

# Differential Geometry II - Smooth Manifolds Winter Term 2024/2025 Lecturer: Dr. N. Tsakanikas Assistant: L. E. Rösler

## Exercise Sheet 12 – Solutions

**Exercise 1:** Let V be a smooth vector field on a smooth manifold M, let  $J \subseteq \mathbb{R}$  be an interval, and let  $\gamma: J \to M$  be an integral curve of V. Prove the following assertions:

(a) Rescaling lemma: For any  $a \in \mathbb{R}$ , the curve

$$
\widetilde{\gamma} \colon \widetilde{J} \to M, \ t \mapsto \gamma(at)
$$

is an integral curve of the vector field  $\widetilde{V} := aV$  on M, where  $\widetilde{J} := \{t \in \mathbb{R} \mid at \in J\}.$ 

(b) Translation lemma: For any  $b \in \mathbb{R}$ , the curve

$$
\widehat{\gamma} \colon \widehat{J} \to M, \ t \mapsto \gamma(t+b)
$$

is also an integral curve of V on M, where  $\hat{J} := \{t \in \mathbb{R} \mid t + b \in J\}.$ 

## Solution:

(a) If  $t \in \tilde{J}$ , then

$$
\widetilde{\gamma}'(t) = a\gamma'(at) = aV_{\gamma(at)} = \widetilde{V}_{\widetilde{\gamma}(t)}.
$$

(b) If  $t \in \widehat{J}$ , then

$$
\widehat{\gamma}'(t) = \gamma'(t+b) = V_{\gamma(t+b)} = V_{\widehat{\gamma}(t)}.
$$

**Exercise 2** (The Euler vector field): Consider the Euler vector field on  $\mathbb{R}^n$ , i.e., the vector field V on  $\mathbb{R}^n$  whose value at a point  $x = (x^1, \ldots, x^n) \in \mathbb{R}^n$  is

$$
V_x = x^1 \frac{\partial}{\partial x_1}\bigg|_x + \ldots + x^n \frac{\partial}{\partial x_n}\bigg|_x.
$$

- (a) Check that V is a smooth vector field on  $\mathbb{R}^n$ .
- (b) Let  $c \in \mathbb{R}$  and let  $f: \mathbb{R}^n \setminus \{0\} \to \mathbb{R}$  be a smooth function which is *positively homo*geneous of degree c, i.e.,  $f(\lambda x) = \lambda^c f(x)$  for all  $\lambda > 0$  and  $x \in \mathbb{R}^n \setminus \{0\}$ . Prove that  $V f = cf.$

[Hint: Differentiate the above relation with respect to both  $x^i$  and  $\lambda$ .]

(c) Compute the integral curves of  $V$ .

#### Solution:

(a) Note that the component functions of V with respect to the standard coordinate frame for  $\mathbb{R}^n$  are linear, hence smooth. Therefore, V is a smooth vector field on  $\mathbb{R}^n$  by Proposition 7.2.

(b) Using the chain rule, we obtain

$$
\lambda^c \frac{\partial f}{\partial x^i}(x) = \frac{\partial}{\partial x^i} (\lambda^c f(x)) = \frac{\partial}{\partial x^i} (f(\lambda x)) = \lambda \frac{\partial f}{\partial x^i} (\lambda x)
$$
 (1)

and

$$
c\lambda^{c-1}f(x) = \frac{d}{d\lambda}(\lambda^c f(x)) = \frac{d}{d\lambda}(f(\lambda x)) = \sum_{i=1}^n x^i \frac{\partial f}{\partial x^i}(\lambda x).
$$
 (2)

Since

$$
(Vf)(x) = V_x f = \sum_{i=1}^n x^i \frac{\partial f}{\partial x^i}(x),
$$

we have

$$
(Vf)(\lambda x) = V_{\lambda x}f = \sum_{i=1}^{n} (\lambda x^{i}) \frac{\partial f}{\partial x^{i}}(\lambda x) \stackrel{(1)}{=} \lambda^{c} \sum_{i=1}^{n} x^{i} \frac{\partial f}{\partial x^{i}}(x) = \lambda^{c}(Vf)(x)
$$
(3)

but also

$$
(Vf)(\lambda x) = V_{\lambda x}f = \sum_{i=1}^{n} (\lambda x^{i}) \frac{\partial f}{\partial x^{i}}(\lambda x) \stackrel{(2)}{=} c\lambda^{c} f(x).
$$
 (4)

It follows now from (3) and (4) that

$$
(Vf)(x) = cf(x) \text{ for every } x \in \mathbb{R}^n \setminus \{(0,0)\}.
$$

(c) Since at  $p = (0, \ldots, 0) \in \mathbb{R}^n$  we have  $V_p = (0, \ldots, 0)$ , the unique maximal integral curve of V starting at p is the constant curve  $\gamma_0 \colon \mathbb{R} \to \mathbb{R}^n$ ,  $t \mapsto (0, \ldots, 0)$ .

