

# **Stellar orbits**

**2<sup>nd</sup> part**

# Outlines

## Orbits in axisymmetric potentials

- orbits in the equatorial plane
- orbits outside the equatorial plane
- equations of motion
- orbits in the meridian plane
- examples

## Nearly circular orbits

- Epicycle frequencies

**Stellar orbits**

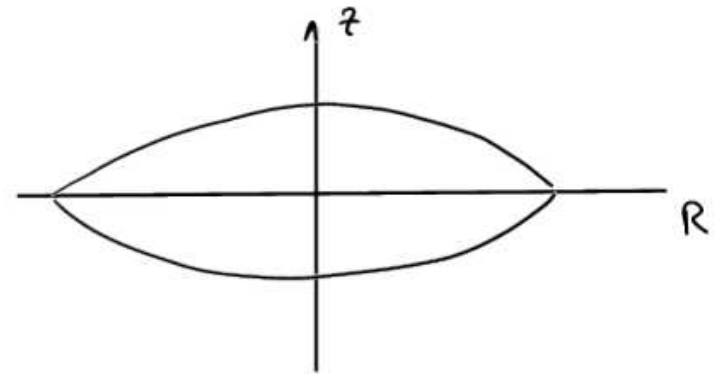
**Axisymmetric Systems**

# Orbits in axisymmetric potentials

## Axisymmetric potential

$$\phi(\vec{x}) = \phi(R, |z|)$$

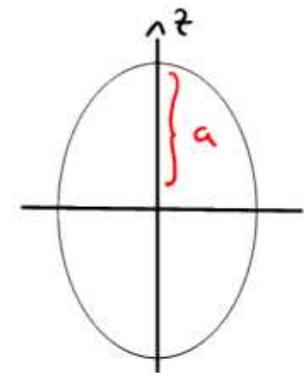
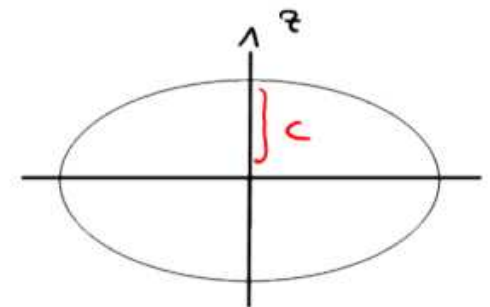
- symmetry of revolution around  $z$
- reflection symmetry with respect to the  $z=0$  plane



## Definitions

Oblate systems :  $c$ , the semi-minor axis is parallel to  $\vec{z}$

Prolate systems :  $a$ , the semi-major axis is parallel to  $\vec{z}$



## Description of the dynamics

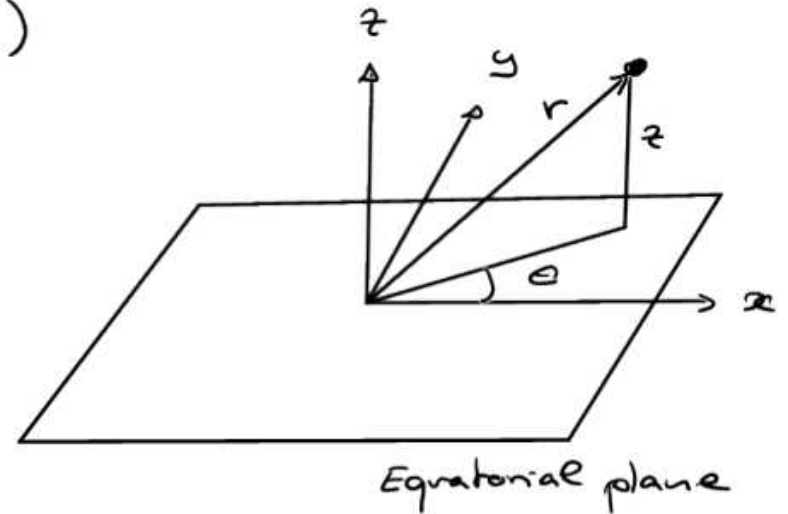
Cylindrical coordinates

$$(R, \theta, z)$$

Orbits in the equatorial plane

$$\forall t, \underline{z = 0}$$

$$\phi(R, |z|=0) \equiv \phi(R)$$



The potential seen by the stars is similar to a spherical potential

- description of the orbits in polar coordinates  $r, \varphi$
- recycle all results developed for spherical potentials

## Angular momentum derivative

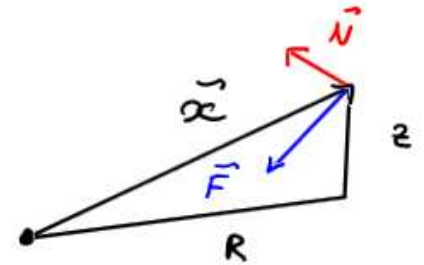
$$\frac{d\vec{L}}{dt} = \vec{x} \times \vec{g}(\vec{x}) = \vec{N}$$

$$\vec{x} = R \vec{e}_R + z \vec{e}_z$$

$$\vec{g}(\vec{x}) = -\vec{\nabla} \phi(x)$$

$$= -\frac{\partial \phi}{\partial R} \vec{e}_R - \frac{1}{R} \frac{\partial \phi}{\partial \theta} \vec{e}_\theta - \frac{\partial \phi}{\partial z} \vec{e}_z$$

$= 0$



$$\frac{d\vec{L}}{dt} = \left( z \frac{\partial \phi}{\partial R} - R \frac{\partial \phi}{\partial z} \right) \vec{e}_\theta$$

①

But

$$\vec{L} = L_R \vec{e}_R + L_\theta \vec{e}_\theta + L_z \vec{e}_z$$

$$\begin{cases} \dot{\vec{e}}_R = \dot{\theta} \vec{e}_\theta \\ \dot{\vec{e}}_\theta = -\dot{\theta} \vec{e}_R \\ \dot{\vec{e}}_z = 0 \end{cases}$$

$$\begin{aligned} \frac{d\vec{L}}{dt} &= \dot{L}_R \vec{e}_R + L_R \dot{\vec{e}}_R + \dot{L}_\theta \vec{e}_\theta + L_\theta \dot{\vec{e}}_\theta + \dot{L}_z \vec{e}_z \\ &= (\dot{L}_R - L_\theta \dot{\theta}) \vec{e}_R + (\dot{L}_\theta + L_R \dot{\theta}) \vec{e}_\theta + \dot{L}_z \vec{e}_z \end{aligned}$$

comparing with (1)

$$\begin{cases} \dot{L}_z = 0 & \Rightarrow L_z = \text{cte} \\ \dot{L}_R - L_\theta \dot{\theta} = 0 & \Rightarrow L_z = \text{cte} \end{cases}$$

**EXERCISE**

The  $z$ -component of the angular momentum is conserved

Orbits that moves outside the equatorial plane

Cylindrical coordinates

$$\begin{cases} x = R \cos \theta & \dot{x} = \dot{R} \cos \theta - R \sin \theta \dot{\theta} \\ y = R \sin \theta & \dot{y} = \dot{R} \sin \theta + R \cos \theta \dot{\theta} \\ z = z & \dot{z} = \dot{z} \end{cases}$$

$$\underline{\dot{x}^2 + \dot{y}^2 = \dot{R}^2 + R^2 \dot{\theta}^2}$$

Lagrangian (specific) in cylindrical coordinates

$$\mathcal{L} = \frac{1}{2} (\dot{x}^2 + \dot{y}^2) + \phi(\sqrt{x^2 + y^2}) = \frac{1}{2} (\dot{R}^2 + R^2 \dot{\theta}^2 + \dot{z}^2) - \phi(R, z)$$

Lagrange equations

$$\boxed{\frac{d}{dt} \left( \frac{\partial \mathcal{L}}{\partial \dot{\vec{q}}} \right) - \frac{\partial \mathcal{L}}{\partial \vec{q}} = 0}$$

$$\vec{q} = \begin{Bmatrix} R \\ \theta \\ z \end{Bmatrix} \quad \dot{\vec{q}} = \begin{Bmatrix} \dot{R} \\ \dot{\theta} \\ \dot{z} \end{Bmatrix}$$



## Lagrange equations

$$\begin{cases} \ddot{R} = R\dot{\theta}^2 & - \frac{\partial \phi}{\partial R} & (1) \\ \frac{d}{dt}(R^2\dot{\theta}) = & \left( - \frac{\partial \phi}{\partial \theta} \right) = 0 & (2) \\ \ddot{z} = & - \frac{\partial \phi}{\partial z} & (3) \end{cases}$$

$$(2) \quad R^2\dot{\theta} = \text{cte} = L_z$$

The  $z$ -component of the angular momentum is conserved

Solution

$$\theta(t) = L_z \int_{t_0}^{t_1} \frac{1}{R^2(r)} dt$$

(1) + (3) two coupled through  $\phi(R, z)$  equations for  $R$  and  $z$

## Hamiltonian/Energy

$$H(\vec{q}, \vec{p}, t) := \vec{p} \cdot \dot{\vec{q}} - L(\vec{q}, \dot{\vec{q}}, t)$$

$$\vec{q} = \begin{cases} R \\ \theta \\ z \end{cases} \quad \dot{\vec{q}} = \begin{cases} \dot{R} \\ \dot{\theta} \\ \dot{z} \end{cases}$$

$$\vec{p} = \begin{cases} \frac{\partial L}{\partial \dot{R}} = \dot{R} \\ \frac{\partial L}{\partial \dot{\theta}} = R^2 \dot{\theta} \\ \frac{\partial L}{\partial \dot{z}} = \dot{z} \end{cases}$$

$$p_{\theta} = R^2 \dot{\theta} = L_z$$

$$H(R, \dot{R}, \theta, \dot{\theta}, z, \dot{z}) = \frac{1}{2} (\dot{R}^2 + R^2 \dot{\theta}^2 + \dot{z}^2) + \phi(R, z) = E$$

$E$  (Energy) is conserved

as  $L$  is time independent

$\phi$

## Effective potential

$$\text{with } L_z = R^2 \dot{\theta}$$

Definition

$$\phi_{\text{eff}}(R, z) = \phi(R, z) + \frac{L_z^2}{2R^2}$$

$$L_z^2 = R^4 \dot{\theta}^2$$

$$\left\{ \begin{array}{l} \frac{\partial \phi_{\text{eff}}}{\partial R} = \frac{\partial \phi}{\partial R} - \frac{L_z^2}{R^3} \equiv \frac{\partial \phi}{\partial R} - R \dot{\theta}^2 \\ \frac{\partial \phi_{\text{eff}}}{\partial z} = \frac{\partial \phi}{\partial z} \end{array} \right.$$

The equations of motion (1) + (3) becomes

$$\left\{ \begin{array}{l} \ddot{R} = - \frac{\partial \phi_{\text{eff}}}{\partial R}(R, z) \\ \ddot{z} = - \frac{\partial \phi_{\text{eff}}}{\partial z}(R, z) \end{array} \right.$$

The 3D motion of a star in an axisymmetric potential is reduced to a 2D motion in the meridian plane  $(R, z)$

phase space  $6D \rightarrow 4D$

## Hamiltonian in the meridian plane

Those equations of motion may be derived from the Lagrangian

$$\mathcal{L}(R, \dot{R}, z, \dot{z}) = \frac{1}{2} \dot{R}^2 + \frac{1}{2} \dot{z}^2 - \phi_{\text{eff}}(R, z)$$

The corresponding Hamiltonian writes  $(p_R = \dot{R}, p_z = \dot{z})$

$$\begin{aligned} H(R, \dot{R}, z, \dot{z}) &= \frac{1}{2} (\dot{R}^2 + \dot{z}^2) + \phi_{\text{eff}}(R, z) \\ &= \frac{1}{2} (\dot{R}^2 + \dot{z}^2) + \phi(R, z) + \frac{L_z^2}{2R^2} \\ &= \frac{1}{2} (\dot{R}^2 + \dot{z}^2) + \phi(R, z) + \frac{1}{2} R^2 \dot{\theta}^2 = E \end{aligned}$$

kinetic energy  
in the orbital  
plane

$E$  is conserved  
as  $\phi_{\text{eff}}$  is  
time independent

orbit's  
total energy

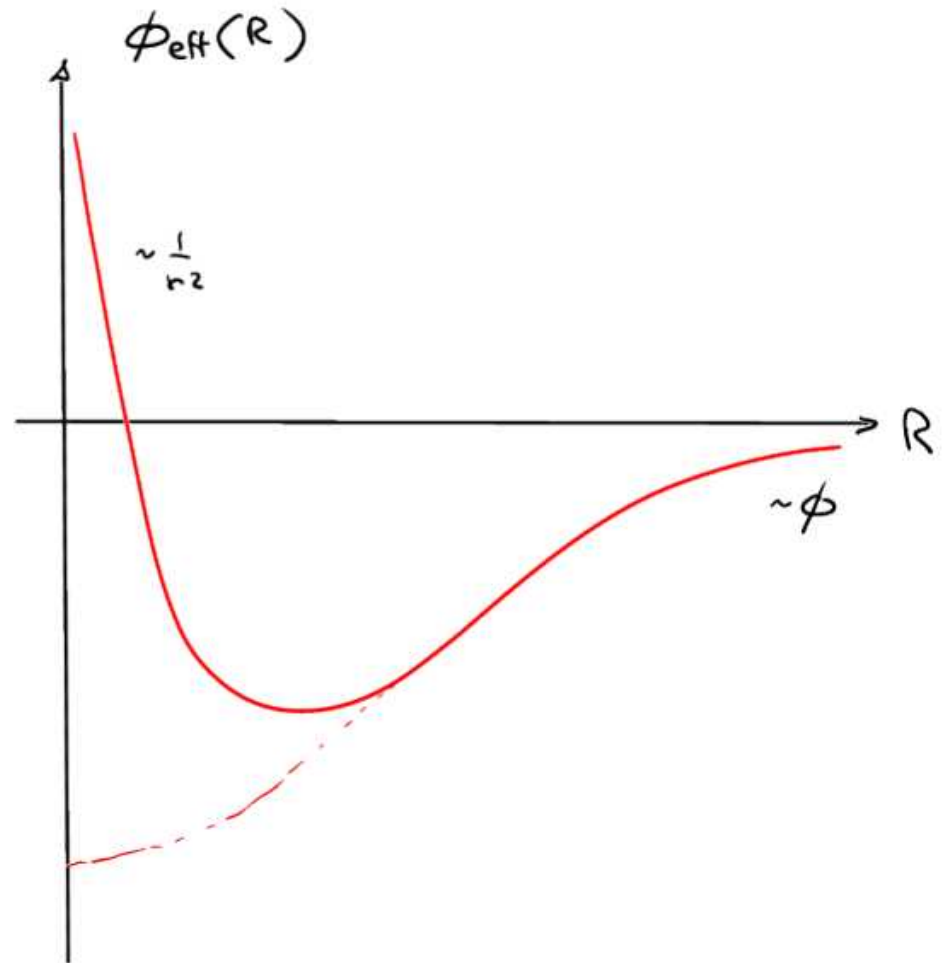
## Illustration in the $z=0$ plane

for  $R \rightarrow \infty$

$$\phi_{\text{eff}} = \phi + \underbrace{\frac{L^2}{2}}_{\rightarrow 0} \frac{1}{R^2} \sim \phi$$

for  $R \rightarrow 0$

$$\phi_{\text{eff}} = \underbrace{\phi}_{\text{bounded}} + \underbrace{\frac{L^2}{2}}_{\text{diverges}} \frac{1}{R^2} \sim \frac{1}{R^2}$$

