

Astrophysics IV: Stellar and galactic dynamics

Solutions

Problem 1:

In two dimensions and in cylindrical coordinates, assuming a bar rotating with a pattern speed $\vec{\Omega}_b = \Omega_b \vec{e}_z$, the Lagrangian writes:

$$L(R, \dot{R}, \theta, \dot{\theta}) = \frac{1}{2} \dot{R}^2 + \frac{1}{2} \left(R (\dot{\theta} + \Omega_b) \right)^2 - \phi(R, \theta). \quad (1)$$

The equations of motion are derived using the Euler-Lagrange equation:

$$\begin{cases} \ddot{R} = R (\dot{\theta} + \Omega_b)^2 - \frac{\partial \phi}{\partial R} \\ \frac{d}{dt} \left(R^2 (\dot{\theta} + \Omega_b) \right) = - \frac{\partial \phi}{\partial \theta} \end{cases}. \quad (2)$$

We assume a weak bar with:

$$\phi(R, \theta) = \phi_0(R) + \phi_1(R, \theta), \quad \left| \frac{\phi_1}{\phi_0} \right| \ll 1, \quad (3)$$

where ϕ_0 represents the cylindrical symmetry, while ϕ_1 the perturbation. We then split the motion into two parts:

$$\begin{cases} R(t) = R_0 + R_1(t) \\ \theta(t) = \theta_0(t) + \theta_1(t) \end{cases} \quad (4)$$

with R_0 the radius of the guiding centre (circular orbit). The goal is then to develop the equations of motion at the first order and interpret both the zeroth and first-order terms.

To do so, we first need to Taylor expand the potential:

$$\phi(R, \theta) \cong \phi_0(R_0) + \phi_1(R_0, \theta) + \left. \frac{\partial \phi_0}{\partial R} \right|_{R_0} (R - R_0) + \left. \frac{\partial \phi_1}{\partial R} \right|_{R_0} (R - R_0) \quad (5)$$

$$+ \left. \frac{1}{2} \frac{\partial^2 \phi_0}{\partial R^2} \right|_{R_0} (R - R_0)^2 + \left. \frac{1}{2} \frac{\partial^2 \phi_1}{\partial R^2} \right|_{R_0} (R - R_0)^2, \quad (6)$$

Then, differentiating the potential with respect to R and θ , we get:

$$\begin{cases} \frac{\partial \phi}{\partial R} \cong \left. \frac{\partial \phi_0}{\partial R} \right|_{R_0} + \left. \frac{\partial \phi_1}{\partial R} \right|_{R_0} + \left. \frac{\partial^2 \phi_0}{\partial R^2} \right|_{R_0} (R - R_0) \\ \frac{\partial \phi}{\partial \theta} \cong \left. \frac{\partial \phi_1}{\partial \theta} \right|_{R_0} \end{cases}. \quad (7)$$

Note, we drop the $\left. \frac{\partial^2 \phi_1}{\partial R^2} \right|_{R_0} (R - R_0)$ term, as $\phi_1 \ll \phi_0$.

Now, the goal is to introduce Eq. 3 and Eq. 7 in the equations of motion (1) and discuss the terms of different orders.

Zeroth order terms :

1. Radial equation

$$\ddot{R} = R \left(\dot{\theta} + \Omega_b \right)^2 - \frac{\partial \phi}{\partial R} \rightarrow R_0 \left(\dot{\theta}_0 + \Omega_b \right)^2 = \left. \frac{\partial \phi_0}{\partial R} \right|_{R_0} ; \quad (8)$$

2. Azimuthal equation

$$\frac{d}{dt} \left(R^2 \left(\dot{\theta} + \Omega_b \right) \right) = - \frac{\partial \phi}{\partial \theta} \rightarrow \dot{\theta}_0 = \text{const.} \quad (9)$$

Interpretation: in the absence of perturbation, the circular frequency at the radius R_0 is written:

$$\Omega^2 (R_0) = \left. \frac{1}{R_0} \frac{\partial \phi_0}{\partial R} \right|_{R_0}, \quad (10)$$

thus, Eq. 8 leads to:

$$\dot{\theta}_0 + \Omega_b = \Omega (R_0) = \Omega_0, \quad (11)$$

and the angular frequency in the rotating rest frame is then:

$$\theta_0 (t) = (\Omega_0 - \Omega_b) t. \quad (12)$$

First order terms :

1. Radial equation

$$\ddot{R} = R \left(\dot{\theta} + \Omega_b \right)^2 - \frac{\partial \phi}{\partial R} \rightarrow \ddot{R}_1 + R_1 \left(\frac{\partial^2 \phi_0}{\partial R^2} - \Omega_b^2 \right) \Big|_{R_0} - 2R_0 \dot{\theta}_1 \Omega_0 = - \left. \frac{\partial \phi_1}{\partial R} \right|_{R_0} ; \quad (13)$$

2. Azimuthal equation

$$\frac{d}{dt} \left(R^2 \left(\dot{\theta} + \Omega_b \right) \right) = - \frac{\partial \phi}{\partial \theta} \rightarrow \ddot{\theta}_1 + 2\Omega_0 \frac{\dot{R}_1}{R_0} = - \left. \frac{1}{R_0^2} \frac{\partial \phi_1}{\partial \theta} \right|_{R_0}. \quad (14)$$

To move forward, we have to guess some specific potential. We assume a perturbation of the type:

$$\phi_1 (R, \theta) = \phi_b (R) \cos (m\theta). \quad (15)$$

where $m = 2$ corresponds to a bar.