Now, if  $\gamma: J \to \mathbb{R}^n$  is a smooth curve, written in standard coordinates as

$$
\gamma(t) = (\gamma^1(t), \ldots, \gamma^n(t)),
$$

then the condition  $\gamma'(t) = V_{\gamma(t)}$  for  $\gamma$  to be an integral curve of V translates to

$$
\dot{\gamma}^j(t) = \gamma^j(t) \text{ for every } 1 \le j \le n,
$$

which yields

$$
\gamma^j \colon J = \mathbb{R} \to \mathbb{R}, \ \gamma^j(t) = c_j e^t, \quad 1 \le j \le n,
$$

for some constants  $c_j \in \mathbb{R}$ . Therefore, the unique maximal integral curve of V starting at  $p=(p^1,\ldots,p^n)\in\mathbb{R}^n$  is the smooth curve

$$
\gamma \colon \mathbb{R} \to \mathbb{R}^n, \ t \mapsto (p^1 e^t, \dots, p^n e^t).
$$

**Observation:** The Euler vector field V is a *complete* vector field on  $\mathbb{R}^n$ .

Remark. The statement from *Exercise* 2(b) is referred to as the Euler's homogeneous function theorem in the literature. In fact, it can also be shown that the converse to Euler's homogeneous function theorem holds: if  $f \in C^{\infty}(\mathbb{R}^n \setminus \{(0,0)\})$  satisfies  $Vf = cf$ , where V is the Euler vector field on  $\mathbb{R}^n$  and  $c \in \mathbb{R}$ , then f is positively homogeneous of degree c.

### Exercise 3:

(a) Consider the open submanifold

$$
M := \left\{ (x, y) \in \mathbb{R}^2 \mid x > 0, \ y > 0 \right\} \subseteq \mathbb{R}^2
$$

the map

$$
F\colon M\to M,\ (x,y)\mapsto \left(xy,\ \frac{y}{x}\right),
$$

and the smooth vector fields

$$
X \coloneqq x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \quad \text{ and } \quad Y \coloneqq y \frac{\partial}{\partial x}
$$

on M.

- (i) Show that F is a diffeomorphism, compute its Jacobian matrix  $DF(x, y)$  at an arbitrary point  $(x, y) \in M$ , and determine its inverse  $F^{-1}$ .
- (ii) Compute the pushforwards  $F_*X$  and  $F_*Y$  of X and Y, respectively.
- (iii) Compute the Lie brackets  $[X, Y]$  and  $[F_*X, F_*Y]$ .
- (iv) Find the maximal integral curve of Y starting at the point  $(1, 1) \in M$  and describe its image geometrically.
- (b) Compute the flow of each of the following smooth vector fields on  $\mathbb{R}^2$ :

(i) 
$$
U = y \frac{\partial}{\partial x} + \frac{\partial}{\partial y}
$$
.  
\n(ii)  $V = x \frac{\partial}{\partial x} + 2y \frac{\partial}{\partial y}$ .  
\n(iii)  $W = x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y}$ .

### Solution:

 $(a)(i)$  Define the map

$$
G\colon M\to M,\ (x,y)\mapsto \left(\sqrt{x/y},\ \sqrt{xy}\right).
$$

Note that  $G$  is smooth, as the functions

$$
(x, y) \in M \mapsto x/y \in \mathbb{R}_{>0}
$$
 and  $(x, y) \in M \mapsto xy \in \mathbb{R}_{>0}$ 

are smooth (they are rational polynomials with non-vanishing denominator), and the function  $u \in \mathbb{R}_{>0} \mapsto \sqrt{u} \in \mathbb{R}_{>0}$  is smooth as well. Observe also that

$$
(G \circ F)(x, y) = \left(\sqrt{\frac{xy}{y/x}}, \sqrt{xy \cdot \frac{y}{x}}\right) = (x, y)
$$

and

$$
(F \circ G)(x, y) = \left(\sqrt{\frac{x}{y}} \cdot \sqrt{xy}, \frac{\sqrt{xy}}{\sqrt{x/y}}\right) = (x, y)
$$

for all  $(x, y) \in M$ , so F and G are mutually inverse. Hence, F is a diffeomorphism with inverse  $F^{-1} = G$ . Furthermore, the Jacobian of F is given by

$$
DF(x, y) = \begin{pmatrix} y & x \\ -y/x^2 & 1/x \end{pmatrix}
$$
 for all  $(x, y) \in M$ .

