# EPFL 

Differential Geometry II - Smooth Manifolds<br>Winter Term 2023/2024<br>Lecturer: Dr. N. Tsakanikas<br>Assistant: L. E. Rösler

## Exercise Sheet 11 - Solutions

Exercise 1 (Uniqueness of the smooth structure on $T M$ ): Let $M$ be a smooth $n$-manifold. Show that the topology and smooth structure on the tangent bundle $T M$ constructed in Proposition 3.12 are the unique ones with respect to which $\pi: T M \rightarrow M$ is a smooth vector bundle with the given vector space structure on the fibers, and such that all coordinate vector fields are smooth local sections.
[Hint: Use Exercise 5, Sheet 10.]
Solution: Denote by $(T M)^{\prime}$ a smooth manifold with underlying set $T M=\bigsqcup_{p \in M} T_{p} M$, but with possibly different topology and smooth structure than the usual tangent bundle $T M$, such that the map $\pi^{\prime}:(T M)^{\prime} \rightarrow M$, sending $v \in T_{p} M$ to $p \in M$, gives $(T M)^{\prime}$ the structure of a smooth vector bundle over $M$ such that all the coordinate vector fields are smooth local sections (note that, as set-theoretic maps, $\pi$ and $\pi^{\prime}$ are the same, but we denote them differently to emphasize that their source may have different topology and smooth structure). By assumption, if $\left(U,\left(x^{1}, \ldots, x^{n}\right)\right)$ is a smooth chart for $M$, then the maps

$$
\begin{aligned}
\frac{\partial}{\partial x^{i}}: U & \rightarrow(T M)^{\prime} \\
p & \left.\mapsto \frac{\partial}{\partial x^{i}}\right|_{p}
\end{aligned}
$$

are smooth local sections of $\pi^{\prime}$. Since for every $p \in U$ the vectors $\left.\frac{\partial}{\partial x^{1}}\right|_{p}, \ldots,\left.\frac{\partial}{\partial x^{n}}\right|_{p}$ form a basis of $T_{p} M$, it follows that $\left(\left.\frac{\partial}{\partial x^{i}}\right|_{p}\right)_{1 \leq i \leq n}$ is a smooth local frame for $(T M)^{\prime}$, and according to part (d) of Exercise 5, Sheet 10, the map

$$
\begin{aligned}
\widetilde{\varphi}:\left(\pi^{\prime}\right)^{-1}(U) & \rightarrow \varphi(U) \times \mathbb{R}^{n} \\
\left(p,\left.v^{i} \frac{\partial}{\partial x^{i}}\right|_{p}\right) & \mapsto\left(\varphi(p), v^{1}, \ldots, v^{n}\right)
\end{aligned}
$$

is a smooth chart for $(T M)^{\prime}$. But the same holds for $T M$ (as we saw in the proof of Proposition 3.12). It follows that the identity map $T M \rightarrow(T M)^{\prime}$ is a diffeomorphism. In particular, it is a homeomorphism, and thus also the topology agrees.

Remark. We somewhat used in Exercise 1 that the smooth structure actually determines the topology. That is, we have the following:

Let $M$ be a set and let $\mathcal{T}$ and $\mathcal{T}^{\prime}$ be two topologies on $M$, both endowing it with the structure of a topological manifold. Supposed that $\mathcal{A}$ is an atlas for both topologies, such that both $(M, \mathcal{T}, \mathcal{A})$ and $\left(M, \mathcal{T}^{\prime}, \mathcal{A}\right)$ are smooth manifolds. Then $\mathcal{T}=\mathcal{T}^{\prime}$. Indeed, the identity $\operatorname{Id}_{M}:(M, \mathcal{T}, \mathcal{A}) \rightarrow\left(M, \mathcal{T}^{\prime}, \mathcal{A}\right)$ is smooth, as we have the same atlas on both sides; in particular, it is continuous, so $\mathcal{T}^{\prime} \subseteq \mathcal{T}$. A symmetric argument also shows that the reverse inclusion holds. Therefore, $\mathcal{T}=\mathcal{T}^{\prime}$, as claimed.

## Exercise 2:

(a) Consider the tangent bundle $\pi: T \mathbb{S}^{2} \rightarrow \mathbb{S}^{2}$ of the unit sphere $\mathbb{S}^{2} \subseteq \mathbb{R}^{3}$. Compute the transition function associated with the two local trivializations determined by stereographic coordinates.
(b) Show that there is a smooth vector field on $\mathbb{S}^{2}$ which vanishes at exactly one point. [Hint: Use the stereographic projection and consider one of the coordinate vector fields.]

