Advanced Probability and Applications

## Solutions to Homework 10

**Exercise 1\*.** We use the large deviations principle to find a tight upper bound. Before this, we need to check that the moment generating function  $\mathbb{E}(e^{sX_1})$  is finite in a proper neighborhood of s = 0:

$$\mathbb{E}(e^{sX_1}) = \int_0^\infty e^{sx} \,\lambda e^{-\lambda x} \,dx = \frac{\lambda}{\lambda - s}, \quad \text{for } s < \lambda$$

Therefore, by applying the large deviations principle, we obtain for  $t > 1/\lambda$ :

$$\mathbb{P}(\{S_n > nt\}) \le \exp(-n\Lambda^*(t)) \quad \text{where} \quad \Lambda^*(t) = \max_{s \in \mathbb{R}} \left\{ st - \log\left(\frac{\lambda}{\lambda - s}\right) \right\}$$

By taking the derivative of  $st - \log\left(\frac{\lambda}{\lambda - s}\right)$  with respect to s and setting it equal to zero, we obtain that  $\Lambda^*(t)$  is maximum at  $s^* = \lambda - \frac{1}{t}$ . Hence,

$$\mathbb{P}(\{S_n > nt\}) \le \exp(-n\left(\lambda t - 1 - \log(\lambda t)\right))$$

**Exercise 2.** a) Use part (ii) of the definition with  $U \equiv 1$  (such a U belongs to G).

b) (i)  $Z = \mathbb{E}(X)$  is constant and therefore  $\mathcal{G}$ -measurable; (ii) Let  $U \in G$ :  $\mathbb{E}(XU) = \mathbb{E}(X)\mathbb{E}(U) = \mathbb{E}(X)U) = \mathbb{E}(ZU)$  (using the independence of X and U and the linearity of expectation).

c) (i) Z = X is  $\mathcal{G}$ -measurable by assumption; (ii) Let  $U \in G$ :  $\mathbb{E}(XU) = \mathbb{E}(ZU)$  !

d) (i)  $Z = \mathbb{E}(X|\mathcal{G}) Y$  is  $\mathcal{G}$ -measurable; (ii) Let  $U \in G$ :  $\mathbb{E}(XYU) = \mathbb{E}(\mathbb{E}(X|\mathcal{G}) YU)$ , because part (ii) of the definition of  $\mathbb{E}(X|\mathcal{G})$  implies the previous equality (indeed,  $YU \in G$ ). Therefore,  $\mathbb{E}(XYU) = \mathbb{E}(ZU)$ .

e) Let us first check the left-hand side equality:  $\mathbb{E}(X|\mathcal{H})$  is  $\mathcal{H}$ -measurable, therefore  $\mathcal{G}$ -measurable, so one can apply property c).

For the right-hand side equality, one has: (i)  $Z = \mathbb{E}(X|\mathcal{H})$  is  $\mathcal{H}$ -measurable; (ii) Let  $U \in H$ :

$$\mathbb{E}(\mathbb{E}(X|\mathcal{G})U) = \mathbb{E}(\mathbb{E}(XU|\mathcal{G})) = \mathbb{E}(XU) = \mathbb{E}(\mathbb{E}(X|\mathcal{H})U) = \mathbb{E}(ZU)$$

using successively d), a) and the definition of  $\mathbb{E}(X|\mathcal{H})$ .

**Exercise 3.** a) We must check that  $\mathbb{E}(\psi(Y)g(Y)) = \mathbb{E}(Xg(Y))$  for any continuous and bounded function g. The computation gives indeed:

$$\mathbb{E}(\psi(Y)\,g(Y)) = \sum_{y \in C} \psi(y)\,g(y)\,\mathbb{P}(\{Y = y\}) = \sum_{x,y \in C} x\,g(y)\,\mathbb{P}(\{X = x, Y = y\}) = \mathbb{E}(X\,g(Y))$$

b) Let Y and Z be the two independent dice rolls:  $\mathbb{P}(\{Y = i\}) = \mathbb{P}(\{Z = j\}) = 0.25$  and  $\mathbb{P}(\{Y = i, Z = j\}) = \mathbb{P}(\{Y = i\}) \mathbb{P}(\{Z = j\})$ . We therefore have  $\mathbb{E}(\max(Y, Z)|Y) = \psi(Y)$ , where

$$\begin{split} \psi(i) &= \sum_{j=i}^{4} \max(i,j) \mathbb{P}(\{\max(Y,Z)=j\} | \{Y=i\}) = \sum_{j=i}^{4} \max(i,j) \frac{\mathbb{P}(\{\max(Y,Z)=j,Y=i\})}{\mathbb{P}(\{Y=i\})} \\ &= i \frac{\mathbb{P}(\{Z \le i,Y=i\})}{\mathbb{P}(\{Y=i\})} + \sum_{j=i+1}^{4} j \frac{\mathbb{P}(\{Z=j,Y=i\})}{\mathbb{P}(\{Y=i\})} = i \mathbb{P}(\{Z \le i\}) + \sum_{j=i+1}^{4} j \mathbb{P}(\{Z=j\}) \end{split}$$

So  $\psi(1) = 2.5$ ,  $\psi(2) = 2.75$ ,  $\psi(3) = 3.25$  and  $\psi(4) = 4$ .