(a)(ii) The push-forward  $F_*X$  of X is the unique vector field on M that is F-related to X, i.e.,

$$
dF_{(x,y)}\left(X_{(x,y)}\right) = (F_*X)_{F(x,y)} \text{ for all } (x,y) \in M.
$$

The matrix of  $dF_{(x,y)}$  with respect to the bases provided by  $\partial/\partial x$  and  $\partial/\partial y$  is precisely  $DF(x, y)$ . Since X is given with respect to this basis by  $(x, y)^T$  and since

$$
\begin{pmatrix} y & x \ -y/x^2 & 1/x \end{pmatrix} \cdot \begin{pmatrix} x \ y \end{pmatrix} = \begin{pmatrix} 2xy \ 0 \end{pmatrix},
$$

we obtain that

$$
(F_*X)_{F(x,y)} = 2xy \left. \frac{\partial}{\partial x} \right|_{F(x,y)}.
$$

Replacing  $(x, y)$  by  $G(x, y)$  yields

$$
(F_*X)_{(x,y)} = 2x \left. \frac{\partial}{\partial x} \right|_{(x,y)},
$$

and thus  $F_*X = 2x \frac{\partial}{\partial x}$ .

Similarly, since Y is given by  $(y, 0)^T$  with respect to the standard basis and since

$$
\begin{pmatrix} y & x \ -y/x^2 & 1/x \end{pmatrix} \cdot \begin{pmatrix} y \ 0 \end{pmatrix} = \begin{pmatrix} y^2 \ -y^2/x^2 \end{pmatrix},
$$

we obtain

$$
(F_*Y)_{F(x,y)} = y^2 \left. \frac{\partial}{\partial x} \right|_{F(x,y)} - \frac{y^2}{x^2} \left. \frac{\partial}{\partial y} \right|_{F(x,y)}.
$$

Replacing  $(x, y)$  by  $G(x, y)$  yields

$$
(F_*Y)_{(x,y)} = xy \left. \frac{\partial}{\partial x} \right|_{(x,y)} - y^2 \left. \frac{\partial}{\partial y} \right|_{(x,y)},
$$

and thus  $F_*Y = xy\frac{\partial}{\partial x} - y^2\frac{\partial}{\partial y}$ .

Alternatively, working as in the solution of [*Exercise Sheet* 11, *Exercise*  $2(d)(ii)$ ] and using coordinates  $(u, v)$  in the codomain, we compute that

$$
DF(G(u, v)) = \begin{pmatrix} \sqrt{uv} & \sqrt{\frac{u}{v}} \\ -\frac{\sqrt{uv}}{\frac{u}{v}} & \sqrt{\frac{v}{u}} \end{pmatrix},
$$

as well as

$$
X_{G(u,v)} = \sqrt{\frac{u}{v}} \frac{\partial}{\partial x}\bigg|_{G(u,v)} + \sqrt{uv} \frac{\partial}{\partial y}\bigg|_{G(u,v)} \text{ and } Y_{G(u,v)} = \sqrt{uv} \frac{\partial}{\partial x}\bigg|_{G(u,v)},
$$

whence

$$
(F_*X)_{(u,v)} = 2u \frac{\partial}{\partial u}\Big|_{(u,v)}
$$
 and  $(F_*Y)_{(u,v)} = uv \frac{\partial}{\partial u}\Big|_{(u,v)} - v^2 \frac{\partial}{\partial v}\Big|_{(u,v)}.$ 