## Solution:

(a) We use the same notation as the one used in Exercise 6, Sheet 2. According to (the solution of) part (c) of Exercise 1, Sheet 10, the transition function

$$
\tau: \mathbb{S}^{2} \backslash\{N, S\} \rightarrow \mathrm{GL}(\mathbb{R}, 2)
$$

between the two smooth local trivializations of $T \mathbb{S}^{2}$ determined by the stereographic coordinates $\left(\mathbb{S}^{2} \backslash\{N\}, \sigma\right)$ and $\left(\mathbb{S}^{2} \backslash\{S\}, \widetilde{\sigma}\right)$ is given at every point $p \in \mathbb{S}^{2} \backslash\{N, S\}$ by the Jacobian matrix at $\widehat{p}=\sigma(p)=\widetilde{\sigma}(p)$ of the transition map $\sigma \circ \widetilde{\sigma}^{-1}$. We have seen in Exercise 6, Sheet 2 that $\sigma \circ \widetilde{\sigma}^{-1}$ is given by the formula

$$
\left(\sigma \circ \widetilde{\sigma}^{-1}\right)(\widetilde{u}, \widetilde{v})=\left(\frac{\widetilde{u}}{\widetilde{u}^{2}+\widetilde{v}^{2}}, \frac{\widetilde{v}}{\widetilde{u}^{2}+\widetilde{v}^{2}}\right)=(u, v),(\widetilde{u}, \widetilde{v}) \in \mathbb{R}^{2} \backslash\{(0,0)\}
$$

and thus its Jacobian at an arbitrary point $(\widetilde{u}, \widetilde{v}) \in \mathbb{R}^{2} \backslash\{(0,0)$ is the matrix

$$
J\left(\sigma \circ \widetilde{\sigma}^{-1}\right)(\widetilde{u}, \widetilde{v})=\left(\begin{array}{ll}
\frac{\widetilde{v}^{2}-\widetilde{u}^{2}}{\left(\tilde{u}^{2}+\tilde{v}^{2}\right)^{2}} & \frac{-2 \widetilde{u}}{\left(\widetilde{u}^{2}+\tilde{v}^{2}\right)^{2}} \\
\frac{-2 \widetilde{u} \widetilde{v}}{\left(\tilde{u}^{2}+\widetilde{v}^{2}\right)^{2}} & \frac{\widetilde{u}^{2}-\widetilde{v}^{2}}{\left(\tilde{u}^{2}+\widetilde{v}^{2}\right)^{2}}
\end{array}\right)
$$

(whose determinant equal to $-\frac{1}{\left(\widetilde{u}^{2}+\widetilde{v}^{2}\right)^{2}}$, which is clearly non-zero).
(b) We view $(u, v)$, resp. $(\widetilde{u}, \widetilde{v})$, as the component functions of $\sigma$, resp. $\widetilde{\sigma}$, where

$$
\sigma(x, y, z)=\left(\frac{x}{1-z}, \frac{y}{1-z}\right)=(u, v) \quad \text { and } \quad \tilde{\sigma}(x, y, z)=\left(\frac{x}{1+z}, \frac{y}{1+z}\right)=(\widetilde{u}, \widetilde{v})
$$

so that

$$
u=u(\widetilde{u}, \widetilde{v})=\frac{\widetilde{u}}{\widetilde{u}^{2}+\widetilde{v}^{2}} \quad \text { and } \quad v=v(\widetilde{u}, \widetilde{v})=\frac{\widetilde{v}}{\widetilde{u}^{2}+\widetilde{v}^{2}}
$$

resp.

$$
\widetilde{u}=\widetilde{u}(u, v)=\frac{u}{u^{2}+v^{2}} \quad \text { and } \quad \widetilde{v}=\widetilde{v}(u, v)=\frac{v}{u^{2}+v^{2}}
$$

Note that $\widetilde{\sigma} \circ \sigma^{-1}$ is given essentially by the same formula as $\sigma \circ \widetilde{\sigma}^{-1}$ (with the roles of $(u, v)$ and $(\widetilde{u}, \widetilde{v})$ reversed), and thus its Jacobian is essentially the same matrix as the one in part (a) (where everything is now expressed in terms of $(u, v)$ instead of $(\widetilde{u}, \widetilde{v}))$; see Exercise 6, Sheet 2.

We now consider the first coordinate vector field $X:=\frac{\partial}{\partial u}$ associated with the chart $\left(\mathbb{S}^{2} \backslash\{N\}, \sigma\right)$ for $\mathbb{S}^{2}$. It follows from Proposition 7.3 that $X=1 \frac{\partial}{\partial u}+0 \frac{\partial}{\partial v}$ is a smooth vector field on $\mathbb{S}^{2} \backslash\{N\}$, since its component functions with respect to the smooth coordinate frame $\left\{\frac{\partial}{\partial u}, \frac{\partial}{\partial v}\right\}$ are constant, and it is obvious that $X$ does not vanish on $\mathbb{S}^{2} \backslash\{N\}$. We claim that $X$ extends to a smooth vector field on the whole $\mathbb{S}^{2}$ and that it vanishes precisely at the north pole $N \in \mathbb{S}^{2}$. Indeed, on $\mathbb{S}^{2} \backslash\{N, S\}$ we have

$$
\begin{aligned}
X & =\frac{\partial \widetilde{u}}{\partial u} \frac{\partial}{\partial \widetilde{u}}+\frac{\partial \widetilde{v}}{\partial u} \frac{\partial}{\partial \widetilde{v}}=\frac{v^{2}-u^{2}}{\left(u^{2}+v^{2}\right)^{2}} \frac{\partial}{\partial \widetilde{u}}+\frac{-2 u v}{\left(u^{2}+v^{2}\right)^{2}} \frac{\partial}{\partial \widetilde{v}} \\
& =\left(\widetilde{v}^{2}-\widetilde{u}^{2}\right) \frac{\partial}{\partial \widetilde{u}}+(-2 \widetilde{u} \widetilde{v}) \frac{\partial}{\partial \widetilde{v}} .
\end{aligned}
$$