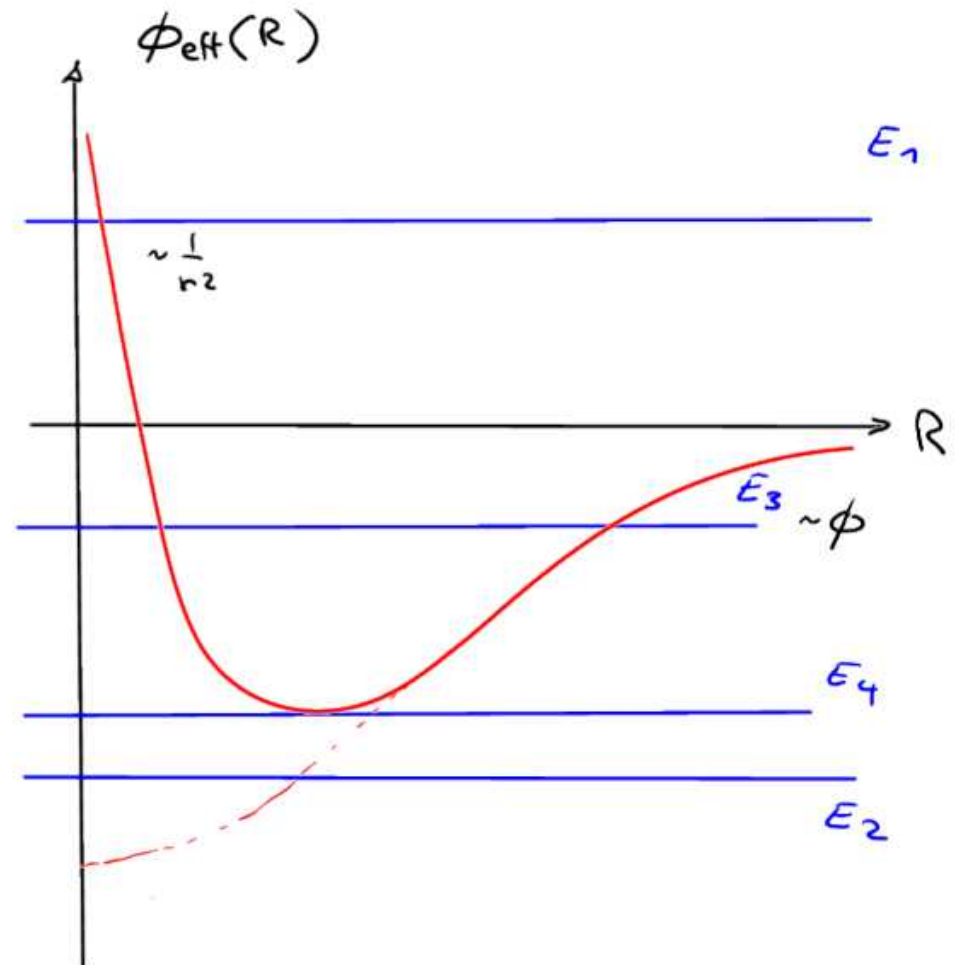


## Illustration in the $z=0$ plane

$$E = \frac{1}{2} \dot{R}^2 + \phi_{\text{eff}}(R)$$

### 4 cases

- ①  $E > \phi_{\text{eff}}(\infty)$  except at  $E = \phi_{\text{eff}}$   
 $\dot{R} \neq 0$  unbound orbits
- ②  $E < \min(\phi_{\text{eff}}(R))$   $\dot{R}^2 < 0$   
impossible
- ③  $\min(\phi_{\text{eff}}(R)) < E < \phi_{\text{eff}}(\infty)$   
orbit bounded between  $R_1$  and  $R_2$  (where  $\dot{R} = 0$ )
- ④  $E = \min(\phi_{\text{eff}}(R))$  (stationary point)  
 $R_1 = R_2$  (circular orbit)



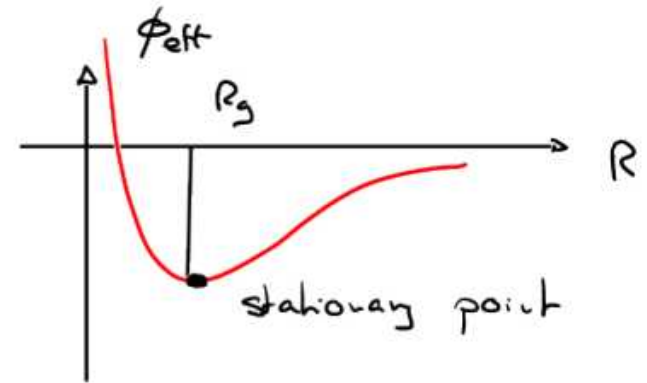
Stationary point

$$\dot{R} = \ddot{R} = 0$$

$$\dot{z} = \ddot{z} = 0$$

from

$$\begin{cases} \ddot{R} = - \frac{\partial \phi_{\text{eff}}}{\partial R}(R, z) \\ \ddot{z} = - \frac{\partial \phi_{\text{eff}}}{\partial z}(R, z) \end{cases}$$



$$\begin{cases} \frac{\partial \phi_{\text{eff}}}{\partial R} = 0 & = \frac{\partial \phi}{\partial R} - \frac{L_z^2}{R^3} = 0 \\ \frac{\partial \phi_{\text{eff}}}{\partial z} = 0 & = \frac{\partial \phi}{\partial z} = 0 \end{cases}$$

→ by symmetry where  $z = 0$

$$R_g \text{ such that } \left. \frac{\partial \phi}{\partial R} \right|_{R_g, 0} = \frac{L_z^2}{R_g^3} = R_g \overset{V_g = R\dot{\phi}}{e^2} = \frac{V_e^2(R_g)}{R_g} = \frac{V_c^2(R_g)}{R_g}$$

$$V_c^2 = R \left. \frac{\partial \phi}{\partial R} \right|_{R, 0}$$

$R_g$  : guiding center

The stationary point in  $R_g$  in the meridional plane corresponds to a circular orbit



## Circular orbits

angular speed

$$\dot{\theta} = \frac{L_z}{R_g^2}$$

angular momentum

$$L_z$$

energy

$$\phi_{\text{eff}} + \frac{L_z^2}{2R_g}$$

Note

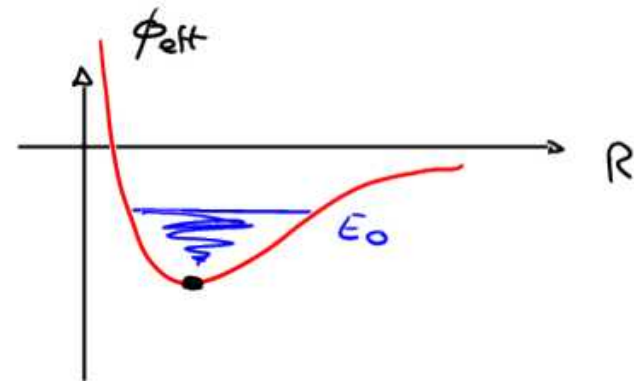
For a given angular momentum  $L_z$ , the circular orbit is the one that minimize the energy.

$$\textcircled{1} \quad E_0 = \frac{1}{2} \dot{R}^2 + \frac{1}{2} \dot{z}^2 + \phi + \frac{L_z^2}{2R}$$

