

For example, if a top. mnfd M can be covered by a single chart, then the smooth compatibility condition is trivially satisfied, so any such chart determines automatically a smooth structure on M (see, e.g., Examples 1.3(1) and 1.8(1))

• DEF. 1.7: Let M be a smooth mnfd. Any chart (U, φ) contained in the maximal smooth atlas is called a smooth chart. The corresponding coordinate map φ is called a smooth coordinate map, and its domain U is called a smooth coordinate domain, or smooth coordinate neighborhood of each of its pts.

~ smooth coordinate ball

~ smooth coordinate cube

• EXAMPLE 1.8:

0) For each $n \in \mathbb{N}$ the Euclidean space \mathbb{R}^n is a smooth n -mnfd with the smooth structure determined by the atlas $\{(R^n, \text{Id}_{R^n})\}$. We call this the standard smooth structure on \mathbb{R}^n and the resulting coordinate map standard coordinates. W.r.t. this smooth structure, the smooth coordinate charts for \mathbb{R}^n are exactly those charts (U, φ) s.t. φ is a diffeo. (in the usual sense) from $U \subseteq \mathbb{R}^n$ to another open subset $\hat{U} \subseteq \mathbb{R}^n$.

1) Graphs of smooth fcts: If $U \subseteq \mathbb{R}^n$ is an open subset and if $f: U \rightarrow \mathbb{R}^k$ is a smooth fct, then by Ex. 1.3(1) the graph $\textcircled{9}$

$\Gamma(\mathbb{H})$ of \mathbb{H} is a top. n-mnfd in the subspace topology. Since $\Gamma(\mathbb{H})$ is covered by the single graph coordinate chart $\varphi: \Gamma(\mathbb{H}) \rightarrow U$, we can put a canonical smooth structure on $\Gamma(\mathbb{H})$ by declaring $(\Gamma(\mathbb{H}), \varphi)$ to be a smooth chart.

2) Spheres: The n-sphere $S^n \subseteq \mathbb{R}^{n+1}$ is a top. n-mnfd by EX. 1.3(2). We put a smooth structure on S^n as follows. For each $i \in \{1, \dots, n+1\}$ we consider the graph coordinate charts $(U_i^\pm \cap S^n, \varphi_i^\pm)$. For any $i \neq j$ and any choice of \pm signs, the transition map $\varphi_i^\pm \circ (\varphi_j^\pm)^{-1}$ and $\varphi_i^\pm \circ (\varphi_j^\mp)^{-1}$ are easily computed. For example, when $i < j$, we get:

$$\begin{aligned}\varphi_i^+ \circ (\varphi_j^+)^{-1}(u^1, \dots, u^n) &= \varphi_i^+(u^1, \dots, \sqrt{1-u_1^2}, \dots, u^n) \\ &= (u^1, \dots, \underset{i\text{-th}}{\hat{u}^i}, \dots, \sqrt{1-u_1^2}, \dots, u^n),\end{aligned}$$

and similar formulas hold in the other cases. When $i=j$, the domains of φ_i^+ and φ_i^- are disjoint, so there is nothing to check. Thus, the collection of charts $\{(U_i^\pm \cap S^n, \varphi_i^\pm)\}_{i=1}^{n+1}$ is a smooth atlas, so it defines a smooth structure on S^n , which we call its standard smooth structure.

3) Open submanifolds: Let U be any open subset of \mathbb{R}^n . Then U is a top. n-mnfd, and the single chart (U, Id_U) determines a smooth structure on U .

More generally, let M be a smooth n-mnfd and let $U \subseteq M$ be an open subset. Define an atlas on U by

$\mathcal{A}_U = \{\text{smooth charts } (V, \varphi) \text{ for } M \text{ s.t. } V \subseteq U\}.$

Every pt $p \in U$ is contained in the domain of some chart (W, φ) for M ; if we set $V = W \cap U$, then $(V, \varphi|_V)$ is a chart in \mathcal{A}_U whose domain contains p . Therefore, U is covered by the domains of the charts in \mathcal{A}_U , and it is easy to verify that this is a smooth atlas for U .

Thus, any open subset of M is itself a smooth n -mfld in a natural way. Endowed with this smooth structure, we call any open subset an open submanifold of M .

In the examples we have seen so far, we constructed a smooth manifold structure in two stages: we started with a top. sp. and checked that it was a top. mfld, and then we specified a smooth structure. The following lemma shows how, given a set with suitable "charts" that overlap smoothly, we can use the charts to define both a topology and a smooth structure on the set.

LEM 1.9 (Smooth mfld chart lemma): Let M be a set.