Since $N=(0,0,1) \in \mathbb{S}^{2}$ corresponds under $\widetilde{\sigma}$ to $(\widetilde{u}, \widetilde{v})=(0,0) \in \mathbb{R}^{2}$, we infer that $X$ can be extended to a vector field on $\mathbb{S}^{2}$ by defining its value at $N$ to be zero; namely,

$$
X: \mathbb{S}^{2} \rightarrow T \mathbb{S}^{2}, p \mapsto\left\{\begin{array}{cl}
\left.\frac{\partial}{\partial u}\right|_{p}, & \text { if } p \neq N \\
0, & \text { if } p=N
\end{array}\right.
$$

The above expression for $X$ also shows that its component functions with respect to the smooth coordinate frame $\left\{\frac{\partial}{\partial \tilde{u}}, \frac{\partial}{\partial \tilde{v}}\right\}$ associated with the chart $\left(\mathbb{S}^{2} \backslash\{S\}, \widetilde{\sigma}\right)$ are smooth, and hence $X$ is smooth (also) on $\mathbb{S}^{2} \backslash\{S\}$ by Proposition 7.3. Therefore, $X$ is a smooth vector field on $\mathbb{S}^{2}$ which vanishes only at the north pole $N$ of $\mathbb{S}^{2}$, as claimed.

Exercise 3: Consider the Euler vector field on $\mathbb{R}^{n}$, i.e., the vector field $V$ on $\mathbb{R}^{n}$ whose value at a point $x=\left(x^{1}, \ldots, x^{n}\right) \in \mathbb{R}^{n}$ is

$$
V_{x}=\left.x^{1} \frac{\partial}{\partial x_{1}}\right|_{x}+\ldots+\left.x^{n} \frac{\partial}{\partial x_{n}}\right|_{x}
$$

(a) Check that $V$ is a smooth vector field on $\mathbb{R}^{n}$.
(b) Let $c \in \mathbb{R}$ and let $f: \mathbb{R}^{n} \backslash\{0\} \rightarrow \mathbb{R}$ be a smooth function which is positively homogeneous of degree $c$, i.e., $f(\lambda x)=\lambda^{c} f(x)$ for all $\lambda>0$ and $x \in \mathbb{R}^{n} \backslash\{0\}$. Prove that $V f=c f$.
[Hint: Differentiate the above relation with respect to both $x^{i}$ and $\lambda$.]
(c) Compute the integral curves of $V$.

## Solution:

(a) Note that the component functions of $V$ with respect to the standard coordinate frame for $\mathbb{R}^{n}$ are linear, hence smooth. Therefore, $V$ is a smooth vector field on $\mathbb{R}^{n}$ by Proposition 7.3.
(b) Using the chain rule, we obtain

$$
\begin{equation*}
\lambda^{c} \frac{\partial f}{\partial x^{i}}(x)=\frac{\partial}{\partial x^{i}}\left(\lambda^{c} f(x)\right)=\frac{\partial}{\partial x^{i}}(f(\lambda x))=\lambda \frac{\partial f}{\partial x^{i}}(\lambda x) \tag{1}
\end{equation*}
$$

and

$$
\begin{equation*}
c \lambda^{c-1} f(x)=\frac{d}{d \lambda}\left(\lambda^{c} f(x)\right)=\frac{d}{d \lambda}(f(\lambda x))=\sum_{i=1}^{n} x^{i} \frac{\partial f}{\partial x^{i}}(\lambda x) . \tag{2}
\end{equation*}
$$

Since

$$
(V f)(x)=V_{x} f=\sum_{i=1}^{n} x^{i} \frac{\partial f}{\partial x^{i}}(x)
$$

we have

$$
\begin{equation*}
(V f)(\lambda x)=V_{\lambda x} f=\sum_{i=1}^{n}\left(\lambda x^{i}\right) \frac{\partial f}{\partial x^{i}}(\lambda x) \stackrel{(1)}{=} \lambda^{c} \sum_{i=1}^{n} x^{i} \frac{\partial f}{\partial x^{i}}(x)=\lambda^{c}(V f)(x) \tag{3}
\end{equation*}
$$

but also

$$
\begin{equation*}
(V f)(\lambda x)=V_{\lambda x} f=\sum_{i=1}^{n}\left(\lambda x^{i}\right) \frac{\partial f}{\partial x^{i}}(\lambda x) \stackrel{(2)}{=} c \lambda^{c} f(x) . \tag{4}
\end{equation*}
$$