$\textcircled{2}$  Dissipate energy  
~~~~~

$$L_z = \text{cte}$$
$$\dot{z} \gg \dot{R}$$

$\textcircled{3}$  circular orbit





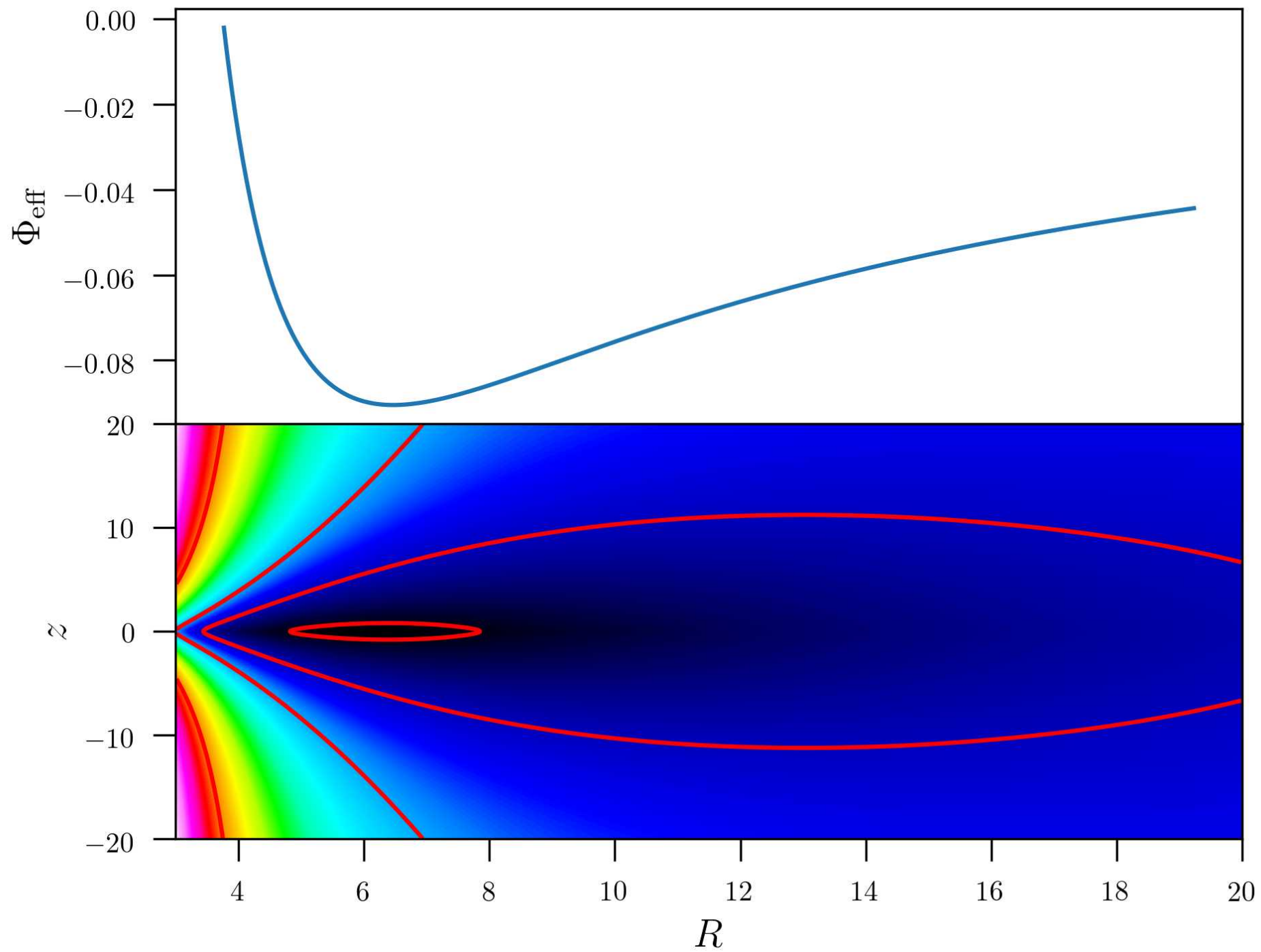
## Examples

### ① Miyamoto - Nagai potential

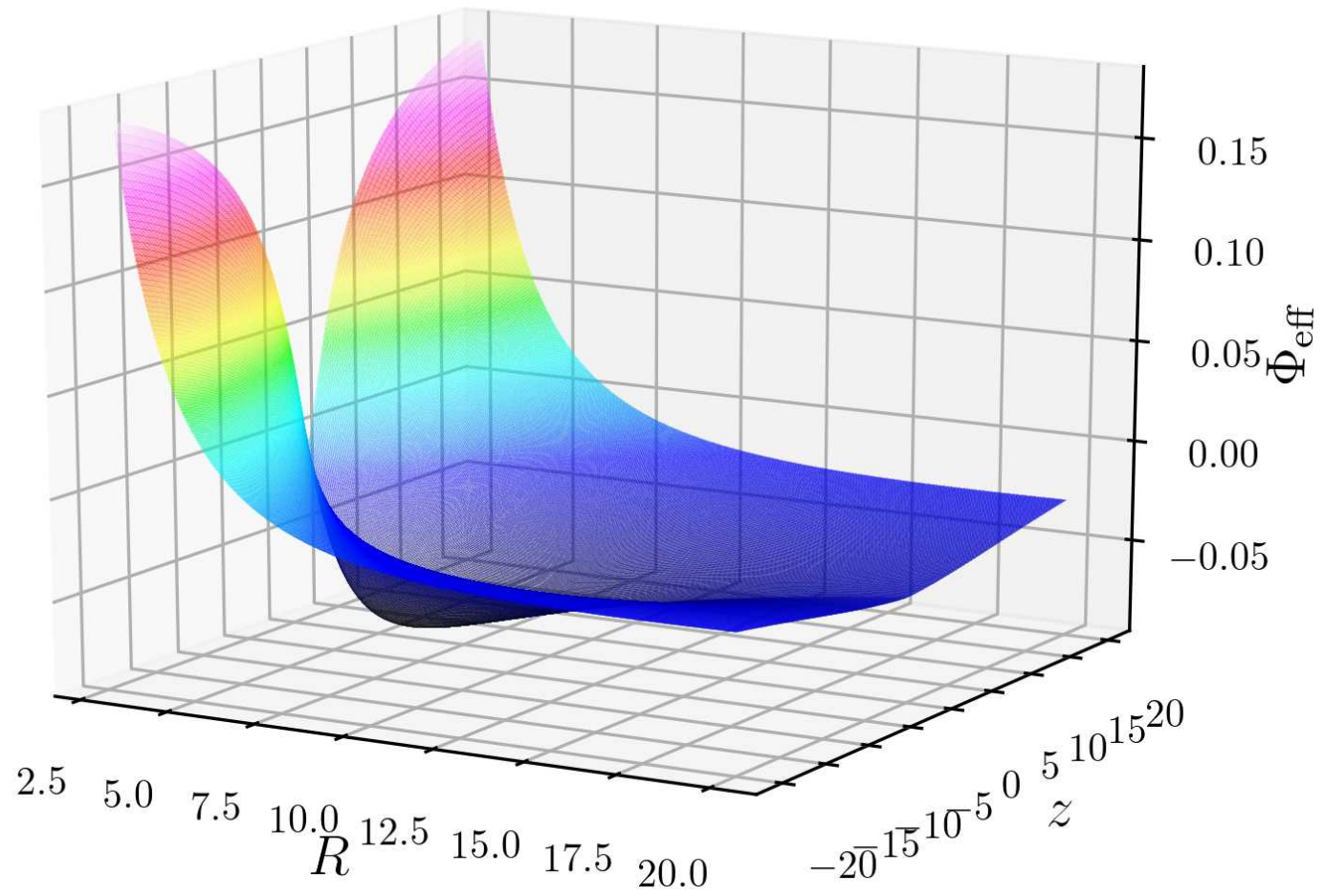
$$\phi(R, z) = - \frac{GM}{\sqrt{R^2 + (a + \sqrt{z^2 + b^2})^2}}$$

$$\phi_{\text{eff}}(R, z=0) = - \frac{GM}{\sqrt{R^2 + (a+b)^2}} + \frac{L_z^2}{2R^2}$$

Miyamoto Nagai Potential



# Miyamoto Nagai Potential



## Examples

### ① Miyamoto - Nagai potential

$$\phi(R, z) = - \frac{GM}{\sqrt{R^2 + (a + \sqrt{z^2 + b^2})^2}}$$

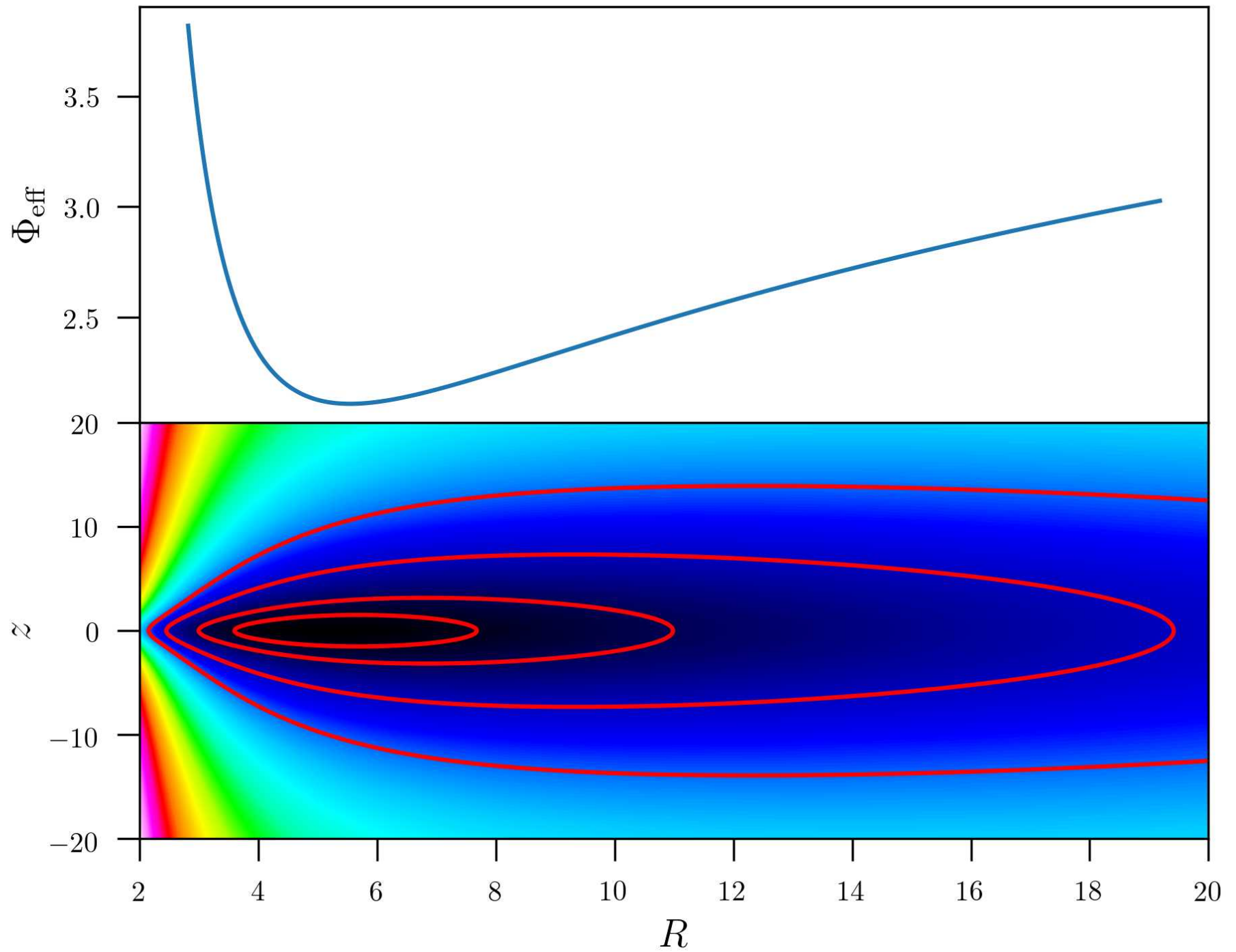
$$\phi_{\text{eff}}(R, z=0) = - \frac{GM}{\sqrt{R^2 + (a+b)^2}} + \frac{L_z^2}{2R^2}$$

### ② Logarithmic potential

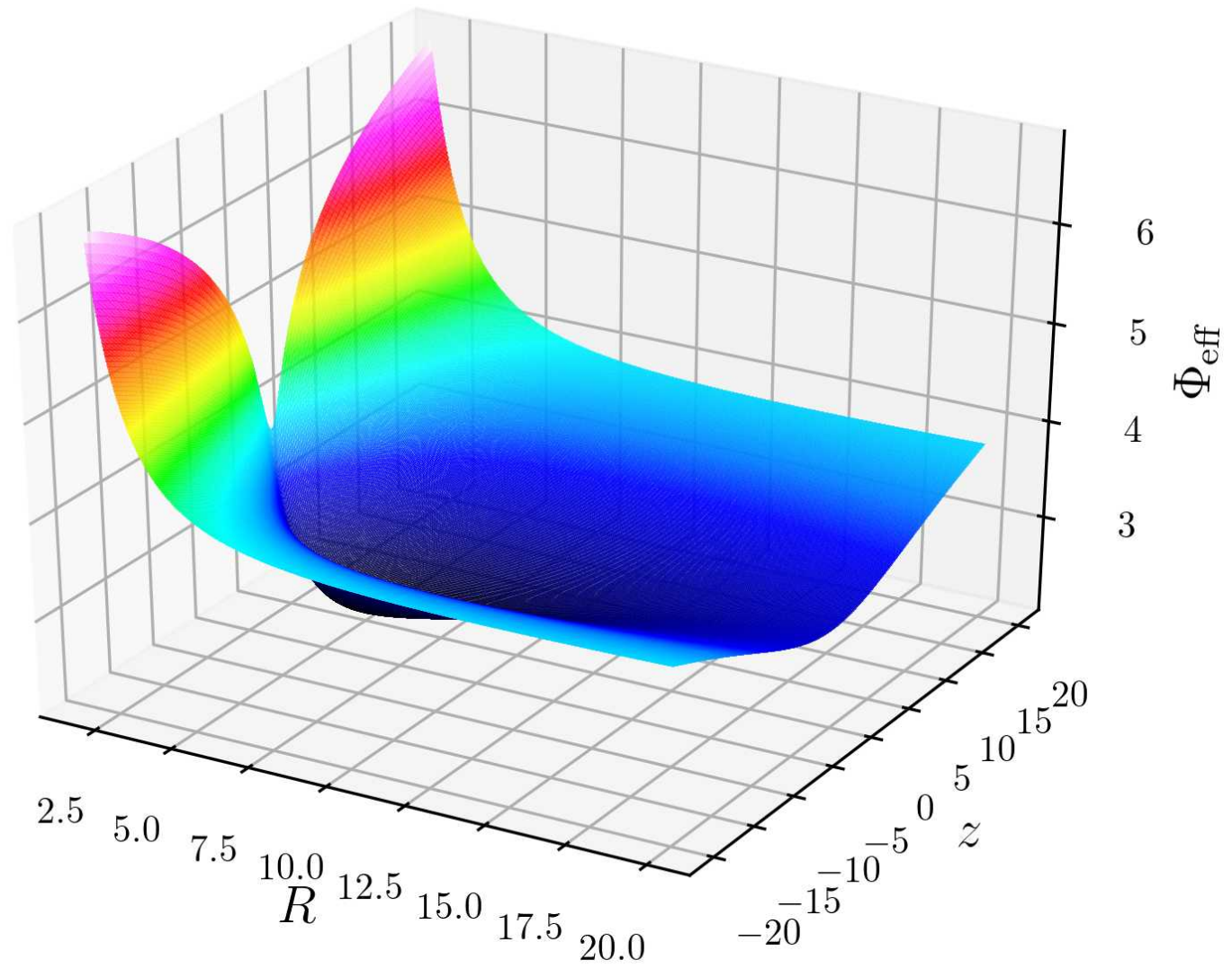
$$\phi(R, z) = \frac{1}{2} V_0^2 \ln \left( R^2 + \frac{z^2}{q^2} \right)$$

$$\phi_{\text{eff}}(R, z=0) = \frac{1}{2} V_0^2 \ln(R^2) + \frac{L_z^2}{2R^2}$$

Logarithmic Potential



# Logarithmic Potential



## General solutions for the equations of motion

$$\begin{cases} \ddot{R} = - \frac{\partial \phi_{\text{eff}}}{\partial R}(R, z) \\ \ddot{z} = - \frac{\partial \phi_{\text{eff}}}{\partial z}(R, z) \end{cases}$$

no simple solutions ☹️

need numerical integration

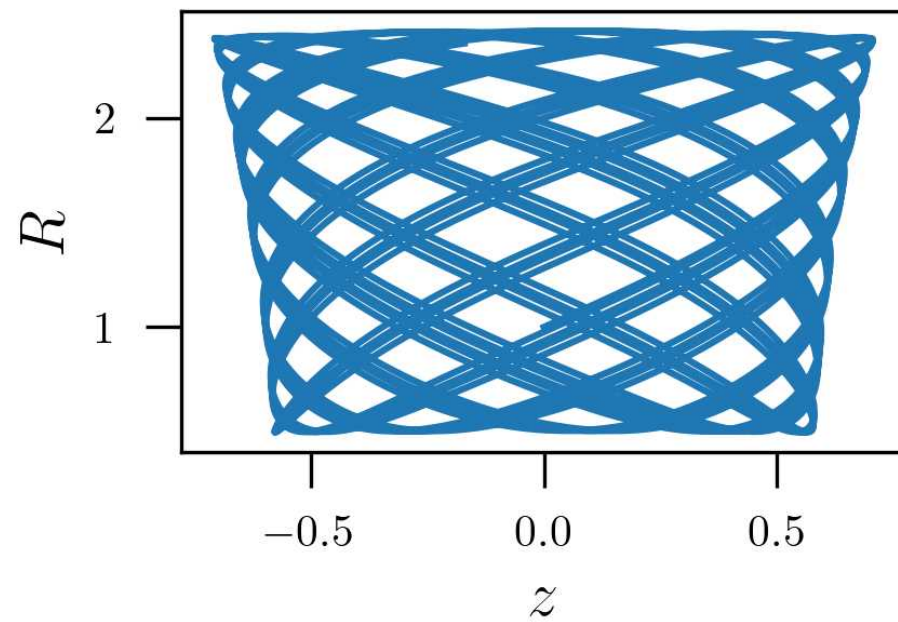
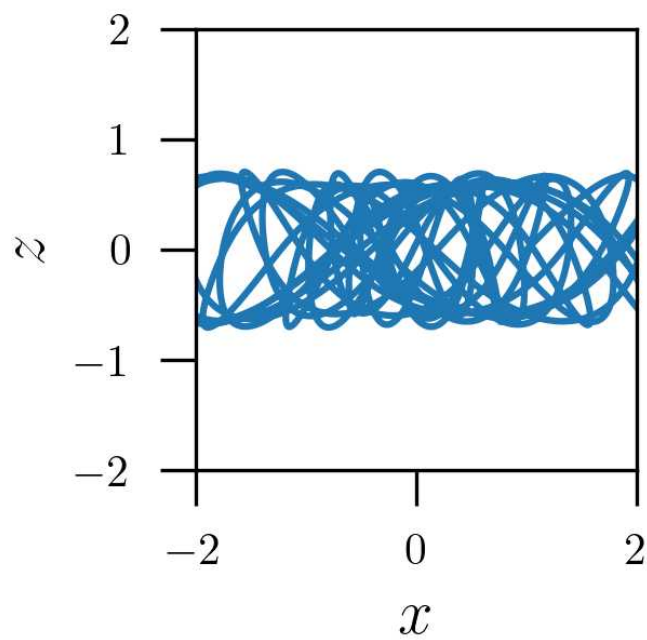
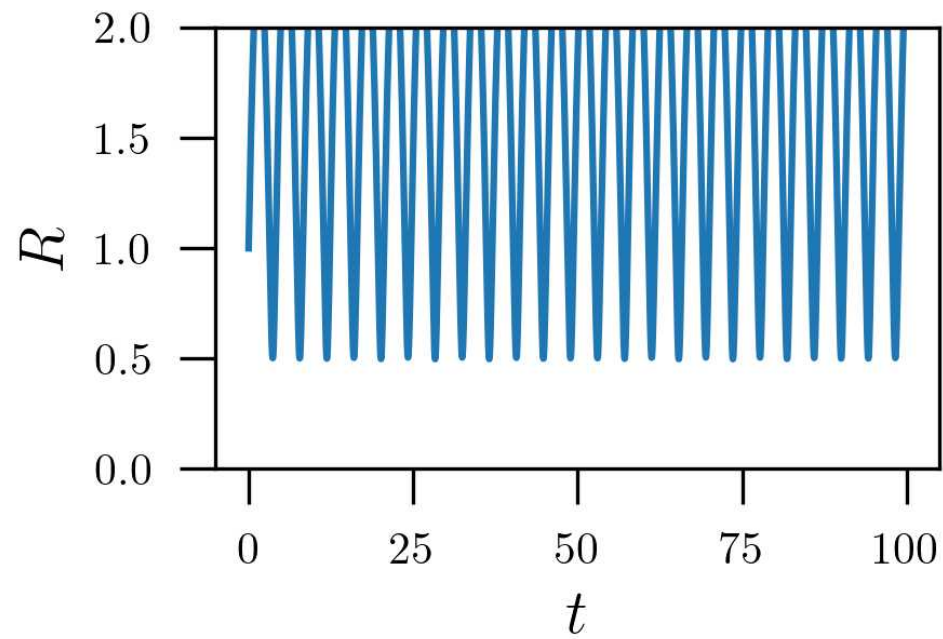
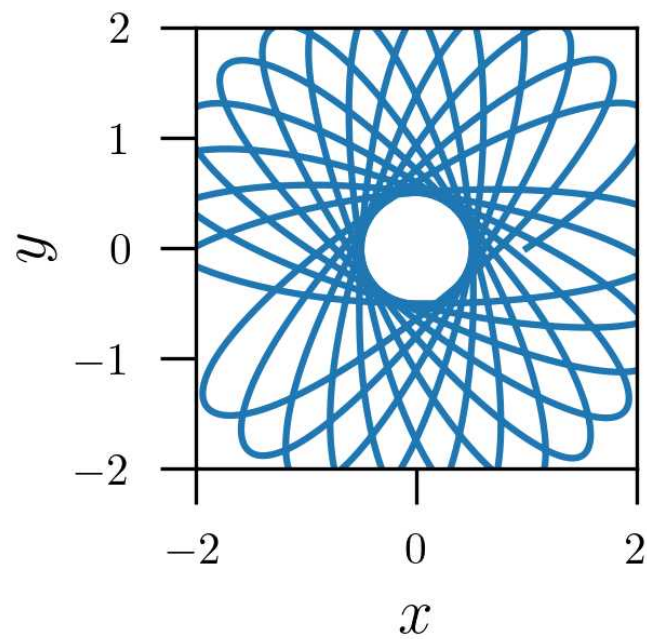
Hamilton's Equations

$$\vec{q} = \begin{Bmatrix} R \\ z \end{Bmatrix} \quad \dot{\vec{q}} = \begin{Bmatrix} \dot{R} \\ \dot{z} \end{Bmatrix} \quad \vec{p} = \begin{Bmatrix} p_R \\ p_z \end{Bmatrix}$$

$$\begin{cases} \dot{q}_R = p_R & \equiv \dot{R} \\ \dot{q}_z = p_z & \equiv \dot{z} \\ \dot{p}_R = - \frac{\partial \phi_{\text{eff}}}{\partial q_R}(q_R, q_z) & \equiv - \frac{\partial \phi_{\text{eff}}}{\partial R}(R, z) \\ \dot{p}_z = - \frac{\partial \phi_{\text{eff}}}{\partial q_z}(q_R, q_z) & \equiv - \frac{\partial \phi_{\text{eff}}}{\partial z}(R, z) \end{cases}$$