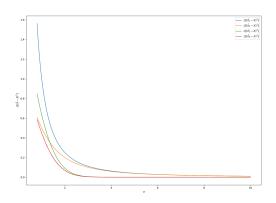
**Exercise 4.** a) Let us compute theoretically the first three MSE's:

$$\begin{split} \mathbb{E}((\widehat{X}_1 - X)^2) &= \mathbb{E}\left(\left(X + \frac{Z}{a} - X\right)^2\right) = \frac{\mathbb{E}(Z^2)}{a^2} = \frac{1}{a^2}\\ \mathbb{E}((\widehat{X}_2 - X)^2) &= \mathbb{E}\left(\left(\frac{a^2X + aZ}{a^2 + 1} - X\right)^2\right) = \mathbb{E}\left(\left(-\frac{1}{a^2 + 1}X + \frac{a}{a^2 + 1}Z\right)^2\right)\\ &= \frac{1}{(a^2 + 1)^2} + \frac{a^2}{(a^2 + 1)^2} = \frac{1}{a^2 + 1}\\ \mathbb{E}((\widehat{X}_3 - X)^2) &= \mathbb{E}((\operatorname{sign}(a^2X + aZ) - X)^2) = 4Q(-|a|) \end{split}$$

where  $Q(x) = \int_{-\infty}^{x} p_Z(z) dz$  is the cdf of  $Z \sim \mathcal{N}(0, 1)$ . The fourth MSE is given by

$$\mathbb{E}((\hat{X}_4 - X)^2) = \mathbb{E}((\tanh(a^2X + aZ) - X)^2) = 1 - \mathbb{E}(\tanh(a^2 + aZ)^2)$$

(see computation below in part c) for the last equality). This expression can be computed by numerical integration or by the Monte-Carlo method, as suggested in the problem set. The four MSE's are represented as functions of a on the figure below:



This shows that the fourth estimator gives the minimum MSE.

b) As we shall see below, the fourth estimator corresponds to the conditional expectation  $\mathbb{E}(X|Y)$ , which by definition minimizes  $\mathbb{E}((Z-X)^2)$  among all random variables Z which are  $\sigma(Y)$ -measurable and square-integrable. The computation of the condition expectation gives  $\mathbb{E}(X|Y) = \psi(Y)$ , where

$$\psi(y) = \sum_{x \in \{-1,+1\}} x \, \frac{p_x \, p_Z(y - ax)}{p_Y(y)} = \frac{p_Z(y - a) - p_Z(y + a)}{p_Z(y - a) + p_Z(y + a)} = \frac{e^{ay} - e^{-ay}}{e^{ay} + e^{-ay}} = \tanh(ay)$$

which confirms that  $\mathbb{E}(X|Y) = \tanh(aY) = \hat{X}_4.$ 

NB: The first expression for the function  $\psi(y)$  above can be obtained either by reasoning intuitively (and forgetting that we are dealing here with a mix of discrete (X) and continuous (Y) random variables), or by proving formally that the random variable  $\psi(Y)$  satisfies (similarly to Ex. 2.a):

 $\mathbb{E}(Xg(Y)) = \mathbb{E}(\psi(Y)\,g(Y)), \quad \text{for every } g: \mathbb{R} \to \mathbb{R} \text{ continuous and bounded}$ 

c) Using the following series of equalities:

$$\mathbb{E}((\mathbb{E}(X|Y) - X)^2) = \mathbb{E}(X^2) + \mathbb{E}(\mathbb{E}(X|Y)^2) - 2\mathbb{E}(X\mathbb{E}(X|Y))$$
$$= \mathbb{E}(X^2) + \mathbb{E}(\mathbb{E}(X|Y)^2) - 2\mathbb{E}(\mathbb{E}(X\mathbb{E}(X|Y)|Y))$$
$$= \mathbb{E}(X^2) + \mathbb{E}(\mathbb{E}(X|Y)^2) - 2\mathbb{E}(\mathbb{E}(X|Y)^2) = \mathbb{E}(X^2) - \mathbb{E}(\mathbb{E}(X|Y)^2)$$

we see that

$$\mathbb{E}((\widehat{X}_4 - X)^2) = \mathbb{E}(X^2) - \mathbb{E}(\widehat{X}_4^2) = 1 - \mathbb{E}(\tanh(aY)^2) = 1 - \mathbb{E}(\tanh(a^2 + aZ)^2)$$

(noticing for the last equality that the value of X can be replaced by +1 using symmetry). A direct computation shows that it also holds that  $\mathbb{E}((\hat{X}_2 - X)^2) = \mathbb{E}(X^2) - \mathbb{E}(\hat{X}_2^2) = \frac{1}{a^2+1}$ , but that the equality does not hold for  $\hat{X}_1$  and  $\hat{X}_3$ .