It follows now from (3) and (4) that

$$
(V f)(x)=c f(x) \text { for every } x \in \mathbb{R}^{n} \backslash\{(0,0)\}
$$

as desired.
(c) Since at $p=(0, \ldots, 0) \in \mathbb{R}^{n}$ we have $V_{p}=(0, \ldots, 0)$, the unique maximal integral curve of $V$ starting at $p$ is the constant curve

$$
\gamma_{0}: \mathbb{R} \rightarrow \mathbb{R}^{n}, t \mapsto(0, \ldots, 0)
$$

Now, if $\gamma: J \rightarrow \mathbb{R}^{n}$ is a smooth curve, written in standard coordinates as $\gamma(t)=$ $\left(\gamma^{1}(t), \ldots, \gamma^{n}(t)\right)$, then the condition $\gamma^{\prime}(t)=V_{\gamma(t)}$ for $\gamma$ to be an integral curve of $V$ translates to

$$
\dot{\gamma}^{j}(t)=\gamma^{j}(t) \text { for every } 1 \leq j \leq n
$$

which yields

$$
\gamma^{j}: J=\mathbb{R} \rightarrow \mathbb{R}, \gamma^{j}(t)=c_{j} e^{t}, \quad 1 \leq j \leq n
$$

for some constants $c_{j} \in \mathbb{R}$. Therefore, the unique maximal integral curve of $V$ starting at $p=\left(p^{1}, \ldots, p^{n}\right) \in \mathbb{R}^{n}$ is the smooth curve

$$
\gamma: \mathbb{R} \rightarrow \mathbb{R}^{n}, t \mapsto\left(p^{1} e^{t}, \ldots, p^{n} e^{t}\right)
$$

Finally, observe that the Euler vector field $V$ is a complete vector field on $\mathbb{R}^{n}$.

Remark. The statement from Exercise 3(b) is referred to as the Euler's homogeneous function theorem in the literature. In fact, it can also be shown that the converse to Euler's homogeneous function theorem holds: if $f \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{(0,0)\}\right)$ satisfies $V f=c f$, where $V$ is the Euler vector field on $\mathbb{R}^{n}$ and $c \in \mathbb{R}$, then $f$ is positively homogeneous of degree $c$.

## Exercise 4:

(a) Let $F: M \rightarrow N$ be a smooth map. Let $X \in \mathfrak{X}(M)$ and $Y \in \mathfrak{X}(N)$. Show that $X$ and $Y$ are $F$-related if and only if for every smooth real-valued function $f$ defined on an open subset of $N$, we have

$$
X(f \circ F)=(Y f) \circ F
$$

(b) Consider the smooth map

$$
F: \mathbb{R} \rightarrow \mathbb{R}^{2}, t \mapsto(\cos t, \sin t)
$$

and the smooth vector fields

$$
X=\frac{d}{d t} \in \mathfrak{X}(\mathbb{R}) \quad \text { and } \quad Y=x \frac{\partial}{\partial y}-y \frac{\partial}{\partial x} \in \mathfrak{X}\left(\mathbb{R}^{2}\right)
$$

Show that $X$ and $Y$ are $F$-related.
(c) Let $F: M \rightarrow N$ be a diffeomorphism and let $X \in \mathfrak{X}(M)$. Prove that there exists a unique smooth vector field $Y$ on $N$ that is $F$-related to $X$. The vector field $Y$ is denoted by $F_{*} X$ and is called the pushforward of $X$ by $F$.
(d) Consider the open submanifolds

$$
M:=\left\{(x, y) \in \mathbb{R}^{2} \mid y>0 \text { and } x+y>0\right\}
$$

and

$$
N:=\left\{(u, v) \in \mathbb{R}^{2} \mid u>0 \text { and } v>0\right\}
$$

of $\mathbb{R}^{2}$ and the map

$$
F: M \rightarrow N,(x, y) \mapsto\left(x+y, \frac{x}{y}+1\right)
$$

(i) Show that $F$ is a diffeomorpism and compute its inverse $F^{-1}$.
(ii) Compute the pushforward $F_{*} X$ of the following smooth vector field $X$ on $M$ :

$$
X_{(x, y)}=\left.y^{2} \frac{\partial}{\partial x}\right|_{(x, y)}
$$

(e) Naturality of integral curves: Let $F: M \rightarrow N$ be a smooth map. Show that $X \in \mathfrak{X}(M)$ and $Y \in \mathfrak{X}(N)$ are $F$-related if and only if $F$ takes integral curves of $X$ to integral curves of $Y$.

