

Nuclear Fusion and Plasma Physics - Exercises

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Solutions to Problem Set 6 -30 October 2023

1 Exercise 1 - The frozen flux theorem

In what follows, please keep in mind that we use interchangeably the following notation for partial derivatives: $\partial_t \equiv \frac{\partial}{\partial t}$, $\partial_t \equiv \frac{\partial}{\partial t}$.

a) Ideal MHD equations

$$\partial_t \rho + \nabla \cdot (\rho \mathbf{u}) = 0 \quad (1)$$

$$\rho [\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u}] = -\nabla p + \mathbf{j} \times \mathbf{B} \quad (2)$$

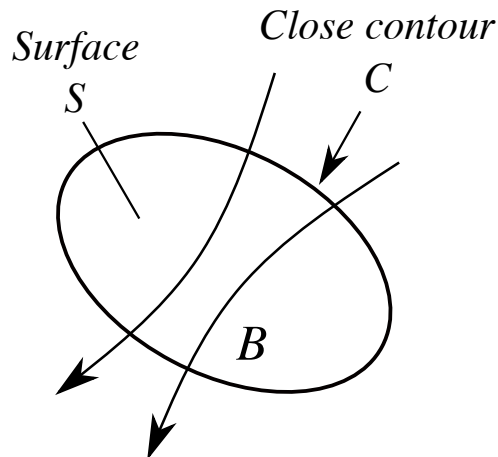
$$\frac{d}{dt} (p \rho_m^{-\gamma}) = 0 \quad \text{State equation} \quad (3)$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{j} \quad (4)$$

$$\nabla \times \mathbf{E} = -\partial_t \mathbf{B} \quad (5)$$

$$\mathbf{E} + \mathbf{u} \times \mathbf{B} = 0 \quad (6)$$

b) Magnetic Flux through a surface S of closed contour C



$$\Phi = \int_S \mathbf{B} \cdot d\mathbf{S} \quad (7)$$

$$\frac{d\Phi}{dt} = \frac{d}{dt} \int_S \mathbf{B} \cdot d\mathbf{S} \quad (8)$$

$$\frac{d\Phi}{dt} = \int_S \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S} + \int_S \mathbf{B} \cdot \frac{d}{dt} d\mathbf{S} \quad (9)$$

We could put the time derivative into the surface integral because the temporal and spatial coordinates are independent.

- c) Equation (9) shows that the variation of the magnetic flux can happen either by a change of \mathbf{B} inside the closed surface or a variation of the enclosing surface. We can rewrite each term of the equation separately.

Starting from the first one and using Faraday's law, we can write.

$$\int_S \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S} = - \int_S (\nabla \times \mathbf{E}) \cdot d\mathbf{S} \quad (10)$$

We use the Stokes' theorem to express the surface integral in an integral over the contour C , delimiting the surface.

$$\int_S \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S} = - \int_S (\nabla \times \mathbf{E}) \cdot d\mathbf{S} = - \oint_C \mathbf{E} \cdot d\mathbf{l} \quad (11)$$

The second term of equation (9) can be developed further by writing the time derivative of the surface element $d\mathbf{S}$ as a function of the fluid velocity \mathbf{u} .

$$d\mathbf{S} = \mathbf{u} dt \times d\mathbf{l} \quad (12)$$

$$\int_S \mathbf{B} \cdot \frac{d}{dt} d\mathbf{S} = \oint_C \mathbf{B} \cdot (\mathbf{u} \times d\mathbf{l}) \quad (13)$$

Putting together the two contributions yields:

$$\frac{d\Phi}{dt} = - \oint_C \mathbf{E} \cdot d\mathbf{l} + \oint_C \mathbf{B} \cdot (\mathbf{u} \times d\mathbf{l}) \quad (14)$$

$$\frac{d\Phi}{dt} = - \oint_C (\mathbf{E} + \mathbf{u} \times \mathbf{B}) \cdot d\mathbf{l} \quad (15)$$

Equation (15) has been obtained rearranging the terms in the second integral of (14) and combining the two integrals. From the ideal ohm's law, it follows that $\mathbf{E} + \mathbf{u} \times \mathbf{B} = \mathbf{0} \Rightarrow \frac{d\Phi}{dt} = \mathbf{0}$.

Exercise 2 - Cylindrical equilibrium

a) Given that

$$\mathbf{B} = B_0 \hat{\mathbf{z}}, \quad p = p_0 \cos^2\left(\frac{\pi r}{2a}\right),$$

the MHD equilibrium is written as

$$\begin{aligned} \mathbf{J} \times \mathbf{B} &= \nabla p \\ \nabla \times \mathbf{B} &= \mu_0 \mathbf{J} \end{aligned}$$

Combining these expressions:

$$\nabla p = \frac{1}{\mu_0} (\nabla \times \mathbf{B}) \times \mathbf{B} = \frac{1}{\mu_0} \left[-\nabla \frac{B^2}{2} + (\mathbf{B} \cdot \nabla) \mathbf{B} \right]$$

$$\begin{aligned} \nabla \left[p + \frac{B^2}{2\mu_0} \right] &= \frac{1}{\mu_0} (\mathbf{B} \cdot \nabla) \mathbf{B} = \frac{\mathbf{B}}{\mu_0} (\hat{\mathbf{b}} \cdot \nabla) (\mathbf{B} \hat{\mathbf{b}}) \\ &= \frac{B^2}{\mu_0} (\hat{\mathbf{b}} \cdot \nabla) \hat{\mathbf{b}} + \hat{\mathbf{b}} (\hat{\mathbf{b}} \cdot \nabla) \frac{B^2}{2\mu_0} \end{aligned}$$

The first term corresponds to the bending force of the B field. The second term corresponds to the compression of the field.

In the case of straight and parallel field lines, the two terms on the right hand side are zero, so

$$p(r) + \frac{B_z^2}{2\mu_0} = p(a) + \frac{B_z^2(a)}{2\mu_0} = \frac{B_0^2}{2\mu_0} \quad (p(a) = 0)$$

So the maximum $p(r)$ would occur for $B_z(r) = 0$ and will have a value $p_{0,max} = \frac{B_0^2}{2\mu}$.

b)

$$\begin{aligned} B_z^2 &= B_0^2 - 2\mu_0 p_0 \cos^2\left(\frac{\pi r}{2a}\right) \\ &= B_0^2 \left[1 - \cos^2\left(\frac{\pi r}{2a}\right) \right] \\ \mathbf{B} &= B_0 \sin\left(\frac{\pi r}{2a}\right) \hat{\mathbf{z}} \end{aligned}$$

$$\mathbf{J} = \frac{1}{\mu_0} \nabla \times \mathbf{B} = \frac{1}{\mu_0} \left(-\frac{\partial B_z}{\partial r} \right) \hat{\theta} = \frac{-\pi B_0}{2\mu_0 a} \cos\left(\frac{\pi r}{2a}\right) \hat{\theta}$$