Suppose we are given a collection $\{U_\alpha\}$ of subsets of M together with maps $\varphi_\alpha : U_\alpha \rightarrow \mathbb{R}^n$ s.t. the following prop. are satisfied:

- (i) For each α , φ_α is a bijection between U_α and an open subset $\varphi_\alpha(U_\alpha) \subseteq \mathbb{R}^n$.
- (ii) For each α and β , the sets $\varphi_\alpha(U_\alpha \cap U_\beta)$ and $\varphi_\beta(U_\alpha \cap U_\beta)$ \cap

are open in \mathbb{R}^n .

(iii) Whenever $U_\alpha \cap U_\beta \neq \emptyset$, the map

$$\varphi_\beta \circ \varphi_\alpha^{-1} : \varphi_\alpha(U_\alpha \cap U_\beta) \rightarrow \varphi_\beta(U_\alpha \cap U_\beta)$$

is smooth.

(iv) Countably many of the sets U_α cover M .

(v) Whenever $p, q \in M$ with $p \neq q$, either there exists some U_α containing both p and q or there exist disjoint sets U_α and U_β with $p \in U_\alpha$ and $q \in U_\beta$.

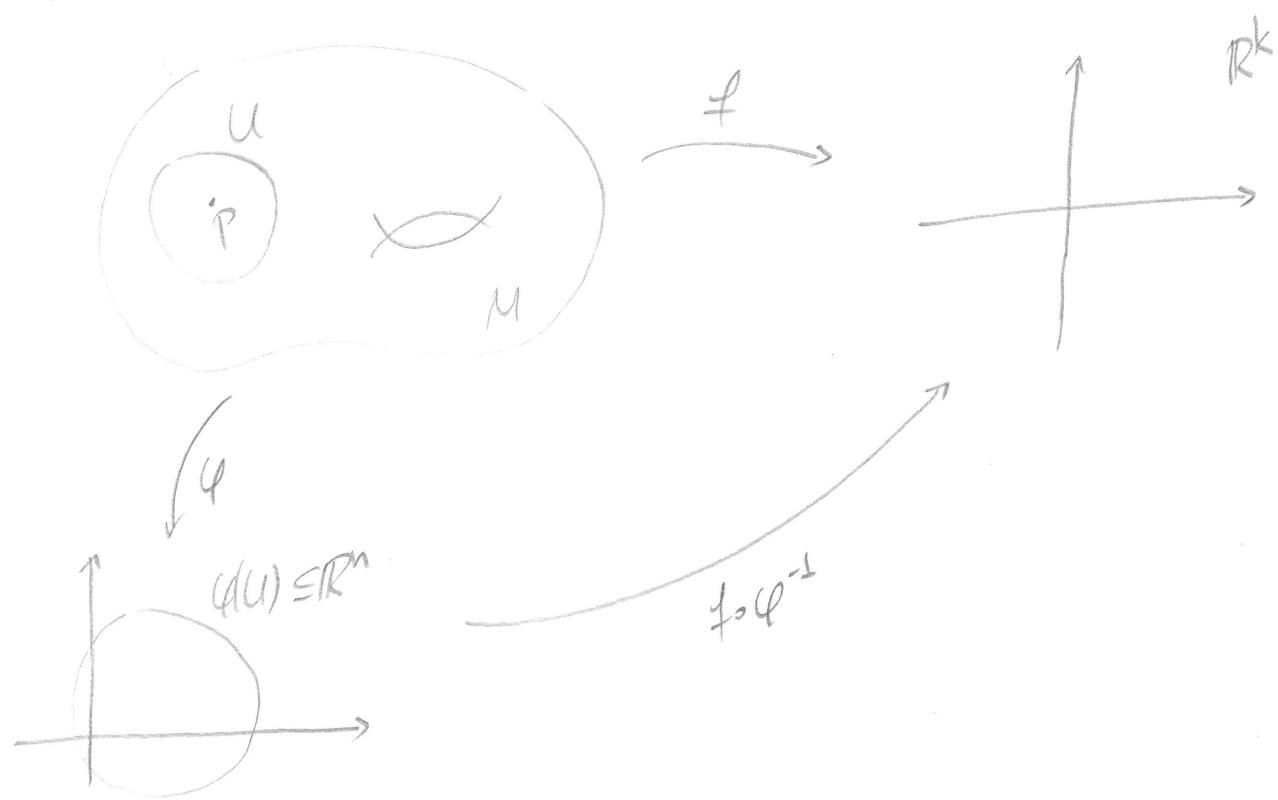
Then M has a unique manifold structure s.t. each $(U_\alpha, \varphi_\alpha)$ is a smooth chart.

- details of the proof : [Lee, Lemma 1.35]

- key idea of the proof : define the topology on M by taking all sets of the form $\varphi_\alpha^{-1}(V)$, $V \subseteq \mathbb{R}^n$ open, as a basis.