## Solution:

(a) For any point $p \in M$ and any smooth real-valued function $f$ defined on an open neighborhood of $F(p)$ we have

$$
X(f \circ F)(p)=X_{p}(f \circ F)=d F_{p}\left(X_{p}\right)(f)
$$

and

$$
((Y f) \circ F)(p)=(Y f)(F(p))=Y_{F(p)} f
$$

Therefore, $X$ and $Y$ are $F$-related, i.e., $d F_{p}\left(X_{p}\right)=Y_{F(p)}$ for every $p \in M$, if and only if for every smooth real-valued function $f$ defined on an open subset of $N$ it holds that $X(f \circ F)=(Y f) \circ F$.
(b) 1st way: We first prove the claim using the definition of $F$-related vector fields. To this end, recall that the differential of $F$ at an arbitrary point $t \in \mathbb{R}$ is represented (with respect to the bases $\left\{d /\left.d t\right|_{t}\right\}$ for $T_{t} \mathbb{R} \cong \mathbb{R}$ and $\left\{\partial /\left.\partial x\right|_{F(t)}, \partial /\left.\partial y\right|_{F(t)}\right\}$ for $T_{F(t)} \mathbb{R}^{2} \cong \mathbb{R}^{2}$ ) by the Jacobian of $F$ at $t$, which is the $2 \times 1$-matrix

$$
\binom{-\sin (t)}{\cos (t)} .
$$

Hence,

$$
d F_{t}\left(X_{t}\right)=\binom{-\sin (t)}{\cos (t)} \cdot(1)=\binom{-\sin (t)}{\cos (t)}=-\left.\sin (t) \frac{\partial}{\partial x}\right|_{F(t)}+\left.\cos (t) \frac{\partial}{\partial y}\right|_{F(t)}=Y_{F(t)}
$$

for any $t \in \mathbb{R}$, which shows that $X$ and $Y$ are $F$-related.
2nd way: Alternatively, we may also prove the assertion using (a) as follows: For every smooth real-valued function $f=f(x, y)$ defined on an open subset of $\mathbb{R}^{2}$ and for any $t \in \mathbb{R}$ we have

$$
\begin{aligned}
X(f \circ F)(t) & =X_{t}(f \circ F)=\left.\frac{d}{d t}\right|_{t}(f \circ F) \\
& =\left(\frac{\partial f}{\partial x}(F(t)), \frac{\partial f}{\partial y}(F(t))\right) \cdot\left(F_{1}^{\prime}(t), F_{2}^{\prime}(t)\right)^{T} \\
& =-\sin (t) \frac{\partial f}{\partial x}(F(t))+\cos (t) \frac{\partial f}{\partial y}(F(t))
\end{aligned}
$$

and

$$
\begin{aligned}
((Y f) \circ F)(t) & =(Y f)(F(t))=Y_{F(t)} f \\
& =\left(\left.\cos (t) \frac{\partial}{\partial y}\right|_{F(t)}-\left.\sin (t) \frac{\partial}{\partial x}\right|_{F(t)}\right) f \\
& =\cos (t) \frac{\partial f}{\partial y}(F(t))-\sin (t) \frac{\partial f}{\partial x}(F(t)),
\end{aligned}
$$

so part (a) implies that $X$ and $Y$ are $F$-related.
(c) Since $F$ is a diffeomorphism, for every $p \in M$ its differential $d F_{p}: T_{p} M \rightarrow T_{F(p)} N$ is an $\mathbb{R}$-linear isomorphism by part (d) of Exercise 1, Sheet 4 . We may thus define the following rough vector field on $N$ :

$$
Y: N \rightarrow T N, q \mapsto d F_{F^{-1}(q)}\left(X_{F^{-1}(q)}\right),
$$

and it is clear that this is the unique (rough) vector field on $N$ that is $F$-related to $X$. We now observe that $Y$ is the composition of the following smooth maps:

$$
N \xrightarrow{F^{-1}} M \xrightarrow{X} T M \xrightarrow{d F} T N,
$$

and hence it is smooth by part (e) of Exercise 3, Sheet 3 (see also part (a) of Exercise 4, Sheet 5).
Remark. Given a diffeomorphism $F: M \rightarrow N$, the pushforward of any $X \in \mathfrak{X}(M)$ by $F$ is defined explicitly by the formula

$$
\left(F_{*} X\right)_{q}=d F_{F^{-1}(q)}\left(X_{F^{-1}(q)}\right),
$$

as already demonstrated in the proof of (c) above. As long as the inverse map $F^{-1}$ of $F$ can be computed explicitly, the pushforward of a smooth vector field can be computed directly from this formula. This observation will be applied in (d) below.
(d) It is straightforward to check that the inverse of $F$ is given by the formula

$$
F^{-1}(u, v)=\left(u-\frac{u}{v}, \frac{u}{v}\right) .
$$

The differential of $F$ at an arbitrary point $(x, y) \in M$ is represented by the Jacobian of $F$ at $(x, y)$, given by

$$
D F(x, y)=\left(\begin{array}{cc}
1 & 1 \\
\frac{1}{y} & -\frac{x}{y^{2}}
\end{array}\right),
$$

and thus $d F_{F^{-1}(u, v)}$ is represented by the matrix

$$
D F\left(u-\frac{u}{v}, \frac{u}{v}\right)=\left(\begin{array}{cc}
1 & 1 \\
\frac{v}{u} & \frac{v-v^{2}}{u}
\end{array}\right) .
$$