(a)(iii) By [*Exercise Sheet* 11, *Exercise* 4(a)] we have

$$
[X,Y] = \left( \underbrace{\left( x \frac{\partial y}{\partial x} - y \frac{\partial x}{\partial x} \right)}_{=-y} + \underbrace{\left( y \frac{\partial y}{\partial y} - 0 \cdot \frac{\partial x}{\partial y} \right)}_{=y} \right) \frac{\partial}{\partial x} + \left( \underbrace{\left( x \frac{\partial 0}{\partial x} - y \frac{\partial y}{\partial x} \right)}_{=0} + \underbrace{\left( y \frac{\partial 0}{\partial y} - 0 \cdot \frac{\partial y}{\partial y} \right)}_{=0} \right) \frac{\partial}{\partial y} = 0.
$$

Now, as  $[F_*X, F_*Y] = F_*[X, Y]$  by [*Exercise Sheet* 11, *Exercise* 6(b)], we conclude that

$$
[F_*X, F_*Y] = 0.
$$

One can also see this with a direct calculation, using part (b) and part (a) of [Exercise Sheet 11, Exercise 4]; namely, we have

$$
[F_*X, F_*Y] = \left( \underbrace{\left( 2x \frac{\partial(xy)}{\partial x} - xy \frac{\partial(2x)}{\partial x} \right) + \left( 0 \cdot \frac{\partial(xy)}{\partial y} + y^2 \frac{\partial(2x)}{\partial y} \right) \right) \frac{\partial}{\partial x}}_{=0} + \left( \underbrace{\left( 2x \frac{\partial(-y^2)}{\partial x} - xy \frac{\partial 0}{\partial x} \right) + \left( 0 \cdot \frac{\partial(-y^2)}{\partial y} + y^2 \cdot \frac{\partial 0}{\partial y} \right) \right) \frac{\partial}{\partial y}}_{=0} = 0.
$$

(a)(iv) If  $\gamma: J \to \mathbb{R}^2$  is a smooth curve in M, written in coordinates as  $\gamma(t) = (\gamma^1(t), \gamma^2(t)),$ then the condition  $\gamma'(t) = Y_{\gamma(t)}$  for  $\gamma$  to be an integral curve of Y translates to the system

$$
\frac{d\gamma^1}{dt}(t) = \gamma^2(t) \quad \text{and} \quad \frac{d\gamma^2}{dt}(t) = 0 \quad \text{for } t \in J,
$$

whence  $\gamma^2$  is a constant function and  $\gamma^1$  is an affine function. Since we also require that  $\gamma(0) = (1, 1)$ , we infer that the unique maximal integral curve of Y starting at  $(1, 1) \in M$ is the smooth curve

$$
\gamma \colon J = (-1, +\infty) \to M \subseteq \mathbb{R}^2, \ t \mapsto (t+1, 1)
$$

whose image is the straight line segment  $\{(x,1) \in \mathbb{R}^2 \mid x > 0\}.$ 

(b) To deal with all the cases we argue exactly as in the solution to *Exercise*  $2(c)$ . Thus, we only provide the details for the solution of (ii).

(b)(i) The unique maximal integral curve of U starting at  $p = (p^1, p^2) \in \mathbb{R}^2$  is the smooth curve  $\gamma: \mathbb{R} \to \mathbb{R}^2$ ,  $t \mapsto (\frac{1}{2})$  $\frac{1}{2}t^2 + p^2t + p^1$ ,  $t + p^2$ , which is a smooth immersion. Hence, the flow of the complete vector field  $U$  is the map

$$
\theta_U : \mathbb{R} \times \mathbb{R}^2 \to \mathbb{R}^2
$$
,  $(t, (x, y)) \mapsto \left(\frac{1}{2}t^2 + yt + x, t + y\right)$ .

(b)(ii) Observe first that the unique maximal integral curve of V starting at  $p = (0,0)$  is the constant curve  $\gamma_0: \mathbb{R} \to \mathbb{R}^2$ ,  $t \mapsto (0,0)$ ; see *Exercise* 6(a). Now, if  $\gamma: J \to \mathbb{R}^2$  is a smooth curve, written in standard coordinates as  $\gamma(t) = (\gamma^1(t), \gamma^2(t))$ , then the condition  $\gamma'(t) = V_{\gamma(t)}$  for  $\gamma$  to be an integral curve of V translates to

$$
\dot{\gamma}^{1}(t) = \gamma^{1}(t), \n\dot{\gamma}^{2}(t) = 2\gamma^{2}(t).
$$

Therefore, there are constants  $c_1, c_2 \in \mathbb{R}$  such that

$$
\gamma^1: J = \mathbb{R} \to \mathbb{R}, \ \gamma^1(t) = c_1 e^t, \n\gamma^2: J = \mathbb{R} \to \mathbb{R}, \ \gamma^2(t) = c_1 e^{2t},
$$

so the unique maximal integral curve of V starting at  $p = (p^1, p^2) \in \mathbb{R}^2$  is the smooth curve  $\gamma: \mathbb{R} \to \mathbb{R}^2$ ,  $t \mapsto (p^1 e^t, p^2 e^{2t})$ , which is in passing a smooth immersion for  $p \in \mathbb{R}^2 \setminus \{(0, 0)\};$ see Exercise 6(b).