CH. 2 : SMOOTH MAPS

DEF. 2.1: Let M be a smooth n -mnfd and let $f: M \rightarrow \mathbb{R}^k$ be a fnct, where $k \in \mathbb{N}$. We say that f is a smooth fnct if for every pt $p \in M$ there exists a smooth chart (U, φ) for M st. $p \in U$ and $f \circ \varphi^{-1}$ is smooth on the open subset $\varphi(U) \subseteq \mathbb{R}^n$.



REMARK:

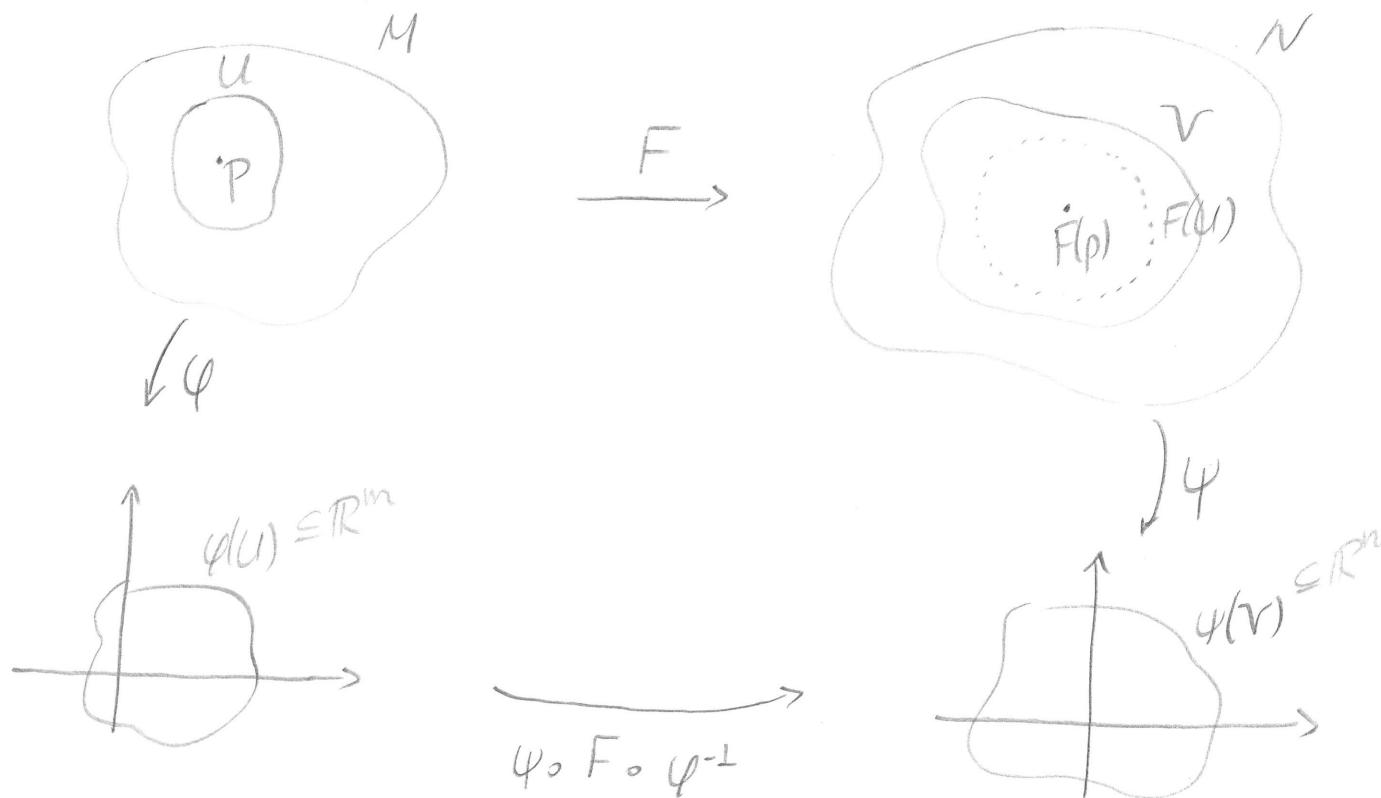
- 1) If M is a smooth mnfd and $f: M \rightarrow \mathbb{R}^k$ is a smooth fnct, then $f \circ \varphi^{-1}: \varphi(U) \rightarrow \mathbb{R}^k$ is smooth for every smooth chart (U, φ) for M (see ES3).
- 2) Let M be a smooth mnfd. The set $C^\infty(M)$ of all smooth real-valued fncts on M is an infinite-dim \mathbb{R} -v.s.: sums and constant multiples of smooth fncts are smooth (see also ES3). Moreover, pointwise multiplication turns

$C^\infty(M)$ into a commutative ring and a commutative and associative \mathbb{R} -algebra.