For any $(u, v) \in N$ we have

$$
X_{F^{-1}(u, v)}=X_{\left(u-\frac{u}{v}, \frac{u}{v}\right)}=\left.\frac{u^{2}}{v^{2}} \frac{\partial}{\partial x}\right|_{\left(u-\frac{u}{v}, \frac{u}{v}\right)}
$$

Therefore, we obtain

$$
\left(F_{*} X\right)_{(u, v)}=\left.\frac{u^{2}}{v^{2}} \frac{\partial}{\partial u}\right|_{(u, v)}+\left.\frac{u}{v} \frac{\partial}{\partial v}\right|_{(u, v)} .
$$

(e) Assume first that $X$ and $Y$ are $F$-related. Let $\gamma$ be an integral curve of $X$. By definition and by part (b) of Exercise 5, Sheet 4 we obtain

$$
(F \circ \gamma)^{\prime}(t)=d F_{\gamma(t)}\left(\gamma^{\prime}(t)\right)=d F_{\gamma(t)}\left(X_{\gamma(t)}\right)=Y_{F(\gamma(t))}=Y_{(F \circ \gamma)(t)},
$$

which shows that $F \circ \gamma$ is an integral curve of $Y$.
Assume now that $F$ takes integral curves of $X$ to integral curves of $Y$. Let $p \in M$ and let $\gamma:(-\varepsilon, \varepsilon) \rightarrow M$ be an integral curve of $X$ starting at $p$. Then $\gamma(0)=p$ and $\gamma^{\prime}(0)=X_{p}$. Moreover, by assumption, $F \circ \gamma:(-\varepsilon, \varepsilon) \rightarrow N$ is an integral curve of $Y$ starting at $F(p)$, so $Y_{(F \circ \gamma)(0)}=(F \circ \gamma)^{\prime}(0)$. Therefore, by part (b) of Exercise 5, Sheet 4 we obtain

$$
Y_{F(p)}=(F \circ \gamma)^{\prime}(0)=d F_{p}\left(\gamma^{\prime}(0)\right)=d F_{p}\left(X_{p}\right)
$$

Since $p \in M$ was arbitrary, we conclude that $X$ and $Y$ are $F$-related.

## Exercise 5:

Let $M$ be a smooth $n$-manifold and let $X$ and $Y$ be smooth vector fields on $M$.
(a) Coordinate formula for the Lie bracket: Let

$$
X=\sum_{i=1}^{n} X^{i} \frac{\partial}{\partial x^{i}} \quad \text { and } \quad Y=\sum_{j=1}^{n} Y^{j} \frac{\partial}{\partial x^{j}}
$$

be the coordinate expressions for $X$ and $Y$, respectively, in terms of some smooth local coordinates $\left(x^{i}\right)$ for $M$. Show that the Lie bracket $[X, Y]$ has the following coordinate expression:

$$
[X, Y]=\sum_{j=1}^{n} \sum_{i=1}^{n}\left(X^{i} \frac{\partial Y^{j}}{\partial x^{i}}-Y^{i} \frac{\partial X^{j}}{\partial x^{i}}\right) \frac{\partial}{\partial x^{j}}
$$

(b) Compute the Lie brackets $\left[\frac{\partial}{\partial x^{i}}, \frac{\partial}{\partial x^{j}}\right]$ of the coordinate vector fields $\partial / \partial x^{i}$ in any smooth chart $\left(U,\left(x^{i}\right)\right)$ for $M$.
(c) Assume now that $M=\mathbb{R}^{3}$,

$$
X=x \frac{\partial}{\partial x}+\frac{\partial}{\partial y}+x(y+1) \frac{\partial}{\partial z} \quad \text { and } \quad Y=\frac{\partial}{\partial x}+y \frac{\partial}{\partial z}
$$

and compute the Lie bracket $[X, Y]$.

## Solution:

(a) For any $f \in C^{\infty}(M)$ we have

$$
\begin{aligned}
{[X, Y](f) } & =X Y(f)-Y X(f)=X\left(\sum_{j} Y^{j} \frac{\partial f}{\partial x^{j}}\right)-Y\left(\sum_{i} X^{i} \frac{\partial f}{\partial x^{i}}\right) \\
& =\sum_{j}\left[X\left(Y^{j}\right) \frac{\partial f}{\partial x^{j}}+Y^{j} X\left(\frac{\partial f}{\partial x^{j}}\right)\right]-\sum_{i}\left[Y\left(X^{i}\right) \frac{\partial f}{\partial x^{i}}-X^{i} Y\left(\frac{\partial f}{\partial x^{i}}\right)\right] \\
& =\sum_{j, i}\left[X^{i} \frac{\partial Y^{j}}{\partial x^{i}} \frac{\partial f}{\partial x^{j}}+Y^{j} X^{i} \frac{\partial}{\partial x^{i}}\left(\frac{\partial f}{\partial x^{j}}\right)\right]-\sum_{i, j}\left[Y^{j} \frac{\partial X^{i}}{\partial x^{j}} \frac{\partial f}{\partial x^{i}}-X^{i} Y^{j} \frac{\partial}{\partial x^{j}}\left(\frac{\partial f}{\partial x^{i}}\right)\right] \\
& =\sum_{i, j}\left(X^{i} \frac{\partial Y^{j}}{\partial x^{i}}-Y^{i} \frac{\partial X^{j}}{\partial x^{i}}\right) \frac{\partial f}{\partial x^{j}}-\sum_{i, j}\left(X^{i} Y^{j}\right) \underbrace{\left[\frac{\partial}{\partial x^{i}}\left(\frac{\partial f}{\partial x^{j}}\right)-\frac{\partial}{\partial x^{j}}\left(\frac{\partial f}{\partial x^{i}}\right)\right]}_{=0} \\
& =\sum_{i, j}\left(X^{i} \frac{\partial Y^{j}}{\partial x^{i}}-Y^{i} \frac{\partial X^{j}}{\partial x^{i}}\right) \frac{\partial f}{\partial x^{j}}
\end{aligned}
$$