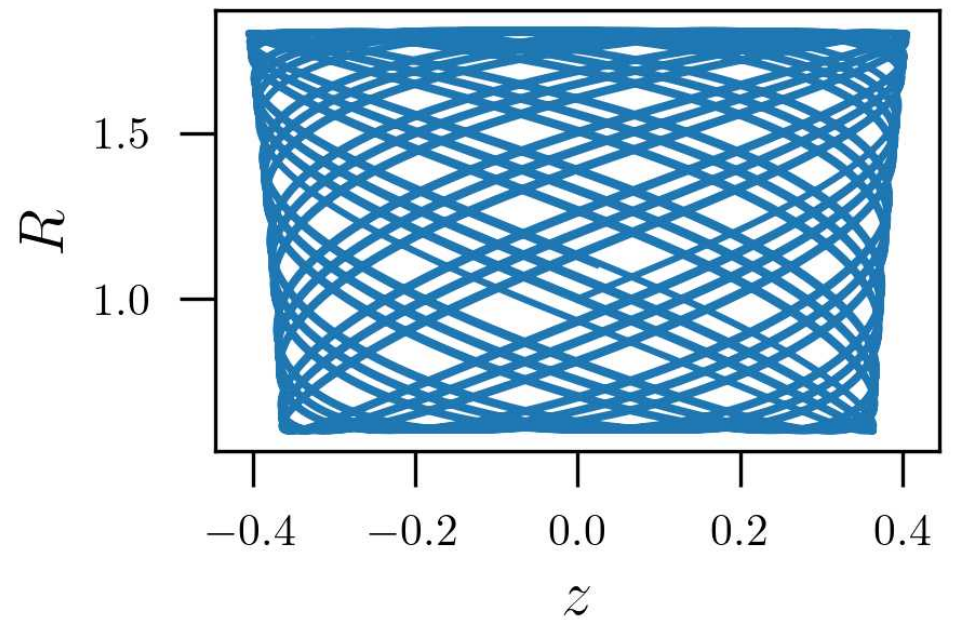
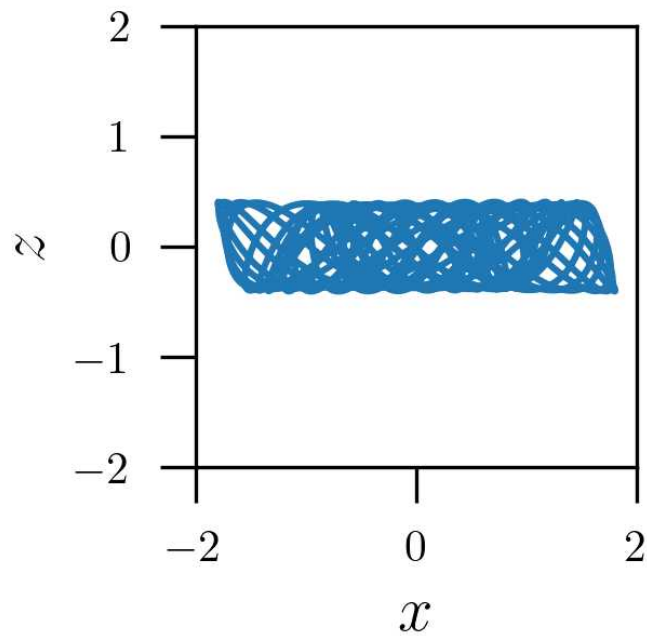
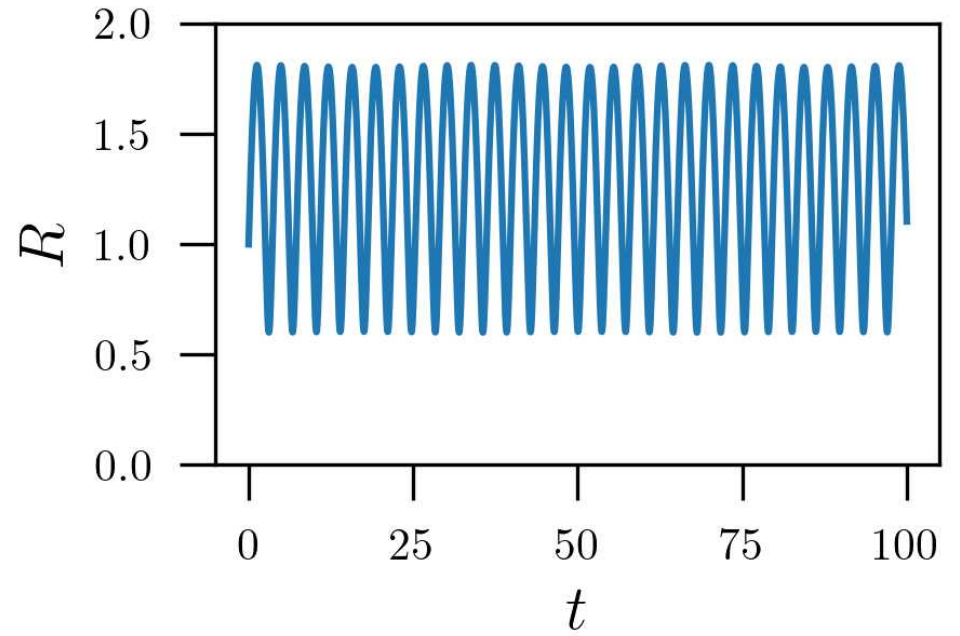
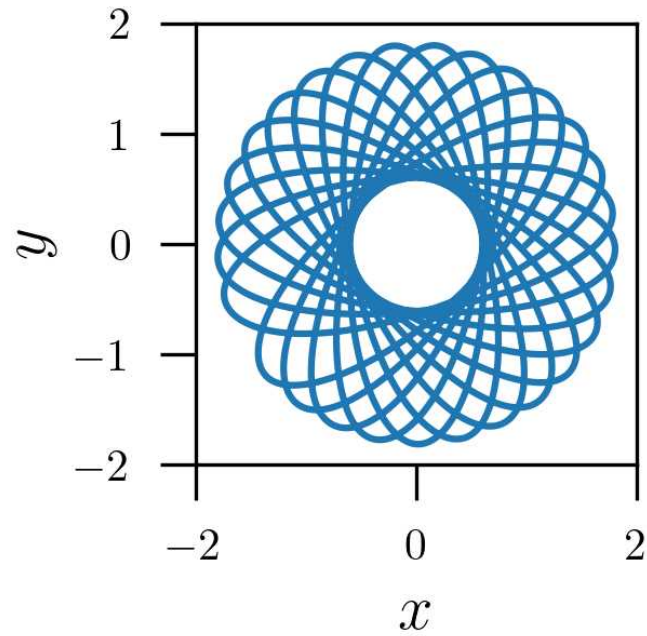


# Miyamoto – Nagai : $\Delta E = 0.2$

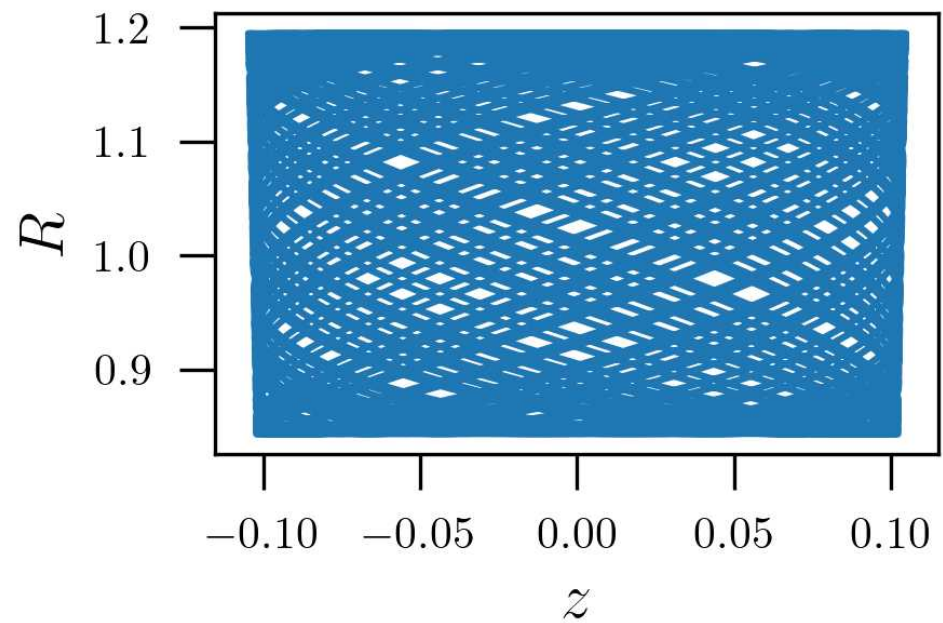
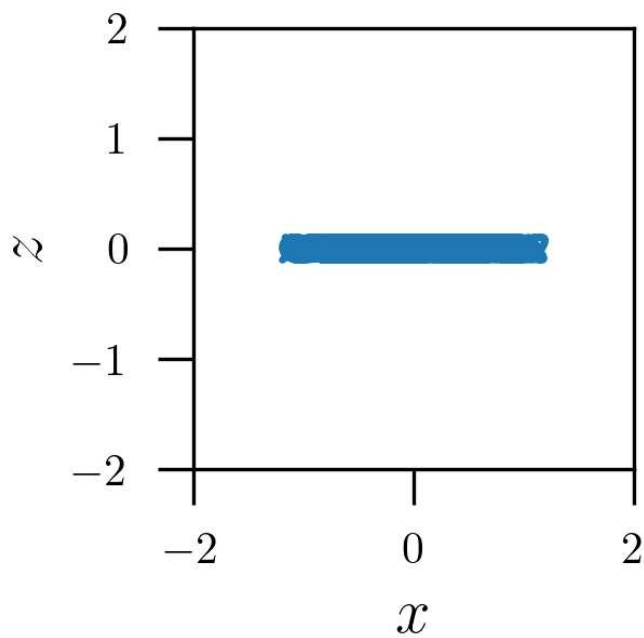
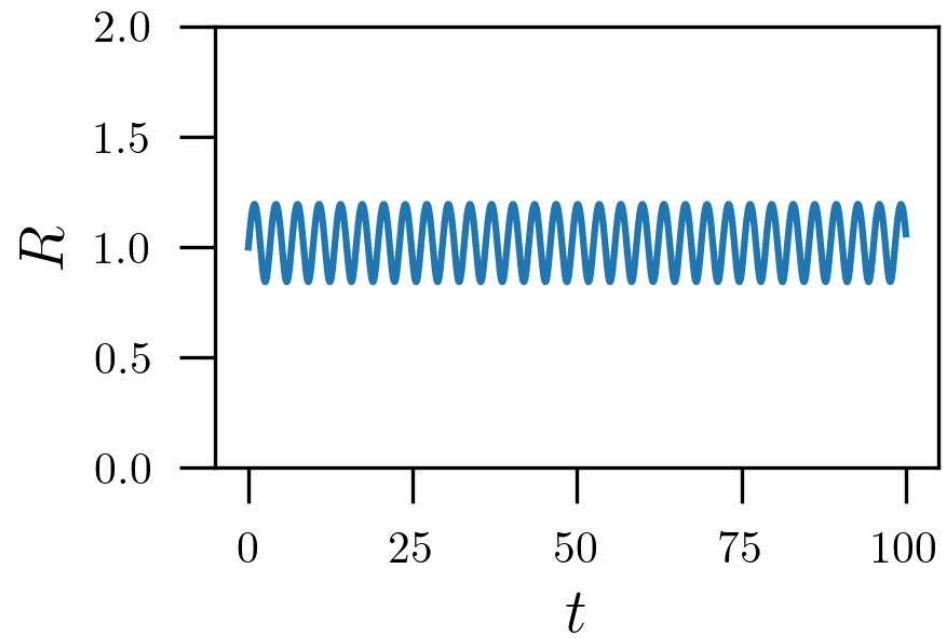
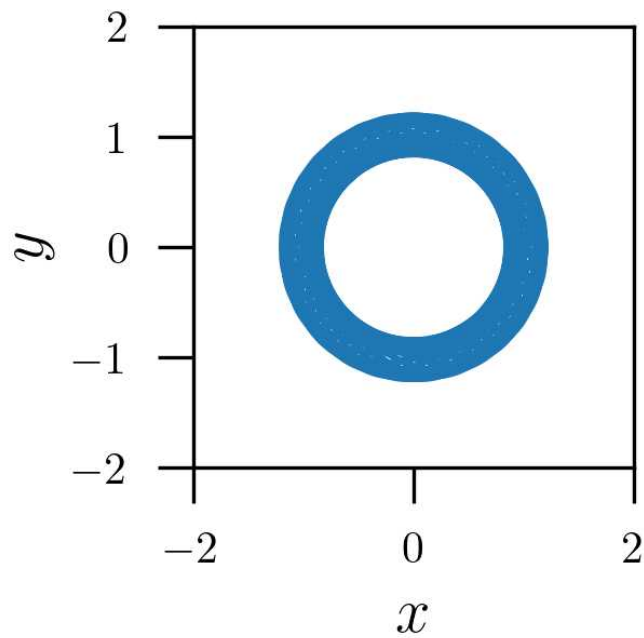




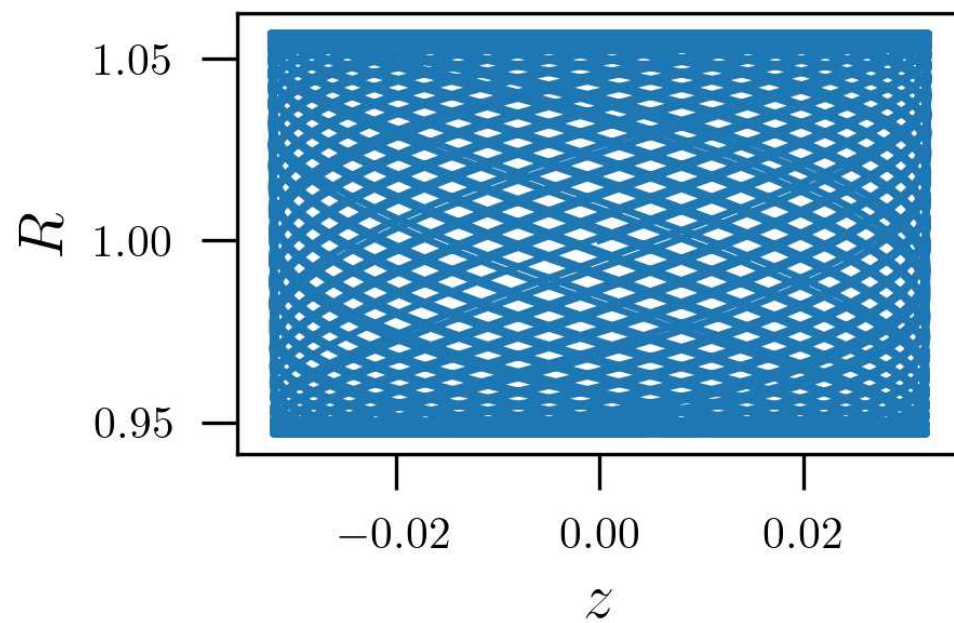
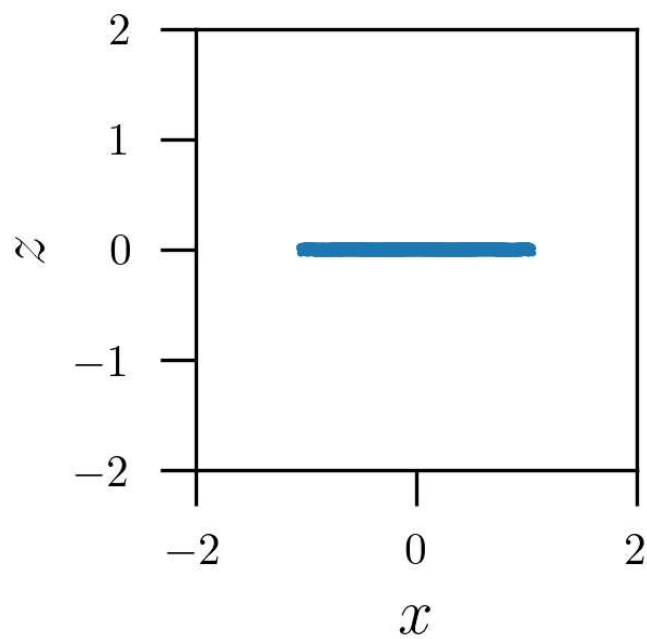
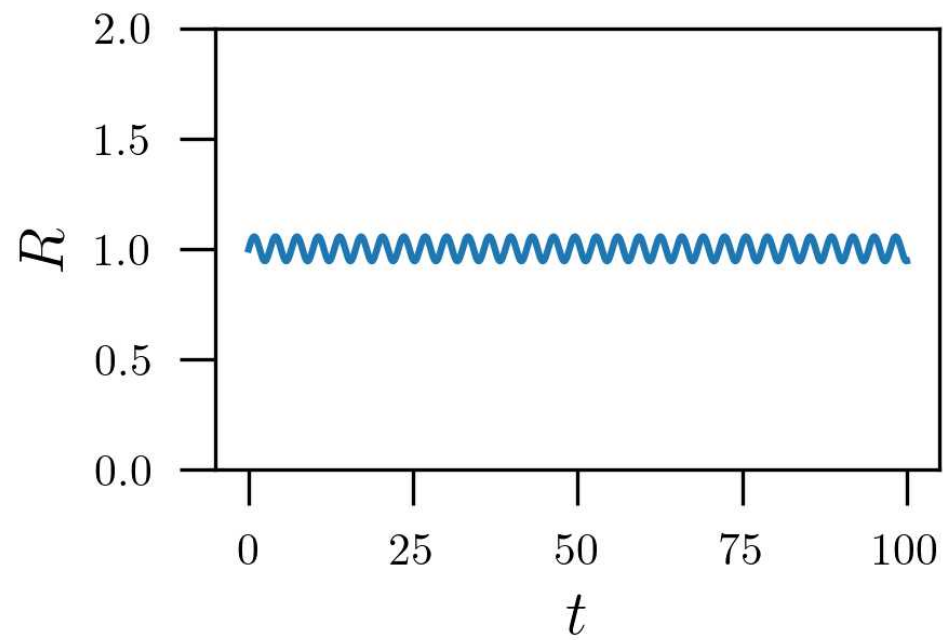
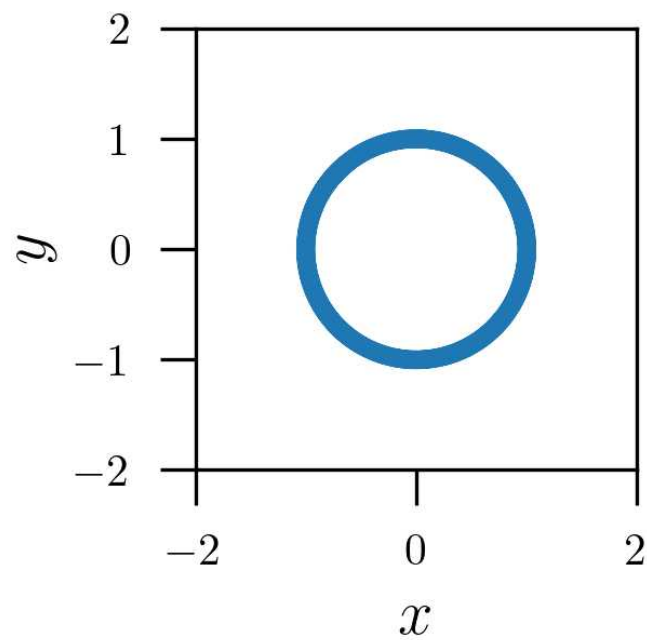
# Miyamoto — Nagai : $\Delta E = 0.1$



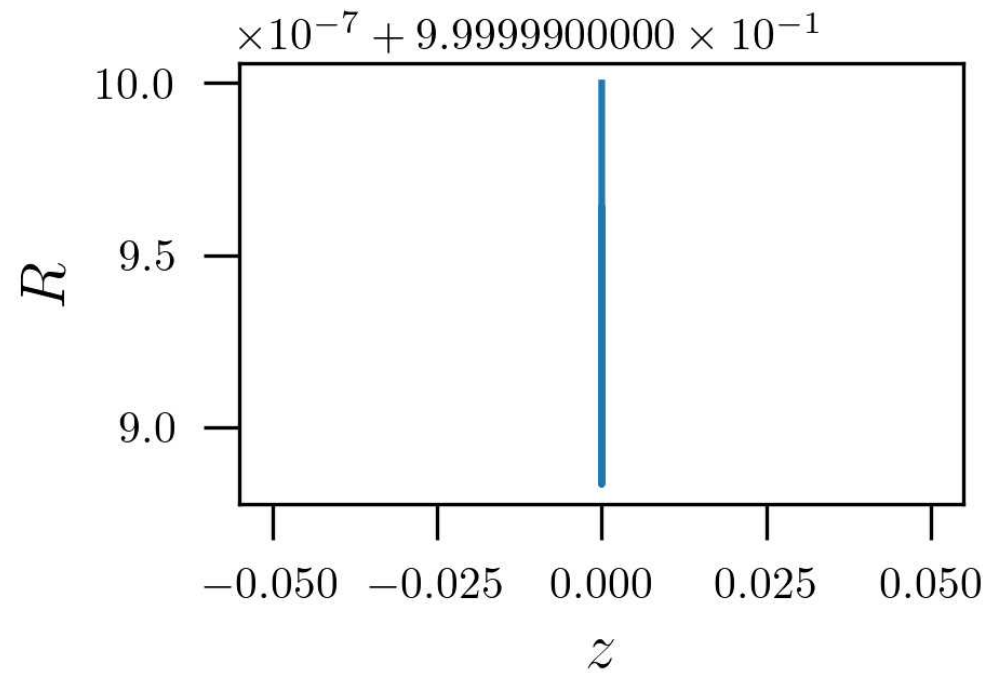
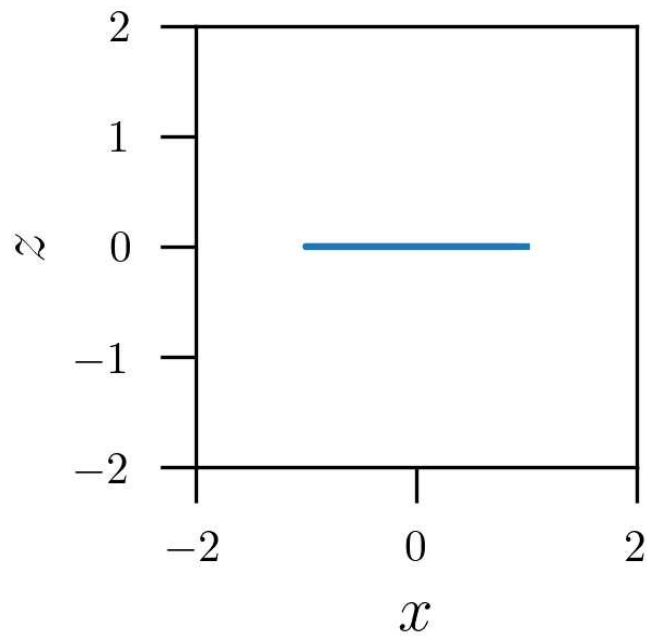
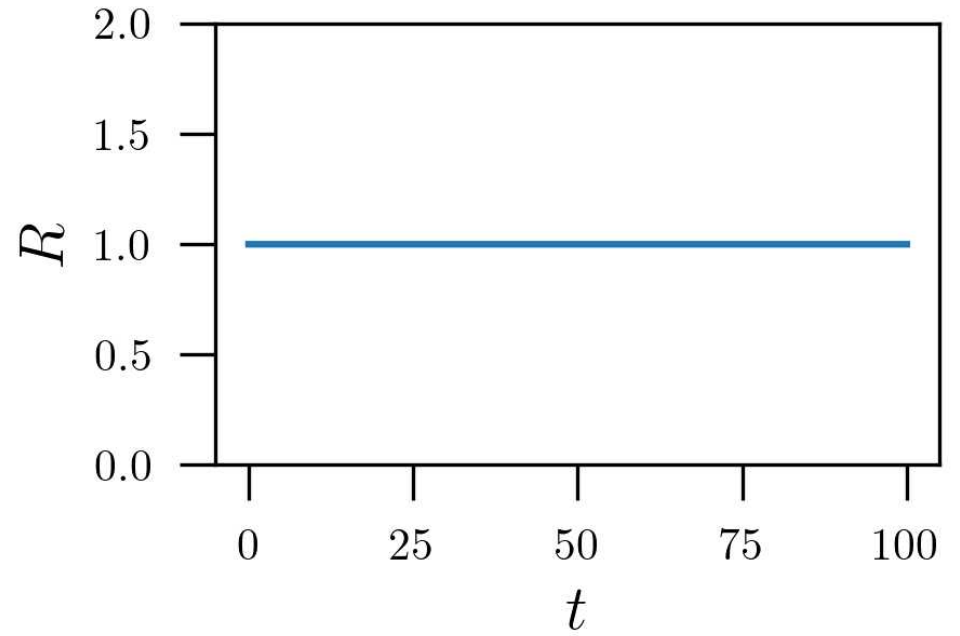
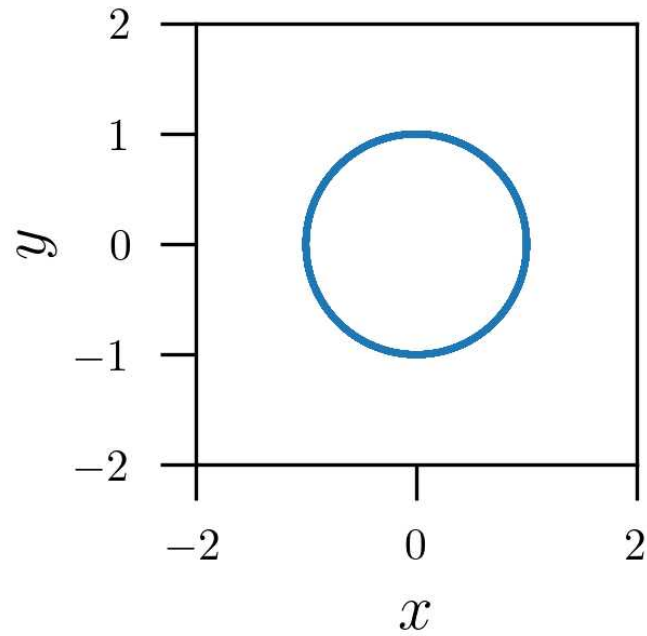
# Miyamoto – Nagai : $\Delta E = 0.01$



Miyamoto — Nagai :  $\Delta E = 0.001$



# Miyamoto – Nagai : $\Delta E = 0$

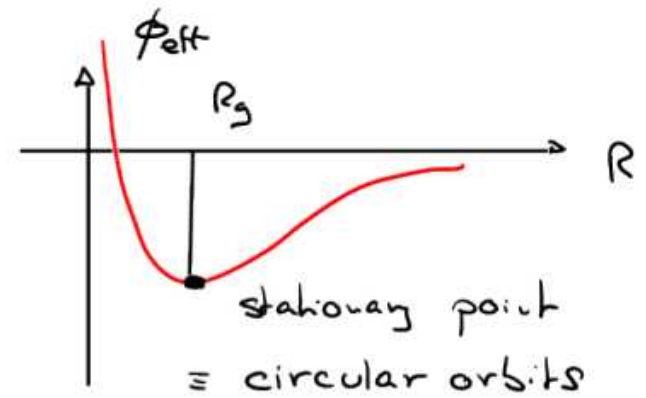


# **Stellar orbits**

## **Nearly circular orbits**

## Nearly circular orbits

From the previous study of orbits in axisymmetric potentials



Goal Study orbits in the neighbourhood of circular orbits

Justifications In a disk galaxy, many stars are found in nearly circular orbits

Recall  $R_g$  : the guiding center

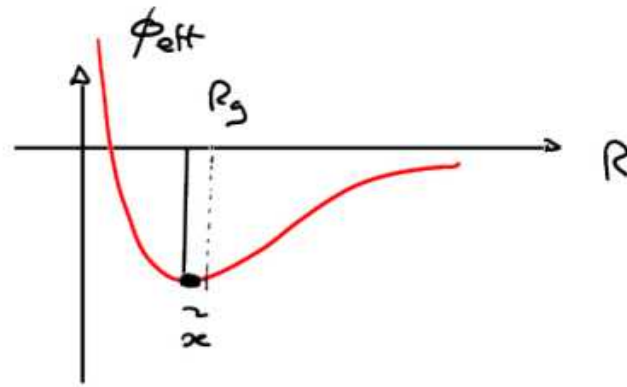
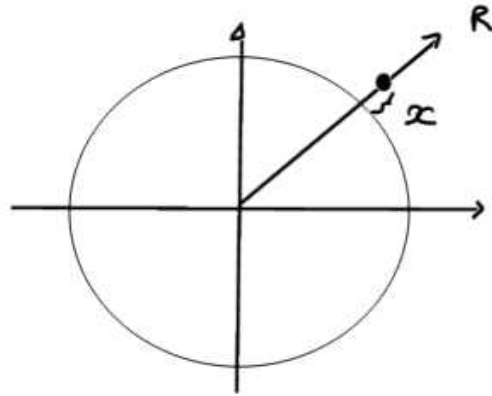
$$R_g \text{ such that } \left. \frac{\partial \phi}{\partial R} \right|_{R_g,0} = \frac{L_z^2}{R_g^3} = R_g \Theta^2$$



We define

$$x := R - R_g$$

the distance to the guiding center  $R_g$



Taylor expansion of  $\phi_{\text{eff}}$  around  $R = R_g$ ,  $z = 0$

$$\begin{aligned}
 \phi_{\text{eff}}(R, z) &\approx \phi_{\text{eff}}(R_g, 0) + \underbrace{\frac{\partial \phi_{\text{eff}}}{\partial R}(R_g, 0)}_{=0 \text{ min}} (R - R_g) + \underbrace{\frac{\partial \phi_{\text{eff}}}{\partial z}(R_g, 0)}_{=0 \text{ sym.}} z \\
 &+ \frac{1}{2} \frac{\partial^2 \phi_{\text{eff}}}{\partial R^2}(R_g, 0) (R - R_g)^2 + \frac{1}{2} \frac{\partial^2 \phi_{\text{eff}}}{\partial z^2}(R_g, 0) z^2 \\