• DEF. 2.2: Let M be a smooth mnfd. Given a fnct $f:M \rightarrow \mathbb{R}^k$ and a chart (U,φ) for M , the fnct $\tilde{f}=f \circ \varphi^{-1}: \varphi(U) \rightarrow \mathbb{R}^k$ is called the coordinate representation of f .

By dfn, f is smooth iff its coordinate representation is smooth in some smooth chart around each pt. By the previous REM(L), smooth fncts have smooth coordinate representations in every smooth chart.

• DEF. 2.3: Let $F:M \rightarrow N$ be a map between smooth mnfds. We say that F is a smooth map if for every $p \in M$ there exist smooth charts (U,φ) containing p and (V,ψ) containing $F(p)$ s.t. $F(U) \subseteq V$ and $\psi \circ F \circ \varphi^{-1}:\varphi(U) \rightarrow \psi(V)$ is smooth.



Observe that DEF. 2.1 is a special case of DEF. 2.3 by taking $N = V = \mathbb{R}^k$ and $\psi = \text{Id}_{\mathbb{R}^k}$.

• PROP. 2.4: Every smooth map is continuous.

PROOF: Let $F: M \rightarrow N$ be a smooth map between smooth mnflds. Fix $p \in M$. Since F is smooth, there are smooth charts (U, φ) containing p and (V, ψ) containing $F(p)$ s.t. $F(U) \subseteq V$ and $\psi \circ F \circ \varphi^{-1}: \varphi(U) \rightarrow \psi(V)$ is smooth, and hence cont. Since $F(U) \subseteq V$ and the maps φ and ψ are homeomorphisms, the map

$$F|_U = \psi^{-1} \circ (\psi \circ F \circ \varphi^{-1}) \circ \varphi: U \rightarrow V$$

is cont. as a composition of cont. maps. Hence, F is cont. in a neighborhood of each pt, and thus cont. on M .

• COMMENT: The requirement that " $\forall p \in M \exists (U, \varphi) \ni p \exists (V, \psi) \ni F(p)$ s.t. $F(U) \subseteq V$ " in the defn of smoothness is included precisely so that smoothness implies continuity.

• DEF. 2.5: Let $F: M \rightarrow N$ be a smooth map between smooth mnflds. If (U, φ) and (V, ψ) are smooth charts for M and N , respectively, then we call $\hat{F} = \psi \circ F \circ \varphi^{-1}$ the coordinate representation of F w.r.t. the given coordinates. It maps $\varphi(U \cap F^{-1}(V))$ to $\psi(V)$.

REMARK: Let $F: M \rightarrow N$ be a smooth map between smooth manifolds. Then the coordinate representation of F w.r.t. every pair of smooth charts for M and N is smooth (see ES3).

- There are equivalent characterizations of smoothness (see ES3). For example, a map $F: M \rightarrow N$ between smooth manifolds is smooth iff F is cont. and there exist smooth atlantes $\{(U_\alpha, \varphi_\alpha)\}$ and $\{(V_\beta, \psi_\beta)\}$ for M and N , respectively, s.t. for each α and β , $\psi_\beta \circ F \circ \varphi_\alpha^{-1}$ is a smooth map from $\varphi_\alpha(U_\alpha \cap F^{-1}(V_\beta))$ to $\psi_\beta(V_\beta)$.
- Smoothness is local (see ES3): if $F: M \rightarrow N$ is a map between smooth manifolds and if $\forall p \in M \exists p \in U \subseteq M$ s.t. $F|_U$ is smooth, then F is smooth.
- Gluing lemma for smooth maps: Let M and N be smooth manifolds and let $\{U_\alpha\}_{\alpha \in A}$ be an open cover for M . Suppose that for each $\alpha \in A$ we are given a smooth map $F_\alpha: U_\alpha \rightarrow N$ s.t. the maps agree on overlaps: $F_\alpha|_{U_\alpha \cap U_\beta} = F_\beta|_{U_\alpha \cap U_\beta}$ for all $\alpha, \beta \in A$. Then there exists a unique smooth map $F: M \rightarrow N$ s.t. $F|_{U_\alpha} = F_\alpha$ for each $\alpha \in A$.

PROP. 2.6: Let M, N and P be smooth manifolds.

- (a) Every constant map $c: M \rightarrow N$ is smooth.
- (b) The identity map I_M of M is smooth.
- (c) If $U \subseteq M$ is an open submanifold, then the inclusion map $i: U \hookrightarrow M$ is smooth.