In conclusion, V is a complete vector field on  $\mathbb{R}^2$  whose flow is the map

$$
\theta_V\colon \mathbb{R}\times\mathbb{R}^2\to\mathbb{R}^2,\,\,\big(t,(x,y)\big)\mapsto\big(xe^t,ye^{2t}\big).
$$

(b)(iii) The unique maximal integral curve of W starting at  $p = (p^1, p^2) \in \mathbb{R}^2$  is the smooth curve  $\gamma: \mathbb{R} \to \mathbb{R}^2$ ,  $t \mapsto (p^1 e^t, p^2 e^{-t})$ , which is a smooth immersion for  $p \in \mathbb{R}^2 \setminus \{(0,0)\}.$ Hence, the flow of the complete vector field  $W$  is the map

$$
\theta_W \colon \mathbb{R} \times \mathbb{R}^2 \to \mathbb{R}^2, \ (t, (x, y)) \mapsto (xe^t, ye^{-t}).
$$

**Exercise 4:** Let  $\theta$ :  $\mathbb{R} \times M \to M$  be a smooth global flow on a smooth manifold M. Show that the infinitesimal generator V of  $\theta$  is a smooth vector field on M, and that each curve  $\theta^{(p)}: \mathbb{R} \to M$  is an integral curve of V.

Solution: By definition of the infinitesimal generator, we have

$$
V_p = \frac{d}{dt}\bigg|_{t=0} \theta(t, p) \text{ for all } p \in M. \tag{\star}
$$

First, to show that V is smooth, we apply *Proposition 7.4*: Given an open subset U of M, a smooth real-valued function f on U, and a point  $p \in U$ , we have

$$
Vf(p) = V_p f = \left(\frac{d}{dt}\bigg|_{t=0} \theta(t, p)\right) f
$$
  
= 
$$
\frac{d}{dt}\bigg|_{t=0} (f \circ \theta)(t, p) = \frac{\partial}{\partial t}\bigg|_{(0, p)} (f \circ \theta)(t, p).
$$

Since the composite map  $f \circ \theta$  is smooth, its partial derivative with respect to t is smooth as well. Thus,  $V f(p)$  depends smoothly on p, which implies that V is smooth.

Next, fix  $p \in M$  and  $s \in \mathbb{R}$ . We have to show that

$$
\left. \frac{d}{dt} \right|_{t=s} \theta(t,p) = V_{\theta(s,p)} \stackrel{(\star)}{=} \left. \frac{d}{dt} \right|_{t=0} \theta\big(t,\theta(s,p)\big).
$$

By definition of a flow, we have

$$
\theta(t+s,p) = \theta(t,\theta(s,p)),
$$

and by first differentiating the above relation with respect to t and then evaluating at  $t = 0$  we obtain the required identity.

### Exercise 5:

(a) Naturality of flows: Let  $F: M \to N$  be a smooth map. Let  $X \in \mathfrak{X}(M)$  and  $Y \in \mathfrak{X}(N)$ . Let  $\theta$  be the flow of X and  $\eta$  be the flow of Y. Show that if X and Y are F-related, then for each  $t \in \mathbb{R}$  it holds that  $F(M_t) \subseteq N_t$  and  $\eta_t \circ F = F \circ \theta_t$  on  $M_t$ :



(b) Diffeomorphism invariance of flows: Let  $F: M \to N$  be a diffeomorphism. Show that if  $X \in \mathfrak{X}(M)$  and if  $\theta$  is the flow of X, then the flow of  $F_*X \in \mathfrak{X}(N)$  is  $\eta_t = F \circ \theta_t \circ F^{-1}$ , with domain  $N_t = F(M_t)$  for each  $t \in \mathbb{R}$ .

