



Differential Geometry II - Smooth Manifolds

Winter Term 2025/2026

Lecturer: Dr. N. Tsakanikas

Assistant: L. E. Rösler

Exercise Sheet 2

Exercise 1 (*Finite-dimensional vector spaces*):

Let V be an $\mathbb{R}$ -vector space of dimension n . Recall that any norm on V determines a topology, which is independent of the choice of norm. Show that V has a natural smooth manifold structure as follows:

- (a) Pick a basis $E_1, \dots, E_n$ for V and consider the map

$$E: \mathbb{R}^n \rightarrow V, (x^1, \dots, x^n) \mapsto \sum_{i=1}^n x^i E_i.$$

Show that (V, E^{-1}) is a chart for V ; in particular, with the topology defined above, V is thus a topological n -manifold.

- (b) Given a different basis $\tilde{E}_1, \dots, \tilde{E}_n$ for V , show that the charts (V, E^{-1}) and $(V, \tilde{E}^{-1})$ are smoothly compatible.

The collection of all such charts for V defines a smooth structure, called the *standard smooth structure on V* .

Exercise 2:

Prove the following assertions:

- (a) The space $M(m \times n, \mathbb{R})$ of $m \times n$ matrices with real entries has a natural smooth manifold structure.
- (b) The *general linear group* $\mathrm{GL}(n, \mathbb{R})$ (i.e., the group of invertible $n \times n$ matrices with real entries) has a natural smooth manifold structure.
- (c) The subset $M_m(m \times n, \mathbb{R})$ of $M(m \times n, \mathbb{R})$ of matrices of rank m , where $m < n$ has a natural smooth manifold structure. Similarly for $M_n(m \times n, \mathbb{R})$ when $n < m$.
- (d) The space $\mathcal{L}(V, W)$ of $\mathbb{R}$ -linear maps from V to W , where V and W are two finite-dimensional $\mathbb{R}$ -vector spaces, has a natural smooth manifold structure.

What is the dimension of each of the above smooth manifolds?

Exercise 3 (*Product manifolds*):

Let $M_1, \dots, M_k$ be smooth manifolds of dimensions $n_1, \dots, n_k$, respectively, where $k \geq 2$. Show that the product space $M_1 \times \dots \times M_k$ is a smooth manifold of dimension $n_1 + \dots + n_k$ by constructing a smooth manifold structure on it.

Remark. The n -torus

$$\mathbb{T}^n := \mathbb{S}^1 \times \dots \times \mathbb{S}^1$$

is a smooth n -manifold by *Exercise 3*.

Exercise 4 (*The real projective n -space*):

Denote by $\mathbb{RP}^n$ the real projective n -space, where $n \geq 1$. For each $i \in \{0, \dots, n\}$ consider the chart (U_i, φ_i) for $\mathbb{RP}^n$ described in Appendix A, where

$$U_i := \{[x_0 : \dots : x_n] \in \mathbb{RP}^n \mid x_i \neq 0\} \subseteq \mathbb{RP}^n$$

and

$$\begin{aligned} \varphi_i: U_i &\rightarrow \mathbb{R}^n \\ [x_0 : \dots : x_n] &\mapsto \left(\frac{x_0}{x_i}, \dots, \frac{x_{i-1}}{x_i}, \frac{x_{i+1}}{x_i}, \dots, \frac{x_n}{x_i} \right). \end{aligned}$$

Show that the collection

$$\mathcal{A}_{\mathbb{RP}^n} := \{(U_i, \varphi_i)\}_{i=0}^n$$

is a smooth atlas for $\mathbb{RP}^n$.

Exercise 5 (to be submitted by Thursday, 25.09.2025, 16:00):

Consider the n -sphere $\mathbb{S}^n \subseteq \mathbb{R}^{n+1}$. Denote by $N = (0, \dots, 0, 1) \in \mathbb{R}^{n+1}$ the *north pole* and by $S = -N = (0, \dots, 0, -1)$ the *south pole* of $\mathbb{S}^n$. Define the *stereographic projection from the north pole N* as follows:

$$\sigma: \mathbb{S}^n \setminus \{N\} \rightarrow \mathbb{R}^n, \quad \sigma(x^1, \dots, x^{n+1}) = \frac{1}{1 - x^{n+1}} (x^1, \dots, x^n).$$

Let $\tilde{\sigma}(x) = -\sigma(-x)$ for $x \in \mathbb{S}^n \setminus \{S\}$; it is called the *stereographic projection from the south pole*.

- (a) For any $x \in \mathbb{S}^n \setminus \{N\}$, show that $\sigma(x) = u$, where $(u, 0)$ is the point where the line through N and x intersects the linear subspace where $x^{n+1} = 0$. Similarly, show that $\tilde{\sigma}(x)$ is the point where the line through S and x intersects the same subspace.
- (b) Show that σ is bijective, and

$$\sigma^{-1}(u^1, \dots, u^n) = \frac{1}{|u|^2 + 1} (2u^1, \dots, 2u^n, |u|^2 - 1).$$

- (c) Verify that the atlas consisting of the two charts $(\mathbb{S}^n \setminus \{N\}, \sigma)$ and $(\mathbb{S}^n \setminus \{S\}, \tilde{\sigma})$ is a smooth atlas for $\mathbb{S}^n$, and hence defines a smooth structure on $\mathbb{S}^n$. (The coordinates defined by σ or $\tilde{\sigma}$ are called *stereographic coordinates*.)
- (d) Show that the smooth structure determined by the above atlas is the same as the one defined via graph coordinates in *Example 1.10(2)*.