(b) Recall that the component functions of each coordinate vector field $\partial / \partial x^{j}$ in the coordinate frame $\left(\partial / \partial x^{i}\right)$ associated with the smooth chart $\left(U,\left(x^{i}\right)\right)$ are constant, so it follows immediately from (a) that

$$
\left[\frac{\partial}{\partial x^{i}}, \frac{\partial}{\partial x^{j}}\right]=0 .
$$

(c) By part (a) we obtain

$$
\begin{aligned}
{[X, Y]=} & ((x \cdot 0-1 \cdot 1)+(1 \cdot 0-0 \cdot 0)+(x(y+1) \cdot 0-1 \cdot 0)) \frac{\partial}{\partial x} \\
& +((x \cdot 0-1 \cdot 0)+(x \cdot 0-0 \cdot 0)+(x(y+1) \cdot 0-y \cdot 0)) \frac{\partial}{\partial y} \\
& +((x \cdot 0-1 \cdot(y+1))+(1 \cdot 1-0 \cdot x)+(x(y+1) \cdot 0-y \cdot 0)) \frac{\partial}{\partial z} \\
= & -\frac{\partial}{\partial x}-y \frac{\partial}{\partial z}
\end{aligned}
$$

Exercise 6 (Properties of the Lie bracket): Let $M$ be a smooth manifold. Show that the Lie bracket satisfies the following identities for all $X, Y, Z \in \mathfrak{X}(M)$ :
(a) Bilinearity: For all $a, b \in \mathbb{R}$ we have

$$
\begin{aligned}
{[a X+b Y, Z] } & =a[X, Z]+b[Y, Z] \\
{[Z, a X+b Y] } & =a[Z, X]+b[Z, Y]
\end{aligned}
$$

(b) Antisymmetry:

$$
[X, Y]=-[Y, X] .
$$

(c) Jacobi identity:

$$
[X,[Y, Z]]+[Y,[Z, X]]+[Z,[X, Y]]=0
$$

(d) For all $f, g \in C^{\infty}(M)$ we have

$$
[f X, g Y]=f g[X, Y]+(f X g) Y-(g Y f) X
$$

## Solution:

(a) We first make the following observation: given $\lambda, \mu \in \mathbb{R}$ and $U, V, W \in \mathfrak{X}(M)$, for any $f \in C^{\infty}(M)$ it holds that

$$
(\lambda V+\mu W) U f=\lambda V U f+\mu W U f \quad \text { and } \quad U(\lambda V+\mu W) f=\lambda U V f+\mu U W f .
$$

Indeed, for any $p \in M$ we have

$$
\begin{aligned}
((\lambda V+\mu W) U f)(p) & =(\lambda V+\mu W)_{p}(U f)=\left(\lambda V_{p}+\mu W_{p}\right)(U f) \\
& =\lambda V_{p}(U f)+\mu W_{p}(U f)=\lambda V(U f)(p)+\mu W(U f)(p) \\
& =(\lambda V U f+\mu W U f)(p)
\end{aligned}
$$

which yields the first equality above, while the second one is obtained analogously.
Now, given $a, b \in \mathbb{R}$, using the previous observation, for any $f \in C^{\infty}(M)$ we have

$$
\begin{aligned}
{[a X+b Y, Z](f) } & =(a X+b Y) Z f-Z(a X+b Y) f \\
& =a X Z f+b Y Z f-a Z X f-b Z Y f \\
& =a(X Z f-Z X f)+b(Y Z f-Z Y f) \\
& =a[X, Z](f)+b[Y, Z](f) \\
& =(a[X, Z]+b[Y, Z])(f),
\end{aligned}
$$

which yields the first part of the statement, while the second one is obtained similarly.
(b) For any $f \in C^{\infty}(M)$ we have

$$
[X, Y](f)=X Y f-Y X f=-(Y X f-X Y f)=-[Y, X](f)
$$

which yields the statement.
(c) By expanding all the brackets and using linearity we obtain

$$
\begin{aligned}
{[X,[Y, Z]]+} & {[Y,[Z, X]]+[Z,[X, Y]]=} \\
= & X[Y, Z]-[Y, Z] X+Y[Z, X]-[Z, X] Y+Z[X, Y]-[X, Y] Z \\
= & X Y Z-X Z Y-Y Z X+Z Y X+Y Z X-Y X Z-Z X Y+X Z Y+ \\
& +Z X Y-Z Y X-X Y Z+Y X Z \\
= & 0
\end{aligned}
$$

