

# Differential Geometry II - Smooth Manifolds Winter Term 2023/2024 Lecturer: Dr. N. Tsakanikas

Assistant: L. E. Rösler

# Exercise Sheet 2

#### Exercise 1:

Let M be a topological manifold. Prove the following assertions:

(a) Every smooth atlas  $\mathcal{A}$  for M is contained in a unique maximal smooth atlas, called the *smooth structure determined by*  $\mathcal{A}$ .

[Hint: Consider the collection of all charts that are smoothly compatible with every chart in A.]

(b) Two smooth at lases for M determine the same smooth structure if and only if their union is a smooth at las.

#### Exercise 2:

Consider the topological manifold  $\mathbb{R}$  together with the two atlases  $(\mathbb{R}, \mathrm{Id}_{\mathbb{R}})$  and  $(\mathbb{R}, \psi)$ , where  $\psi \colon \mathbb{R} \to \mathbb{R}$ ,  $x \mapsto x^3$ . Show that the corresponding smooth structures on  $\mathbb{R}$  are different, but they are diffeomorphic to each other, i.e., there is a diffeomorphism  $(\mathbb{R}, \mathrm{Id}_{\mathbb{R}}) \to (\mathbb{R}, \psi)$ .

#### Exercise 3 (Finite-dimensional vector spaces):

Let V be an  $\mathbb{R}$ -vector space of dimension n. Recall that any norm on V determines a topology, which is independent of the choice of norm. Show that V has a natural smooth manifold structure as follows:

(a) Pick a basis  $E_1, \ldots, E_n$  for V and consider the map

$$E: \mathbb{R}^n \to V, \ (x^1, \dots, x^n) \mapsto \sum_{i=1}^n x^i E_i.$$

Show that  $(V, E^{-1})$  is a chart for V; in particular, with the topology defined above, V is thus a topological n-manifold.

(b) Given a different basis  $\widetilde{E}_1, \ldots, \widetilde{E}_n$  for V, show that the charts  $(V, E^{-1})$  and  $(V, \widetilde{E}^{-1})$  are smoothly compatible. The collection of all such charts of V defines a smooth structure, called the *standard smooth structure on* V.

## Exercise 4:

Prove the following assertions:

- (a) The space  $M(m \times n, \mathbb{R})$  of  $m \times n$  matrices with real entries has a natural smooth manifold structure.
- (b) The general linear group  $Gl(n, \mathbb{R})$  (i.e., the group of invertible  $n \times n$  matrices with real entries) has a natural smooth manifold structure.
- (c) The subset  $M_m(m \times n, \mathbb{R})$  of  $M(m \times n, \mathbb{R})$  of matrices of rank m, where m < n has a natural smooth manifold structure. Similarly for  $M_n(m \times n, \mathbb{R})$  when n < m.
- (d) The space  $\mathcal{L}(V, W)$  of  $\mathbb{R}$ -linear maps from V to W, where V and W are two finite-dimensional  $\mathbb{R}$ -vector spaces, has a natural smooth manifold structure.

What is the dimension of each of the above smooth manifolds?

## Exercise 5 (Product manifolds):

Let  $M_1, \ldots, M_k$  be smooth manifolds of dimensions  $n_1, \ldots, n_k$ , respectively, where  $k \geq 2$ . Show that the product space  $M_1 \times \ldots \times M_k$  is a smooth manifold of dimension  $n_1 + \ldots + n_k$  by constructing a smooth manifold structure on it.

In particular, the *n*-torus  $\mathbb{T}^n := \mathbb{S}^1 \times \ldots \times \mathbb{S}^1$  is a smooth *n*-manifold.

# Exercise 6 (to be submitted by Friday, 06.10.2023, 20:00):

Consider the *n*-sphere  $\mathbb{S}^n \subseteq \mathbb{R}^{n+1}$ . Denote by  $N = (0, \dots, 0, 1) \in \mathbb{R}^{n+1}$  the north pole and by  $S = -N = (0, \dots, 0, -1)$  the south pole of  $\mathbb{S}^n$ . Define the stereographic projection from the north pole N as follows:

$$\sigma \colon \mathbb{S}^n \setminus \{N\} \to \mathbb{R}^n, \quad \sigma(x^1, \dots, x^{n+1}) = \frac{1}{1 - x^{n+1}} (x^1, \dots, x^n).$$

Let  $\widetilde{\sigma}(x) = -\sigma(-x)$  for  $x \in \mathbb{S}^n \setminus \{S\}$ ; it is called the *stereographic projection from the* south pole.

- (a) For any  $x \in \mathbb{S}^n \setminus \{N\}$ , show that  $\sigma(x) = u$ , where (u, 0) is the point where the line through N and x intersects the linear subspace where  $x^{n+1} = 0$ . Similarly, show that  $\widetilde{\sigma}(x)$  is the point where the line through S and x intersects the same subspace.
- (b) Show that  $\sigma$  is bijective, and

$$\sigma^{-1}(u^1, \dots, u^n) = \frac{1}{|u|^2 + 1} (2u^1, \dots, 2u^n, |u|^2 - 1).$$

- (c) Verify that the atlas consisting of the two charts  $(\mathbb{S}^n \setminus \{N\}, \sigma)$  and  $(\mathbb{S}^n \setminus \{S\}, \widetilde{\sigma})$  is a smooth atlas for  $\mathbb{S}^n$ , and hence defines a smooth structure on  $\mathbb{S}^n$ . (The coordinates defined by  $\sigma$  or  $\widetilde{\sigma}$  are called *stereographic coordinates*.)
- (d) Show that the smooth structure determined by the above atlas is the same as the one defined via graph coordinates in the lecture.