 &+ \frac{1}{2} \underbrace{\frac{\partial^2 \phi_{\text{eff}}}{\partial z \partial R}(R_g, 0)}_{=0} (R - R_g) z + \mathcal{O}(((R - R_g)z)^3)
 \end{aligned}$$

$= 0$   $\phi_{\text{eff}}(R, z)$  must be sym. with respect to  $z = 0$

$$\phi_{\text{eff}}(R, z) \cong \phi_{\text{eff}}(R_g, 0) + \frac{1}{2} \frac{\partial^2 \phi_{\text{eff}}}{\partial R^2}(R_g, 0) x^2 + \frac{1}{2} \frac{\partial^2 \phi_{\text{eff}}}{\partial z^2}(R_g, 0) z^2$$

Definition

$$\begin{cases} \omega^2(R_g) = \left( \frac{\partial^2 \phi_{\text{eff}}}{\partial R^2} \right)_{(R_g, 0)} \\ \nu^2(R_g) = \left( \frac{\partial^2 \phi_{\text{eff}}}{\partial z^2} \right)_{(R_g, 0)} \end{cases}$$

$$[\phi] = \left( \frac{m}{s} \right)^2$$

$$\left[ \left( \frac{\partial^2 \phi}{\partial R^2} \right)^{\frac{1}{2}} \right] = \left[ \left( \frac{\partial^2 \phi}{\partial z^2} \right)^{\frac{1}{2}} \right] = \frac{1}{s}$$

frequency

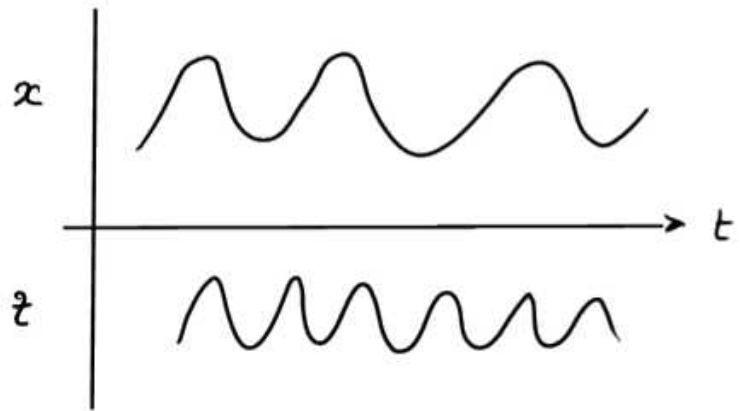
Equations of motion near  $R_g$

$$\begin{cases} \ddot{R} = - \frac{\partial \phi_{\text{eff}}}{\partial R}(R, z) \\ \ddot{z} = - \frac{\partial \phi_{\text{eff}}}{\partial z}(R, z) \end{cases} \Rightarrow$$

$$\begin{cases} \ddot{x} = - \omega^2(R_g) x \\ \ddot{z} = - \nu^2(R_g) z \end{cases}$$



$$\begin{cases} \ddot{x} = -\kappa^2(R_g) x \\ \ddot{z} = -\nu^2(R_g) z \end{cases}$$



Two decoupled harmonic oscillators  
with frequencies  $\kappa$  and  $\nu$

$\kappa$  : epicycle (radial) frequency

$\nu$  : vertical frequency

# Expressions of $\mathcal{R}$ and $\nu$ from the total potential

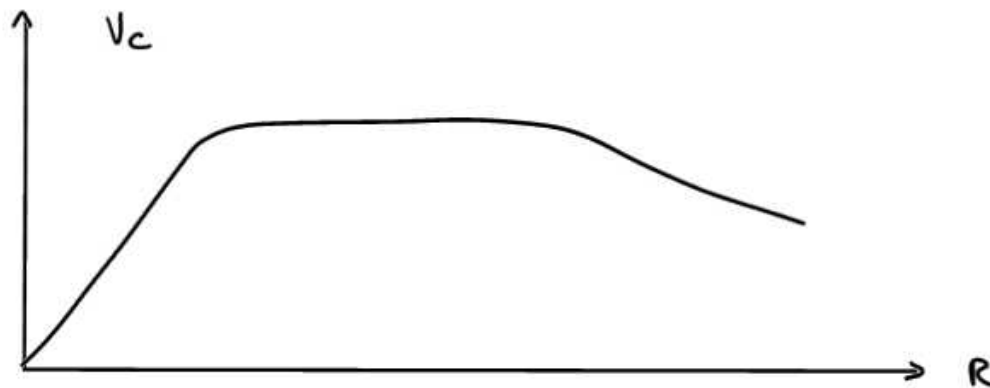
$$\begin{aligned}
 \mathcal{R}^2(R_g) &= \frac{\partial^2 \phi_{\text{eff}}}{\partial R^2} \bigg|_{(R_g, 0)} = \frac{\partial^2 \phi}{\partial R^2} \bigg|_{(R_g, 0)} + 3 \frac{L_z^2}{R_g^4} \\
 &= \frac{\partial^2 \phi}{\partial R^2} \bigg|_{(R_g, 0)} + \frac{3}{R_g} \frac{\partial \phi}{\partial R} \bigg|_{(R_g, 0)} \\