(d) We first make the following observation: if $V \in \mathfrak{X}(M)$ and $s, t \in C^{\infty}(M)$, then

$$
(s V) h=s(V h) \quad(\text { as smooth functions on } M)
$$

since for any $p \in M$ we have

$$
((s V) h)(p)=(s V)_{p} h=\left(s(p) V_{p}\right) h=s(p) V_{p} h=s(p)(V h)(p)=(s(V h))(p) .
$$

Now, fix $f, g \in C^{\infty}(M)$. Using the previous observation and the fact that smooth vector fields are derivations of $C^{\infty}(M)$ by Proposition 7.6, for any $h \in C^{\infty}(M)$ we have

$$
\begin{aligned}
{[f X, g Y](h) } & =(f X)(g Y)(h)-(g Y)(f X)(h) \\
& =(f X)(g(Y h))-(g Y)(f(X h)) \\
& =g(f X)(Y h)+(Y h)(f X)(g)-f(g Y)(X h)-(X h)(g Y)(f) \\
& =g f(X(Y h))+f(X g)(Y h)-f g(Y(X h))-g(Y f)(X h) \\
& =f g((X Y-Y X)(h))+(f X g) Y(h)-(g Y f) X(h) \\
& =(f g[X, Y]+(f X g) Y-(g Y f) X)(h),
\end{aligned}
$$

whence the desired relation.

Remark. A Lie algebra over $\mathbb{R}$ is an $\mathbb{R}$-vector space $\mathfrak{g}$ endowed with a map $\mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$, called the Lie bracket and usually denoted by $(X, Y) \mapsto[X, Y]$, which satisfies the following properties for all $X, Y, Z \in \mathfrak{g}$ :
(a) Bilinearity: For all $a, b \in \mathbb{R}$ we have

$$
\begin{aligned}
{[a X+b Y, Z] } & =a[X, Z]+b[Y, Z] \\
{[Z, a X+b Y] } & =a[Z, X]+b[Z, Y]
\end{aligned}
$$

(b) Antisymmetry:

$$
[X, Y]=-[Y, X] .
$$

(c) Jacobi identity:

$$
[X,[Y, Z]]+[Y,[Z, X]]+[Z,[X, Y]]=0
$$

According to Exercise $6(\mathrm{a})(\mathrm{b})(\mathrm{c})$, the infinite-dimensional $\mathbb{R}$-vector space $\mathfrak{X}(M)$ of all smooth vector fields on a smooth manifold $M$ is a Lie algebra under the Lie bracket. Another example of a Lie algebra is the $\mathbb{R}$-vector space $M_{n}(\mathbb{R})$ of real $n \times n$ matrices equipped with the commutator bracket $[A, B]:=A B-B A$.

Exercise 7: Let $F: M \rightarrow N$ be a smooth map.
(a) Naturality of the Lie bracket: Let $X_{1}, X_{2} \in \mathfrak{X}(M)$ and $Y_{1}, Y_{2} \in \mathfrak{X}(N)$ be vector fields such that $X_{i}$ is $F$-related to $Y_{i}$ for $i \in\{1,2\}$. Show that $\left[X_{1}, X_{2}\right]$ is $F$-related to $\left[Y_{1}, Y_{2}\right]$.
(b) Pushforwards of Lie brackets: Assume that $F$ is a diffeomorphism and consider $X_{1}, X_{2} \in \mathfrak{X}(M)$. Show that

$$
F_{*}\left[X_{1}, X_{2}\right]=\left[F_{*} X_{1}, F_{*} X_{2}\right] .
$$

## Solution:

(a) Since $X_{i}$ is $F$-related to $Y_{i}$ for $i \in\{1,2\}$, by Exercise 4(a) we infer that for every smooth real-valued function $f$ defined on an open subset of $N$ we have

$$
X_{1}(f \circ F)=\left(Y_{1} f\right) \circ F \quad \text { and } \quad X_{2}(f \circ F)=\left(Y_{2} f\right) \circ F
$$

Therefore,

$$
\begin{aligned}
{\left[X_{1}, X_{2}\right](f \circ F) } & =X_{1} X_{2}(f \circ F)-X_{2} X_{1}(f \circ F) \\
& =X_{1}\left(\left(Y_{2} f\right) \circ F\right)-X_{2}\left(\left(Y_{1} f\right) \circ F\right) \\
& =\left(Y_{1}\left(Y_{2} f\right)\right) \circ F-\left(Y_{2}\left(Y_{1} f\right)\right) \circ F \\
& =\left(\left[Y_{1}, Y_{2}\right](f)\right) \circ F,
\end{aligned}
$$

and thus Exercise 4(a) implies that $\left[X_{1}, X_{2}\right]$ is $F$-related to $\left[Y_{1}, Y_{2}\right]$.
(b) Follows immediately from part (a) and from Exercise 4(c).

