positive. Thus the function is strictly convex, hence there exist only a unique global minimum.

The GD update rule is:

$$w_{k+1} = w_k - \eta(w_k - w^*) \left(\frac{1}{n} \sum x_i^2 \right) \implies e_{k+1} = \left(1 - \eta \left(\frac{1}{n} \sum x_i^2 \right) \right) e_k$$

where $e_k = w_k - w^*$ and this converges to zero for $|1 - \eta \frac{1}{n} \sum x_i^2| < 1$, which yields the step size in the range $0 < \eta < \frac{2n}{\sum_i x_i^2}$.

2. The gradient of a single loss term $f_{i_k}(w)$ is $f'_{i_k}(w) = x_{i_k}(wx_{i_k} - y_{i_k}) = wx_{i_k}^2 - x_{i_k}y_{i_k}$. The average over a uniform distribution of indices i_k is exactly the full gradient found in the previous question. This justifies the SGD update equation.

Substituting $w_k = e_k + w^*$ into the SGD equation:

$$e_{k+1} + w^* = e_k + w^* - \eta((e_k + w^*)x_{i_k}^2 - x_{i_k}y_{i_k})$$

$$e_{k+1} = e_k(1 - \eta x_{i_k}^2) - \eta(w^* x_{i_k}^2 - x_{i_k}y_{i_k})$$

We take the conditional expectation $\mathbb{E}_{i_k}[\cdot \mid e_k]$ and note that e_k depends only on the past $i_{k-1}, \dots, i_1$. Since the index i_k is chosen uniformly at random, so we have $\mathbb{E}_{i_k}[x_{i_k}^2] = \frac{1}{n} \sum x_i^2$ and $\mathbb{E}_{i_k}[x_{i_k}y_{i_k}] = \frac{1}{n} \sum x_i y_i$. Thus $\mathbb{E}_{i_k}[w^* x_{i_k}^2 - x_{i_k}y_{i_k}] = 0$ (by the formula found above for w^*). Thus

$$\mathbb{E}_{i_k}[e_{k+1} \mid e_k] = e_k(1 - \eta \frac{1}{n} \sum x_i^2)$$

and hence for the total expectation we get $\mathbb{E}[e_{k+1}] = (1 - \eta \frac{1}{n} \sum x_i^2) \mathbb{E}[e_k]$.

3. Let $A_k = 1 - \eta x_{i_k}^2$ and $B_k = x_{i_k}y_{i_k} - w^* x_{i_k}^2$. The update equation is $e_{k+1} = e_k A_k + \eta B_k$. Squaring both sides yields:

$$e_{k+1}^2 = e_k^2 A_k^2 + 2\eta e_k A_k B_k + \eta^2 B_k^2$$

Taking the condition expectation first:

- e_k is independent of index i_k , so $\mathbb{E}_{i_k}[e_k^2 A_k^2] = e_k^2 \mathbb{E}_{i_k}[A_k^2] = e_k^2 \frac{1}{n} \sum_{i=1}^n (1 - \eta x_i^2)^2$.
- The cross-term satisfies $\mathbb{E}_{i_k}[e_k A_k B_k] = e_k \frac{1}{n} \sum_{i=1}^n (1 - \eta x_i)^2 (x_i y_i - w^* x_i^2)$.
- The last term is $\mathbb{E}_{i_k}[B_k^2] = \frac{1}{n} \sum_{i=1}^n (x_i y_i - w^* x_i^2)^2$.

This yields:

$$\begin{aligned} \mathbb{E}_{i_k}[e_{k+1}^2] &= e_k^2 \frac{1}{n} \sum_{i=1}^n (1 - \eta x_i^2)^2 + 2\eta e_k \frac{1}{n} \sum_{i=1}^n (1 - \eta x_i)^2 (x_i y_i - w^* x_i^2) + \eta^2 \frac{1}{n} \sum_{i=1}^n (x_i y_i - w^* x_i^2)^2 \\ &= \frac{1}{n} \sum_{i=1}^n (e_k (1 - \eta x_i^2) + \eta (x_i y_i - w^* x_i^2))^2 \end{aligned}$$

4. From the expression with the square expanded and noting that $\mathbb{E}[e_k] \rightarrow 0$ as $k \rightarrow +\infty$,

$$\lim_{k \rightarrow +\infty} \mathbb{E}[e_k^2] \left(1 - \frac{1}{n} \sum_{i=1}^n (1 - \eta x_i^2)^2\right) = \eta^2 \frac{1}{n} \sum_{i=1}^n (x_i y_i - w^* x_i^2)^2$$

which leads to

$$\begin{aligned} \lim_{k \rightarrow +\infty} \mathbb{E}[e_k^2] &= \frac{\eta^2 \frac{1}{n} \sum_{i=1}^n (x_i y_i - w^* x_i^2)^2}{\left(1 - \frac{1}{n} \sum_{i=1}^n (1 - \eta x_i^2)^2\right)} \\ &= \frac{\eta \sum_{i=1}^n (x_i y_i - w^* x_i^2)^2}{2 \sum_{i=1}^n x_i^2 (1 - \eta x_i^2)} \end{aligned}$$