 &= \frac{\partial^2 \phi}{\partial R^2} \bigg|_{(R_g, 0)} + 3 \mathcal{R}^2 \\
 &= \left( R \frac{\partial (\mathcal{R}^2)}{\partial R} + 4 \mathcal{R}^2 \right) \bigg|_{(R_g, 0)} \\
 &= \left( \frac{1}{R} \frac{\partial (V_c^2)}{\partial R} + 2 \mathcal{R}^2 \right) \bigg|_{(R_g, 0)} = \left( \frac{1}{R} \frac{\partial (V_c^2)}{\partial R} + 2 \frac{V_c^2}{R^2} \right) \bigg|_{(R_g, 0)}
 \end{aligned}$$

$\text{circ. frequency } \mathcal{R}^2 = \frac{1}{R_g} \frac{\partial \phi}{\partial R} \bigg|_{R_g}$   
 $\mathcal{R}^2 = \frac{V_c^2}{R^2}$

$L_z^2 = V_c^2 R_g^2 = R_g^3 \frac{\partial \phi}{\partial R} \bigg|_{R_g}$

$$\nu^2(R_g) = \frac{\partial^2 \phi_{\text{eff}}}{\partial z^2} \bigg|_{(R_g, 0)} = \frac{\partial^2 \phi}{\partial z^2} \bigg|_{(R_g, 0)}$$

Note :  $\alpha$  depends only on  $V_c$



$\alpha$  obtained by  
derivating  $V_c^2$

Periods :

{ radial  
vertical  
azimuthal

$$T_R := \frac{2\pi}{\alpha}$$

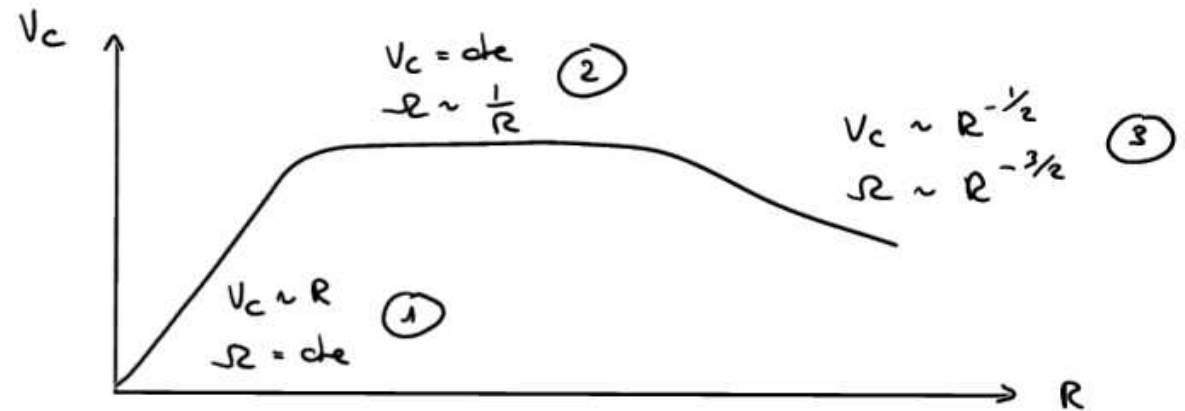
$$T_z := \frac{2\pi}{\gamma}$$

$$T_\theta := \frac{2\pi}{\Omega}$$

## Radial dependencg of $\kappa$ , $\nu$ for a typical galaxy

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$$\Omega = \frac{V_c}{R}$$



- ① near the center

$$V_c \sim R \quad (\text{rigid rotation})$$

$$\Rightarrow \Omega = \text{cte}$$

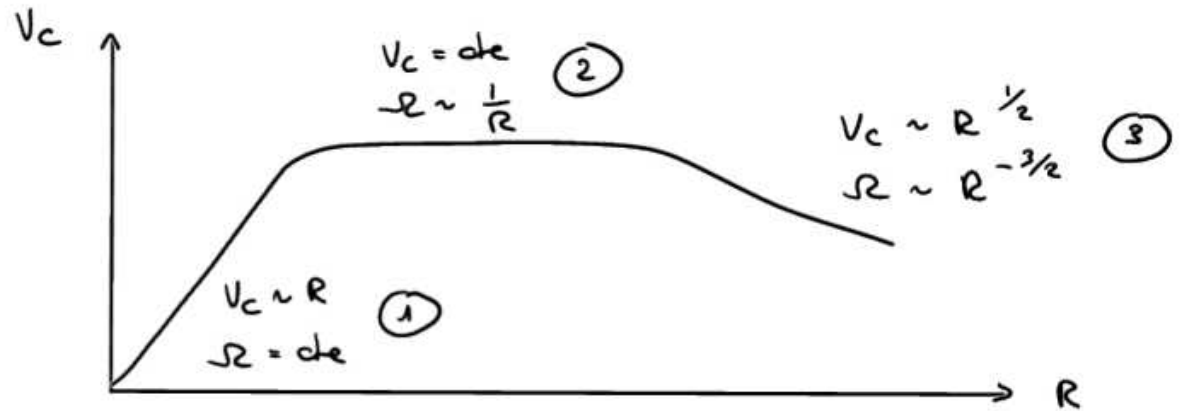
$$\kappa^2 = R \frac{d}{dR}(\Omega^2) + 4\Omega^2$$

$$\Rightarrow \kappa^2 = 4\Omega^2$$

$$\kappa \sim 2\Omega$$

## Radial dependencg of $\kappa$ , $\nu$ for a typical galaxy

$$\Omega = \frac{V_c}{R}$$



### • ② flat rotation part

$$V_c = \text{cte}$$

$$\Omega \sim \frac{1}{R}$$

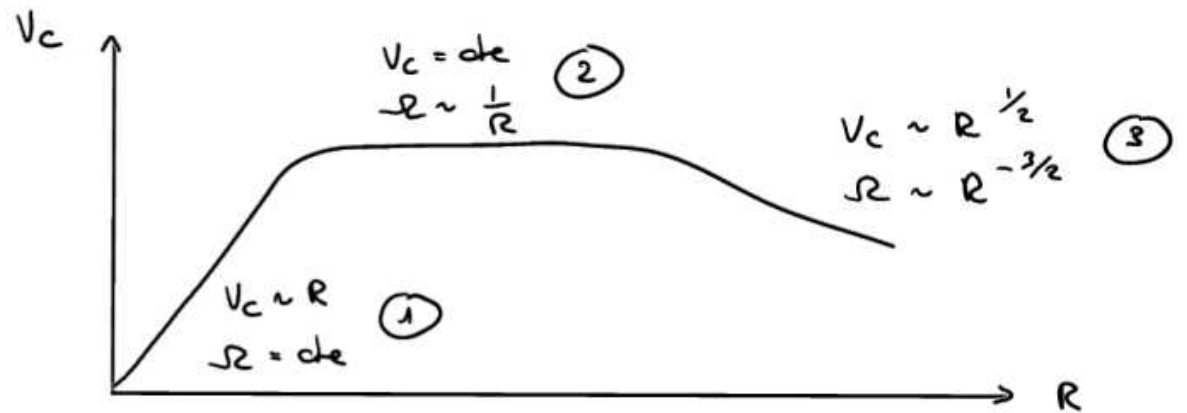
$$\kappa^2 = \frac{1}{R} \frac{\partial}{\partial R} (V_c^2) + 2\Omega^2$$

$$\Rightarrow \kappa^2 = 2\Omega^2$$

$$\kappa \sim \sqrt{2} \Omega$$

# Radial dependencg of $\kappa$ , $\nu$ for a typical galaxy

$$\Omega = \frac{V_c}{R}$$



• ③ further out

$$V_c \sim R^{-1/2} \text{ (Keplerian decrease)}$$