Note also that any other perturbation can be obtained by summing over m .

Assuming $\theta_1 \ll \theta_0$, the gradients of Eq. 7 can now be written as:

$$\begin{cases} \frac{\partial \phi_1}{\partial R} = \frac{\phi_b}{\partial R} \cos(m\theta) \approx \frac{\partial \phi_b}{\partial R} \cos(m\theta_0) = \frac{\partial \phi_b}{\partial R} \cos(m(\Omega_0 - \Omega_b)t) \\ \frac{\partial \phi_1}{\partial \theta} = -\phi_b(R) \sin(m\theta)m \approx -\phi_b(R) m \sin(m(\Omega_0 - \Omega_b)t) \end{cases} . \quad (16)$$

Introducing those gradients in Eq 13 and 2, we get:

$$\begin{cases} \ddot{R}_1 + R_1 \left(\frac{\partial^2 \phi_0}{\partial R^2} - \Omega^2 \right) \Big|_{R_0} - 2R_0 \dot{\theta}_1 \Omega_0 = - \frac{\partial \phi_b}{\partial R} \Big|_{R_0} \cos(m(\Omega_0 - \Omega_b)t) \\ \ddot{\theta}_1 + 2\Omega_0 \frac{\dot{R}_1}{R_0} = \frac{m\phi_b(R_0)}{R_0^2} \sin(m(\Omega_0 - \Omega_b)t) \end{cases} . \quad (17)$$

At this stage, it is possible to integrate $\ddot{\theta}_1$ over time:

$$\dot{\theta}_1 = -2\Omega_0 \frac{R_1}{R_0} - \frac{\phi_b(R_0)}{R_0^2 (\Omega_0 - \Omega_b)} \cos(m(\Omega_0 - \Omega_b)t) + const, \quad (18)$$

and replacing it in the equation for \ddot{R}_1 we find:

$$\ddot{R}_1 + \kappa_0^2 R_1 = - \left[\frac{\partial \phi_b}{\partial R} + \frac{2\Omega_0 \phi_b}{R(\Omega_0 - \Omega_b)} \right]_{R_0} \cos(m(\Omega_0 - \Omega_b)t) + const. \quad (19)$$

Note that we have used the radial epicycle frequency:

$$\kappa_0^2 = \left(\frac{\partial^2 \phi}{\partial R^2} + 3\Omega^2 \right) \Big|_{R_0} . \quad (20)$$

The general solution is a harmonic oscillator of frequency κ_0 driven at frequency $m(\Omega_0 - \Omega_b)$.

Using Eq. 12 we find:

$$R_1(\theta_0) = C_1 \cos\left(\frac{\chi_0 \theta_0}{\Omega_0 - \Omega_b} + \alpha\right) - \left[\frac{\partial \phi_b}{\partial R} + \frac{2\Omega_0 \phi_b}{R(\Omega_0 - \Omega_b)} \right]_{R_0} \frac{\cos(m\theta_0)}{\chi_0^2 - m^2(\Omega_0 - \Omega_b)^2}, \quad (21)$$

with C_1 and α arbitrary constants.

Problem 2:

We start from the Hamiltonian of a 1-D harmonic oscillator, assuming a frequency ω :

$$H = \frac{1}{2} \dot{x}^2 + \frac{1}{2} \omega^2 x^2$$

The equations of motion (Hamilton equations) are:

$$\begin{cases} \dot{x} = \dot{x} \\ \dot{x} = -\omega^2 x \end{cases}$$

with the general solution:

$$\begin{cases} x(t) = A \cos(\omega t + \alpha) + B \sin(\omega t + \alpha) \\ \dot{x}(t) = -A\omega \sin(\omega t + \alpha) + B\omega \cos(\omega t + \alpha) \end{cases}$$

Taking the square, we get:

$$\begin{cases} x^2(t) = A^2 \cos^2(\omega t + \alpha) + B^2 \sin^2(\omega t + \alpha) + 2AB \cos^2(\omega t + \alpha) \sin^2(\omega t + \alpha) \\ \dot{x}^2(t) = A^2 \omega^2 \sin^2(\omega t + \alpha) + B^2 \omega^2 \cos^2(\omega t + \alpha) - 2AB \omega^2 \cos^2(\omega t + \alpha) \sin^2(\omega t + \alpha) \end{cases}$$

and thus:

$$x(t)^2 + \frac{\dot{x}^2(t)}{\omega^2} = A^2 + B^2 .$$

which is the equation of an ellipse of ellipticity w (if $w < 1$) or $1/w$ (if $w > 1$).

Assuming $\alpha = 0$ we have:

$$\begin{cases} A = x_0 \\ B = v_0/\omega \end{cases}$$

and the evolution is equivalent to multiplying the initial position and velocity by a matrix (time operator):

$$\begin{pmatrix} x(t) \\ \dot{x}(t) \end{pmatrix} = \begin{pmatrix} \cos(\omega t) & \frac{1}{\omega} \sin(\omega t) \\ -\omega \sin(\omega t) & \cos(\omega t) \end{pmatrix} \cdot \begin{pmatrix} x_0 \\ \dot{x}_0 \end{pmatrix}$$

The geometrical interpretation of the matrix is to apply a rotation with some deformation (if $w = 1$, this is a pure rotation). However, as the determinant of the matrix is 1, the area is conserved and thus the density of the phase space is conserved.