#### Solution:

(a) Denote by  $\mathcal{D}_X$  resp.  $\mathcal{D}_Y$  the flow domain of  $\theta$  resp.  $\eta$ . Fix  $t \in \mathbb{R}$  and let  $p \in M_t$ . Then  $t \in \mathcal{D}_X^{(p)}$  and  $\theta^{(p)}: \mathcal{D}_X^{(p)} \to M$  is the unique maximal integral curve of X starting at p. By [Exercise Sheet 11, Exercise 2(e)],  $F \circ \theta^{(p)}$  is an integral curve of Y starting at  $F(p)$ . Hence, by maximality, we obtain that  $\mathcal{D}_X^{(p)} \subseteq \mathcal{D}_Y^{(F(p))}$ , and thus  $t \in \mathcal{D}_Y^{(F(p))}$ , which shows that  $F(p) \in N_t$ . In conclusion,  $F(M_t) \subseteq N_t$ .

Finally, we have

$$
F \circ \theta_t(p) = F(\theta(t,p)) \stackrel{(*)}{=} \eta(t, F(p)) = \eta_t \circ F(p),
$$

where in (\*) we again used that  $F \circ \theta^{(p)}$  is an integral curve of Y starting at  $F(p)$  and thus it is equal to  $\eta^{(F(p))}$  where its defined (this uses the uniqueness part in the theorem about solutions to a system of ODEs).

(b) Denote by  $\eta$  the flow of  $F_*X$ . Applying part (a) to both F and  $F^{-1}$  we infer that  $F(M_t) \subseteq N_t$  and  $F^{-1}(N_t) \subseteq M_t$ , so that  $F(M_t) = N_t$  for each  $t \in \mathbb{R}$ . Furthermore, the commutativity of the above diagram shows that  $\eta_t = F \circ \theta_t \circ F^{-1}$  for all  $t \in \mathbb{R}$ .

**Exercise 6:** Let V be a smooth vector field on a smooth manifold M and let  $\theta \colon \mathfrak{D} \to M$ be the flow generated by  $V$ . Prove the following assertions:

- (a) If  $p \in M$  is a singular point of V, then  $\mathfrak{D}^{(p)} = \mathbb{R}$  and  $\theta^{(p)}$  is the constant curve  $\theta^{(p)}(t) \equiv p.$
- (b) If  $p \in M$  is a regular point of V, then  $\theta^{(p)} \colon \mathfrak{D}^{(p)} \to M$  is a smooth immersion.

[Hint: Argue by contraposition and use the fundamental theorem on flows.]

#### Solution:

(a) If  $V_p = 0$ , then the constant curve  $\gamma : \mathbb{R} \to M$ ,  $t \mapsto p$  is clearly an integral curve of V, so it must be equal to  $\theta^{(p)}$  by uniqueness and maximality.

(b) Assume that  $\theta^{(p)}: \mathfrak{D}^{(p)} \to M$  is not a smooth immersion. Then  $\theta^{(p)}(s) = 0$  for some  $s \in \mathfrak{D}^{(p)}$ . Set  $q := \theta^{(p)}(s)$  and note that  $V_q = 0$ , since  $\theta^{(p)}$  is an integral curve of V. Thus, q is a singular point of V, and by part (a) we infer that  $\mathfrak{D}^{(q)} = \mathbb{R}$  and that  $\theta^{(q)}$  is the constant curve  $\theta^{(q)}(t) \equiv q$ . It follows from *Theorem 7.26*(b) that  $\mathfrak{D}^{(p)} = \mathbb{R}$  as well, and for all  $t \in \mathbb{R}$  the group law gives

$$
\theta^{(p)}(t) = \theta_t(p) = \theta_{t-s}(\theta(s,p)) = \theta_{t-s}(q) = q.
$$

For  $t = 0$  we obtain  $q = \theta^{(p)}(0) = p$ , and hence  $\theta^{(p)}(t) \equiv p$  and  $V_p = \theta^{(p)}(0) = 0$ , which contradicts the assumption that  $p$  is a regular point of  $V$ . This finishes the proof of (b).

*Remark.* It can be shown that if  $V$  is a smooth vector field on a smooth manifold M and if  $p \in M$  is a regular point of V, then there exist smooth coordinates  $(s^i)$  on some neighborhood of p in which V has the coordinate representation  $\frac{\partial}{\partial s^1}$ . Therefore, a flow in a neighborhood of a regular point behaves, up to diffeomorphism, just like translation along parallel coordinate lines in  $\mathbb{R}^n$ ; see *Example 7.23*(1).