$$\Omega = \frac{V_c}{R} \sim R^{-3/2} \quad \Omega^2 \sim R^{-3}$$

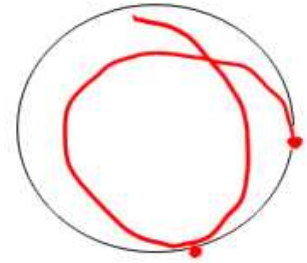
$$\frac{d}{dR}(\Omega^2) = -3 \frac{\Omega^2}{R}$$

$$\kappa^2 = R \underbrace{\frac{d}{dR}(\Omega^2)}_{-3\Omega^2} + 4\Omega^2$$

$$\kappa = \Omega$$

Thus, in general

$$\Omega \leq \mathcal{R} \leq 2\Omega$$





## Integrals of motions

$$\begin{cases} \ddot{x} = -\kappa^2(R_g) x \\ \ddot{z} = -\nu^2(R_g) z \end{cases}$$

$\Rightarrow$  Two integrals of motion  
(one for each oscillator)

$$1) \quad H_R = \frac{1}{2} \dot{x}^2 + \frac{1}{2} \kappa^2 x^2$$

$$2) \quad H_z = \frac{1}{2} \dot{z}^2 + \frac{1}{2} \nu^2 z^2$$

Thus, if a star oscillates near a circular orbit :

3 integrals of motions

$L_z, H_R, H_z$

Total Hamiltonian (near a circular orbit of radius  $R_s$ )

$$H(R, \dot{R}, \theta, \dot{\theta}, z, \dot{z}) = \frac{1}{2} (\dot{R}^2 + R^2 \dot{\theta}^2 + \dot{z}^2) + \phi(R, z)$$

$$= \frac{1}{2} \dot{R}^2 + \frac{1}{2} \dot{z}^2 + \underbrace{\phi(R, z)}_{\phi_{\text{eff}}(R, z)} + \frac{L_z^2}{2 R^2}$$

$$L_z = R^2 \dot{\theta}$$

$$= \frac{1}{2} \dot{R}^2 + \frac{1}{2} \dot{z}^2 + \phi_{\text{eff}}(R_s, 0) + \frac{1}{2} \chi^2 (R - R_s)^2 + \frac{1}{2} \nu^2 z^2$$

$$H(R, p_R, z, p_z) = H_R(R, p_R) + H_z(z, p_z) + \phi_{\text{eff}}(R_s, 0)$$

## Orbital motions

$$\begin{cases} \ddot{x} = -\kappa^2(R_g) x \\ \ddot{z} = -\nu^2(R_g) z \end{cases}$$

$$+ R^2 \dot{\theta} = L_z$$

## Solutions

① motion in  $z$

$$z(t) = Z \cos(\nu t + \xi)$$

② motion in  $x$

$$x(t) = X \cos(\kappa t + \alpha)$$

Note valid only for small oscillations

as long as  $\nu^2 = \frac{\partial^2 \phi}{\partial z^2} \approx \text{cte}$

ie  $\rho_{\text{disk}} \approx \text{cte}$  ( $\nu^2 = \frac{\partial^2 \phi}{\partial z^2} = 4\pi G \rho$ )

$\Rightarrow z < \text{disk scale length}$

$\sim 300 \text{ pc}$

③ motion in  $\Theta$

$$L_z = R^2 \dot{\Theta}$$

$$\Theta(t) = L_z \int_{t_0}^t dt' \frac{1}{R^2(t')} = L_z \int_{t_0}^t dt' \frac{1}{(R_g + x(t'))^2}$$