Problem 4 (10 pts). Multiclass Shattering

Definition 1 (Shattering Multiclass Version). We say that a set $C \subseteq \mathcal{X}$ is *N-shattered* by $\mathcal{H}$ if there exist two functions $f_0, f_1 : C \rightarrow [k]$ such that

- For every $x \in C$, $f_0(x) \neq f_1(x)$.
- For every $B \subseteq C$, there exists a function $h \in \mathcal{H}$ such that

$$\forall x \in B, h(x) = f_0(x) \quad \text{and} \quad \forall x \in C \setminus B, h(x) = f_1(x).$$

Definition 2 (Natarajan Dimension). The *Natarajan dimension* of $\mathcal{H}$, denoted $\text{Ndim}(\mathcal{H})$, is the maximal size of a shattered set $C \subseteq \mathcal{X}$.

Consider the binary classification case $k = 2$:

1. Show that every VC-shattered set is N-shattered.
2. Show that every N-shattered set is VC-shattered.

Hint: Fix an arbitrary labeling of C and show that there exists an hypothesis $h \in \mathcal{H}$ that realize this labeling.

3. Deduce that, in the binary classification case,

$$\text{Ndim}(\mathcal{H}) = \text{VCdim}(\mathcal{H}).$$

Solution to Problem 4.

1. Every VC-shattered set is N-shattered. 4pt.

Let $C \subseteq \mathcal{X}$ be VC-shattered by $\mathcal{H}$. Define two functions

$$f_0(x) = 1, \quad f_1(x) = 0, \quad x \in C.$$

Clearly,

$$f_0(x) \neq f_1(x)$$

for every $x \in C$.

Let $B \subseteq C$ be arbitrary. Since C is VC-shattered, there exists a hypothesis $h \in \mathcal{H}$ realizing the labeling

$$h(x) = 1 \quad \forall x \in B, \quad h(x) = 0 \quad \forall x \in C \setminus B.$$

Equivalently,

$$h(x) = f_0(x) \quad \forall x \in B, \quad h(x) = f_1(x) \quad \forall x \in C \setminus B.$$

Therefore the conditions of N-shattering are satisfied, and hence C is N-shattered.

2. Every N-shattered set is VC-shattered. 4pt.

Let $C \subseteq \mathcal{X}$ be N-shattered. Then there exist functions

$$f_0, f_1 : C \rightarrow \{0, 1\}$$

such that

(a) $f_0(x) \neq f_1(x)$ for every $x \in C$;

(b) for every $B \subseteq C$, there exists $h \in \mathcal{H}$ such that

$$h(x) = f_0(x) \quad \forall x \in B, \quad h(x) = f_1(x) \quad \forall x \in C \setminus B.$$

Since there are only two labels, the condition $f_0(x) \neq f_1(x)$ implies that

$$\{f_0(x), f_1(x)\} = \{0, 1\}$$

for every $x \in C$.

Let $g : C \rightarrow \{0, 1\}$ be an arbitrary binary labeling of C . Define

$$B = \{x \in C : g(x) = f_0(x)\}.$$

By N-shattering, there exists $h \in \mathcal{H}$ such that

$$h(x) = f_0(x) \quad \forall x \in B, \quad h(x) = f_1(x) \quad \forall x \in C \setminus B.$$

If $x \in B$, then $h(x) = f_0(x) = g(x)$. If $x \notin B$, then $g(x) \neq f_0(x)$; since the only labels are 0 and 1, it follows that

$$g(x) = f_1(x) = h(x).$$

Hence $h(x) = g(x)$ for every $x \in C$.

Since every binary labeling g of C is realized by some hypothesis in $\mathcal{H}$, the set C is VC-shattered.

3. Equality of the dimensions. 2pt.

Part (1) shows that every VC-shattered set is N-shattered. Therefore

$$\text{VCdim}(\mathcal{H}) \leq \text{Ndim}(\mathcal{H}).$$

Part (2) shows that every N-shattered set is VC-shattered. Therefore

$$\text{Ndim}(\mathcal{H}) \leq \text{VCdim}(\mathcal{H}).$$

Combining the two inequalities yields

$$\boxed{\text{Ndim}(\mathcal{H}) = \text{VCdim}(\mathcal{H}).}$$