$$\approx \frac{L_z}{R_g^2} \int_{t_0}^t dt' \frac{1}{\left(\frac{x}{R_g} + 1\right)^2} \stackrel{\text{Taylor}}{\approx} R_g \int_{t_0}^t dt' \left(1 - \frac{2x(t')}{R_g}\right)$$

$R_g = \frac{L_z}{R_g^2}$

introducing  $x(t) = X \cos(\omega t + \alpha)$

$$\Theta(t) = R_g \cdot t - \frac{2 R_g X}{\omega R_g} \sin(\omega t + \alpha) + \Theta_0$$

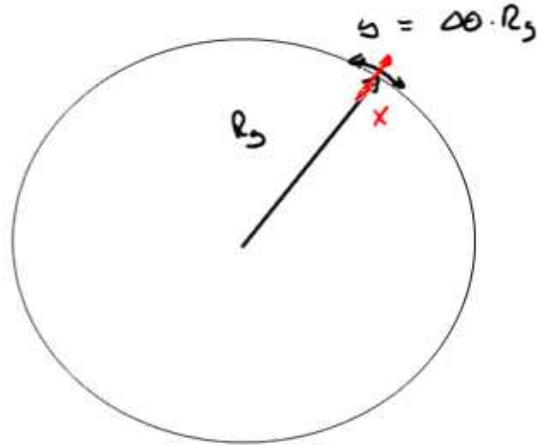
motion of the  
guiding center  
along the circular  
orbit

oscillations

New cartesian system

$x, y, z$

with an origin that follows the guiding center



$$\begin{cases} R(t) = R_g \\ \Theta(t) = R_g t + \Theta_0 \end{cases}$$

Then, from

$$\Theta(t) = R_g \cdot t - \underbrace{\frac{2R_g}{\omega} \frac{x}{R_g} \sin(\omega t + \alpha)}_{\Delta\Theta} + \Theta_0$$

$$\Delta\Theta = \frac{y}{R_g}$$

$$y = - \frac{2R_g}{\omega} x \sin(\omega t + \alpha)$$

$$y(t) = - y \sin(\omega t + \alpha)$$

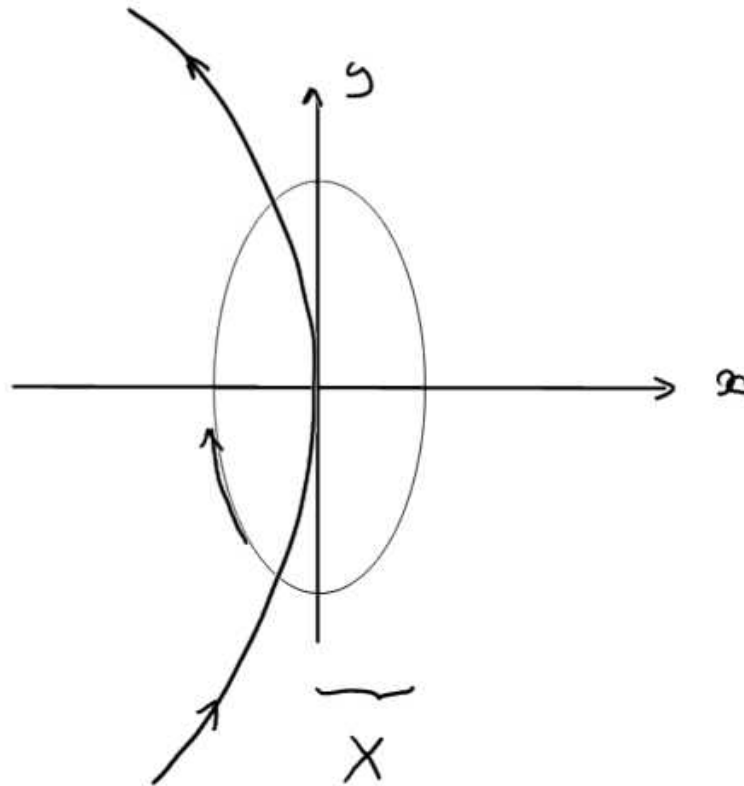
$$y := \frac{2R_g}{\omega} x$$

## Complete solution

$$\begin{cases} x(t) = X \cos(\omega t + \alpha) \\ y(t) = -Y \sin(\omega t + \alpha) \\ z(t) = Z \cos(\nu t + \xi) \end{cases}$$

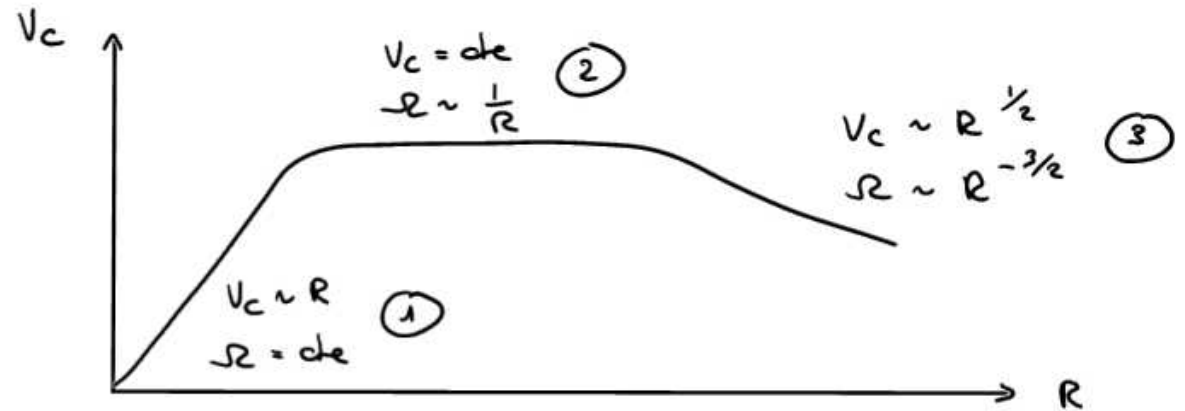
} ellipse

$$Y = \frac{2 R_g}{\omega} X$$



} y

# Radial dependence for a typical galaxy



① near the center

$$x = 2\Omega$$

$$\frac{x}{y} = 1$$

circle



② flat rotation part

$$x = \sqrt{2}\Omega$$

$$\frac{x}{y} = \frac{\sqrt{2}\Omega}{2\Omega}$$

$x < y$



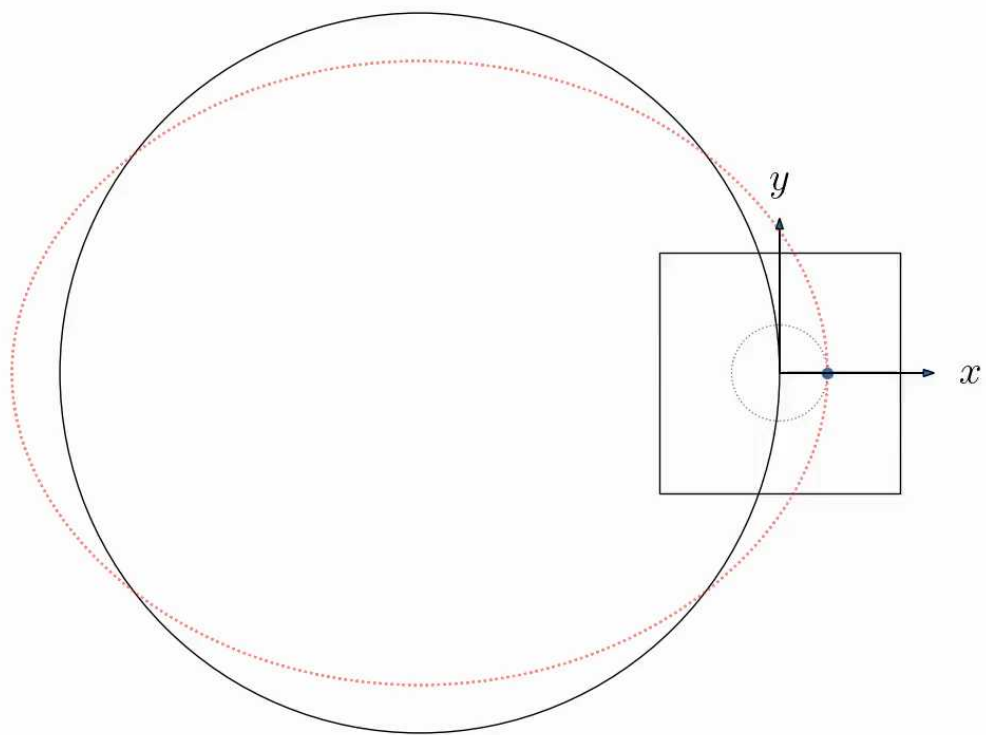
③ further out

$$x = \Omega$$

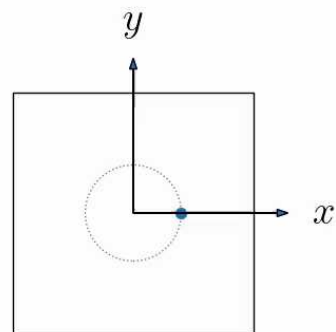
$$\frac{x}{y} = \frac{\Omega}{2\Omega}$$

$x < y$

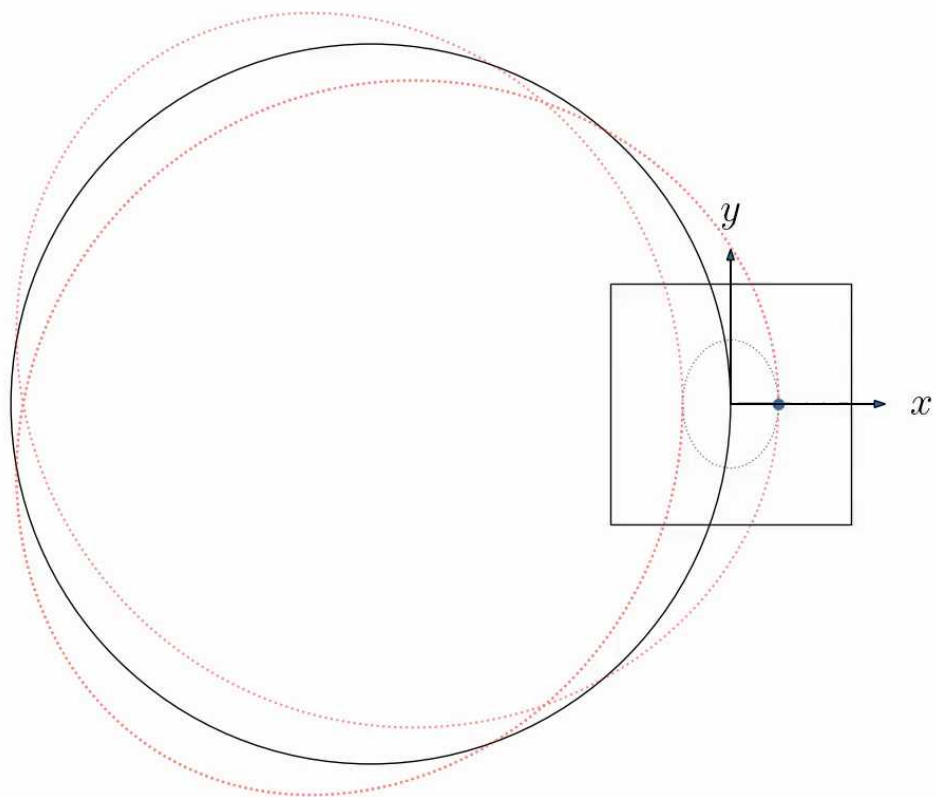




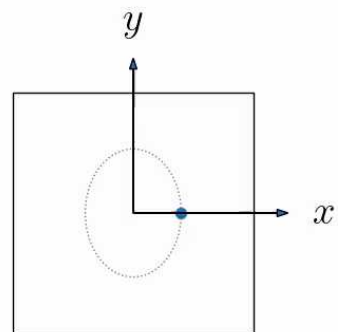
$$\kappa/\Omega = 2.0$$

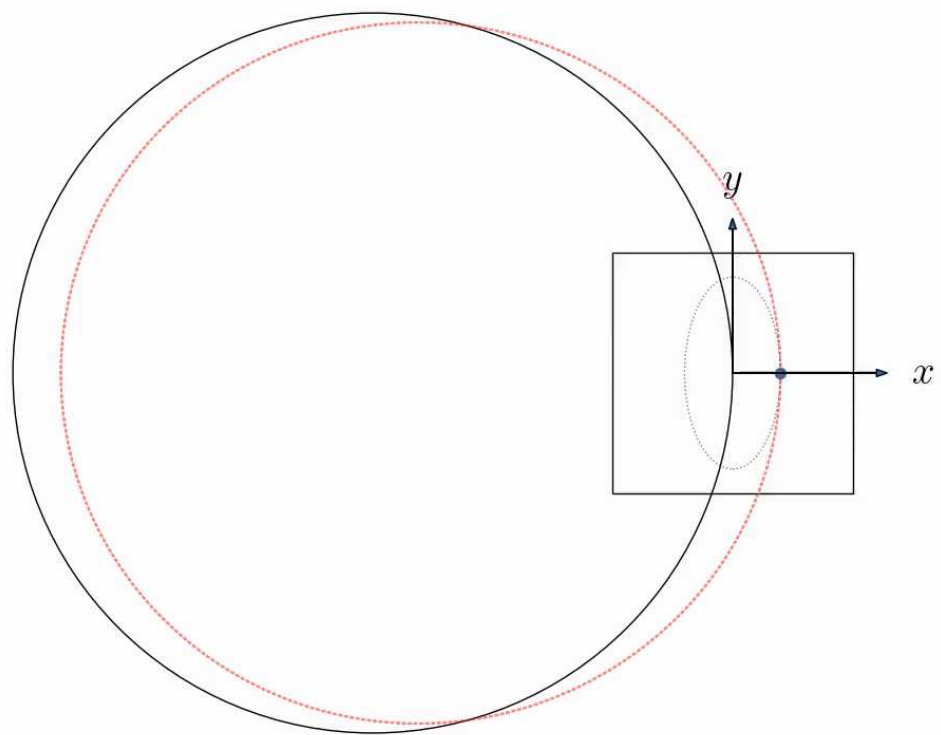




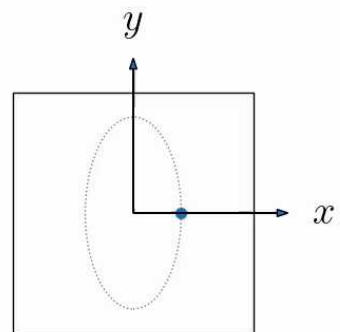


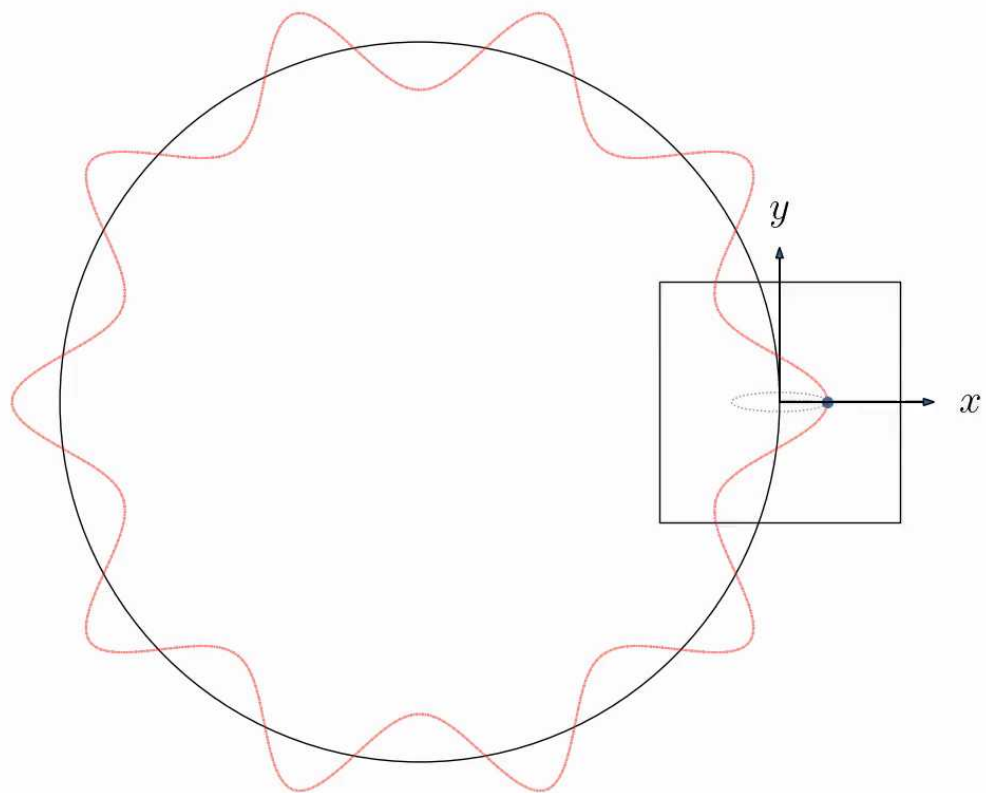
$$\kappa/\Omega = 1.5$$



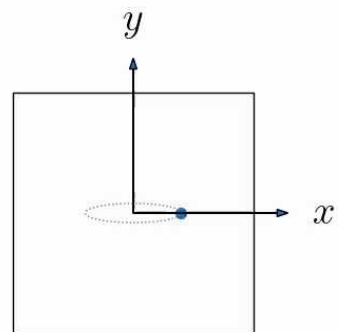


$$\kappa/\Omega = 1.0$$





$$\kappa/\Omega = 10.0$$



**The End**